

An aerial photograph of the SKA (Square Kilometer Array) site, showing a large, circular, green field with several clusters of solar panels. A winding river or canal runs through the field. The text "Continuum surveys with the SKA" is overlaid in large, white, bold letters.

Continuum surveys with the SKA

John McKean
(ASTRON and Kapteyn Astronomical
Institute)

on behalf of Extragalactic continuum SWG

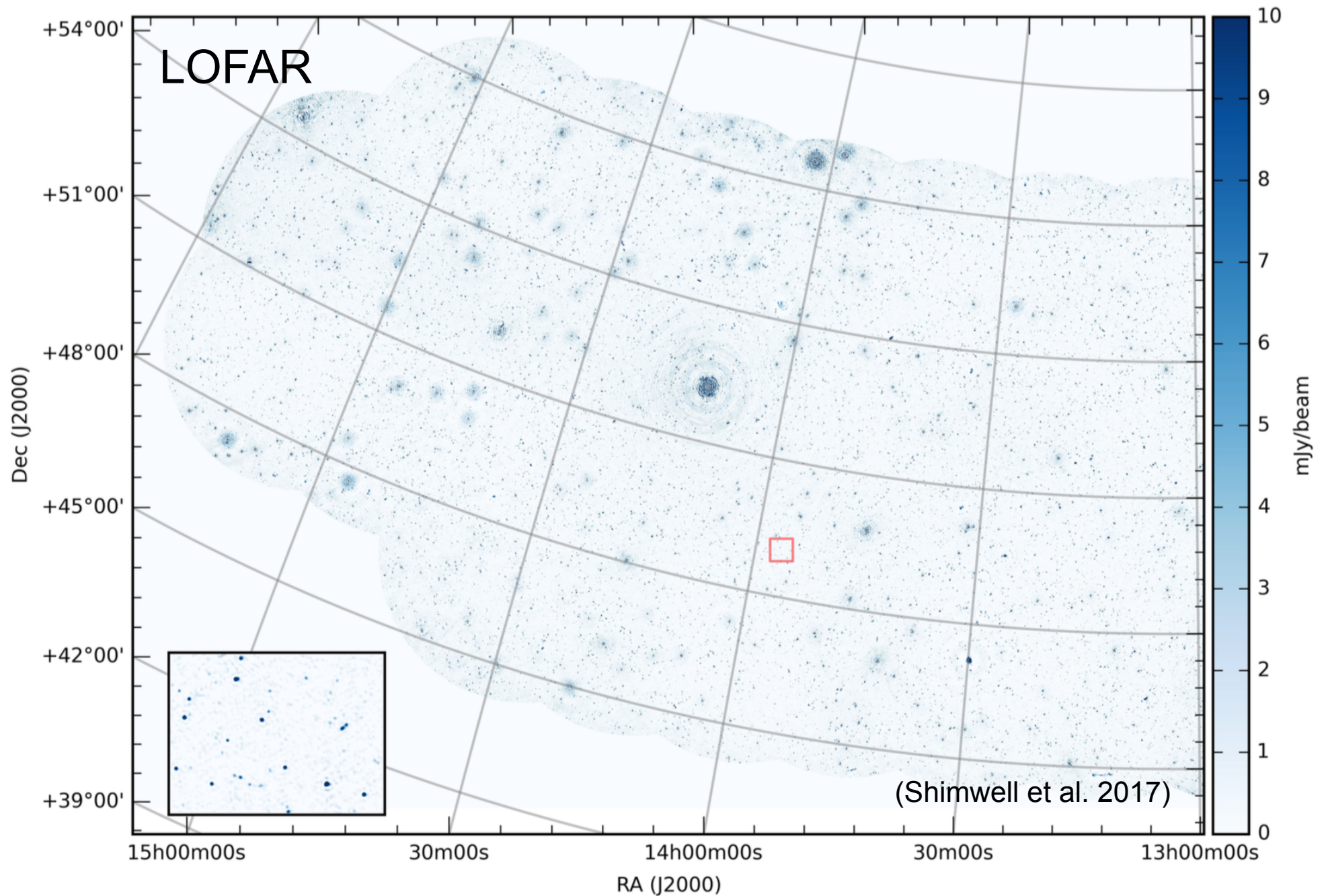
Extragalactic continuum SWG

- **AIM:** SWG established to investigate survey strategies and science capabilities of using continuum science (mainly star-forming galaxies and active galaxies).

- **OUTLINE:**
 1. Continuum science
 2. Minimum data products (images of sky surface brightness distribution)
 3. Desirable data products (re-processed images)

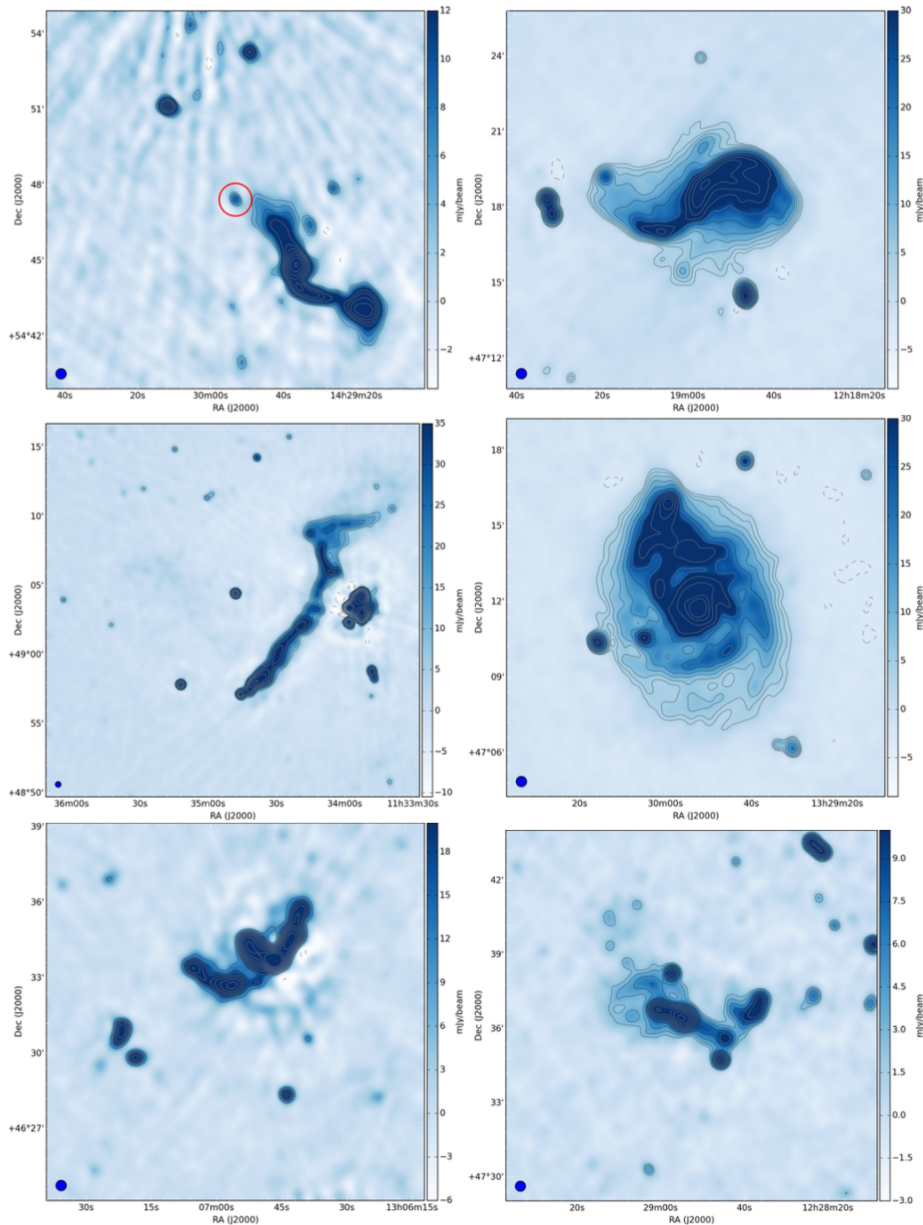
- **THE TEAM:**
 - **Chairs:** Mark Sargent (Sussex) and Natasha Hurley-Walker (Curtin)
 - **Associate Members:** 100 from 21 countries

Continuum science

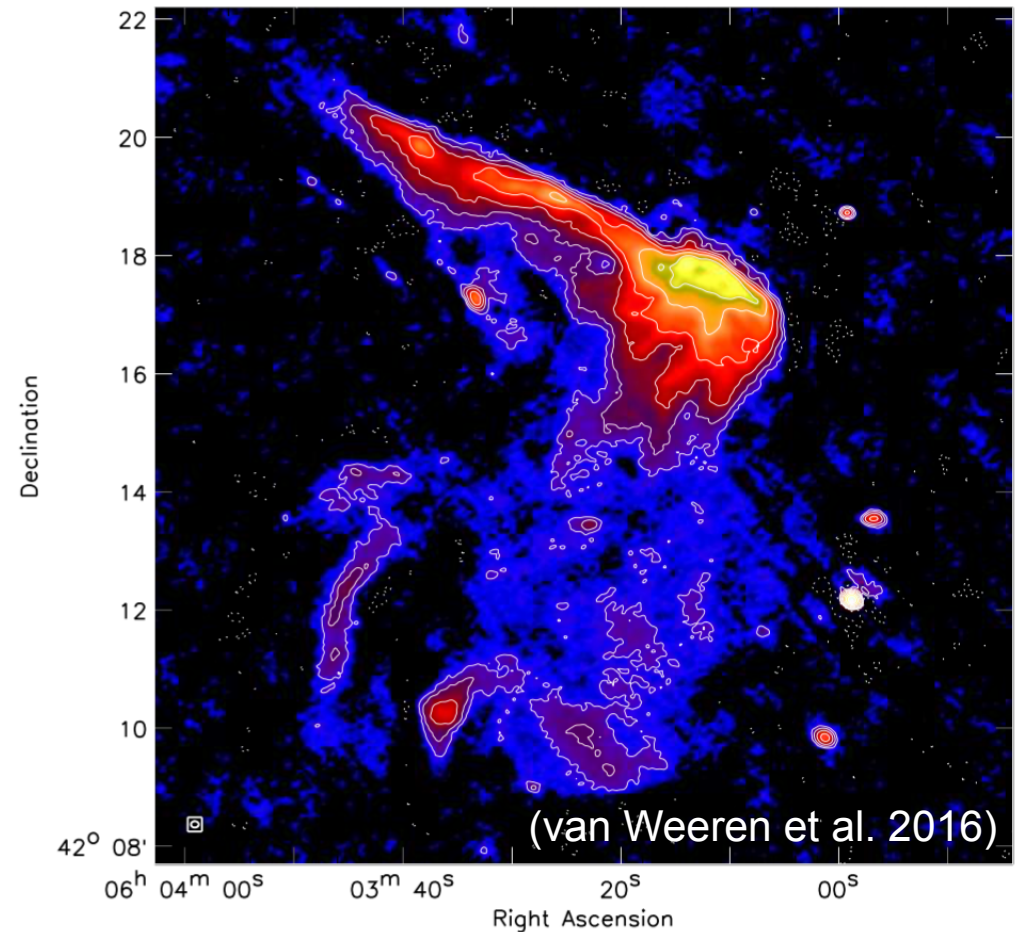


Continuum science

LOFAR



(Shimwell et al. 2017)



Key requirement: Images that describe the surface brightness distribution of the sky as a function of position.

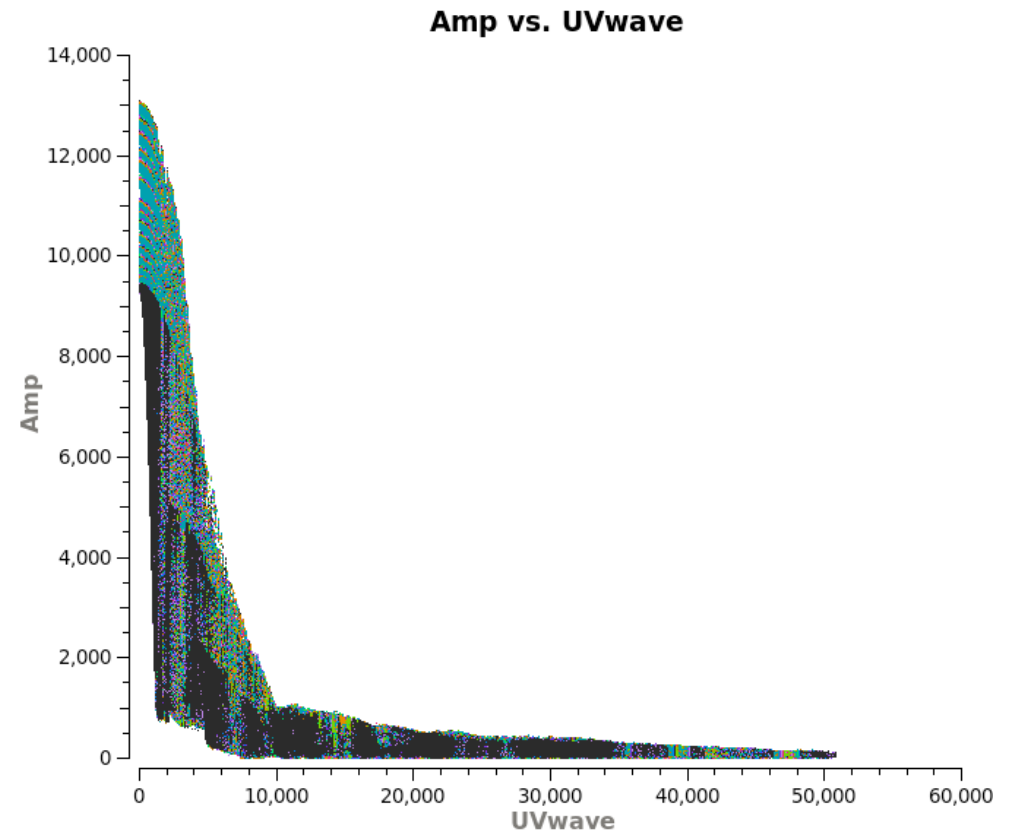
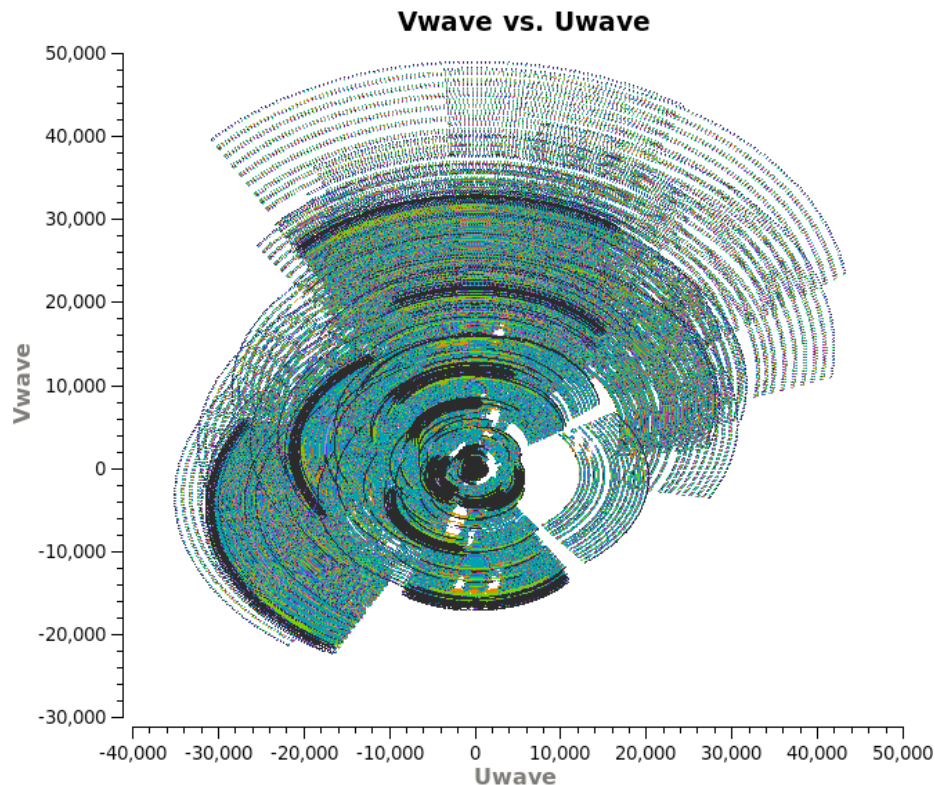
1. Accurate positions
2. Accurate flux-densities

Large spectral bandwidths

The SKA will have a large fraction bandwidth:

1. Good for sensitivity: $\sigma_T \sim (\Delta\nu)^{-0.5}$
2. Better for image fidelity: good uv-coverage.

Must know the surface brightness distribution as a function of frequency.



Multi-frequency synthesis

We can represent the sky in emission in terms of a Taylor expansion about some reference frequency (see Rau & Cornwell 2011).

Build $I(\nu)$ model:

$$I_{\nu}^m = \sum_{t=0}^{N_t-1} w_{\nu}^t I_t^{\text{sky}} \quad \text{where} \quad w_{\nu}^t = \left(\frac{\nu - \nu_0}{\nu_0} \right)^t$$

MS model image
Taylor co-efficient images

A power-law model is used to describe the spectral dependence of the sky emission.

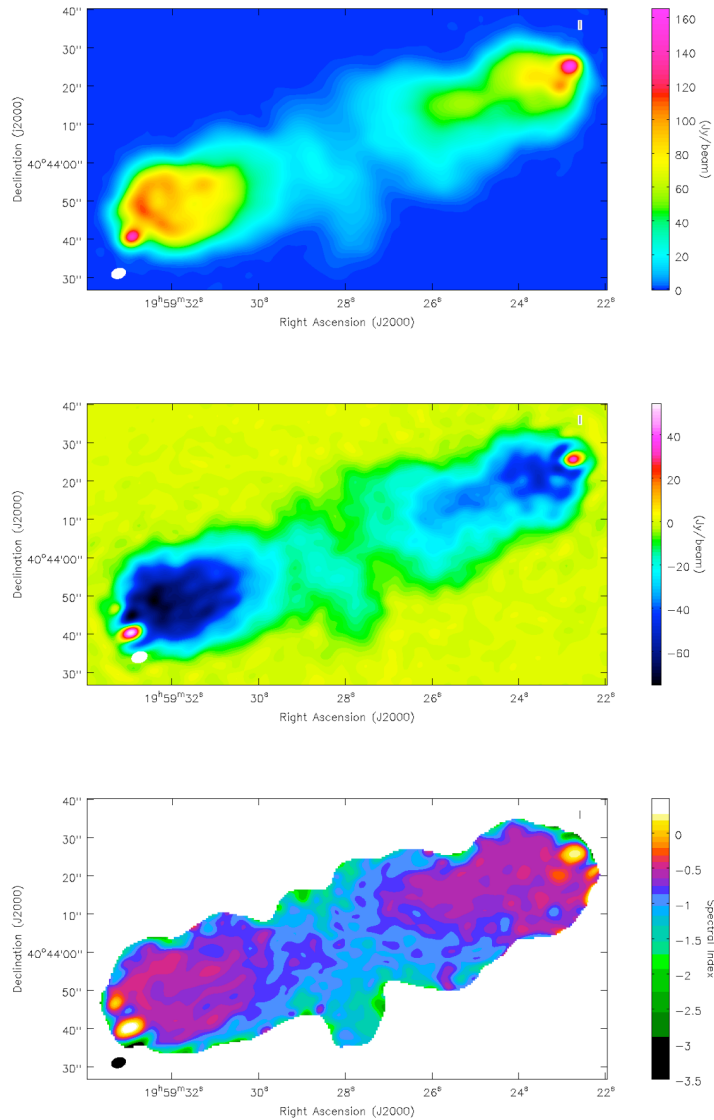
Parameterise:

$$I_{\nu}^{\text{sky}} = I_{\nu_0}^{\text{sky}} \left(\frac{\nu}{\nu_0} \right)^{I_{\alpha}^{\text{sky}} + I_{\beta}^{\text{sky}} \log \left(\frac{\nu}{\nu_0} \right)}$$

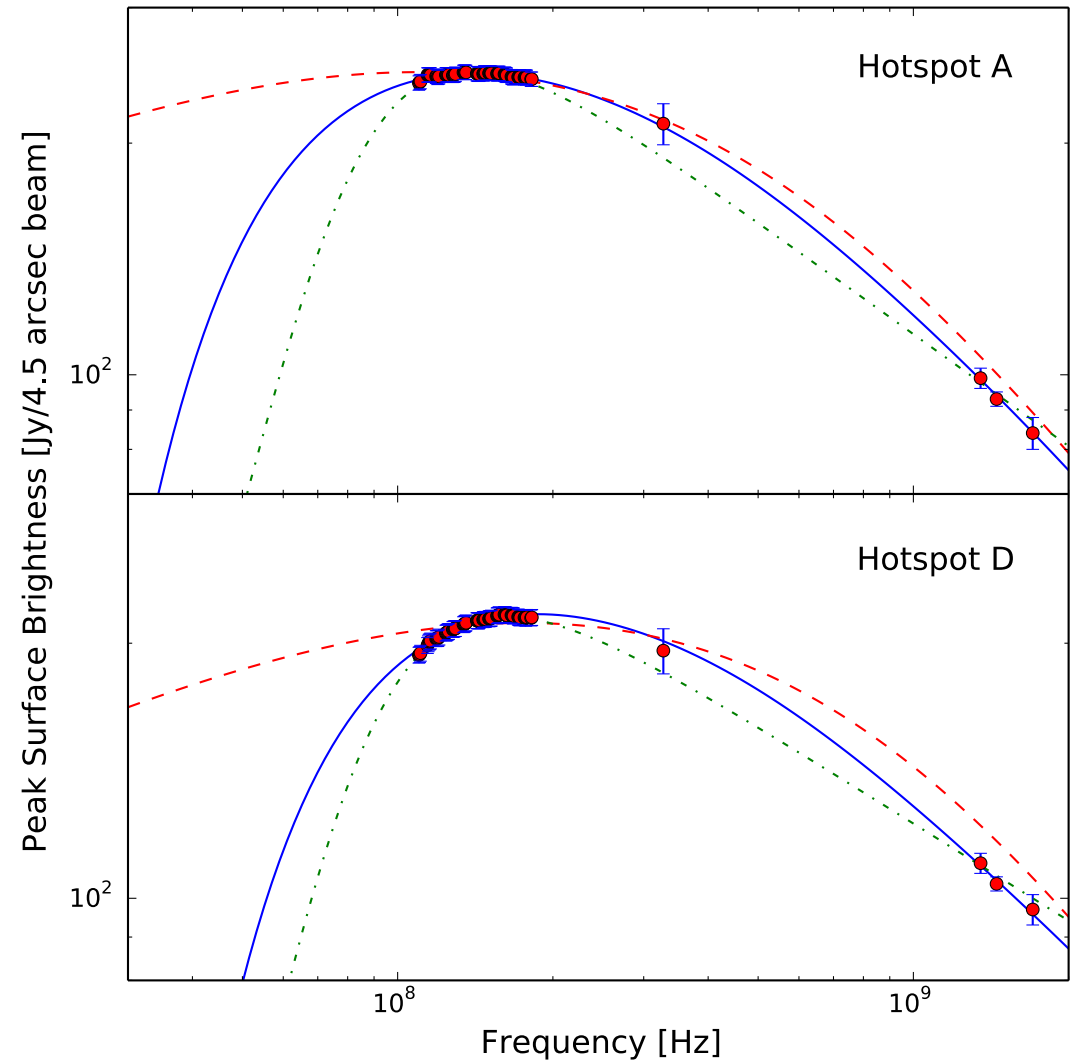
Sky images:

$$I_0^m = I_{\nu_0}^{\text{sky}} \quad ; \quad I_1^m = I_{\alpha}^{\text{sky}} I_{\nu_0}^{\text{sky}} \quad ; \quad I_2^m = \left(\frac{I_{\alpha}^{\text{sky}} (I_{\alpha}^{\text{sky}} - 1)}{2} + I_{\beta}^{\text{sky}} \right) I_{\nu_0}^{\text{sky}}$$

Spectral imaging



(McKean et al. 2017)

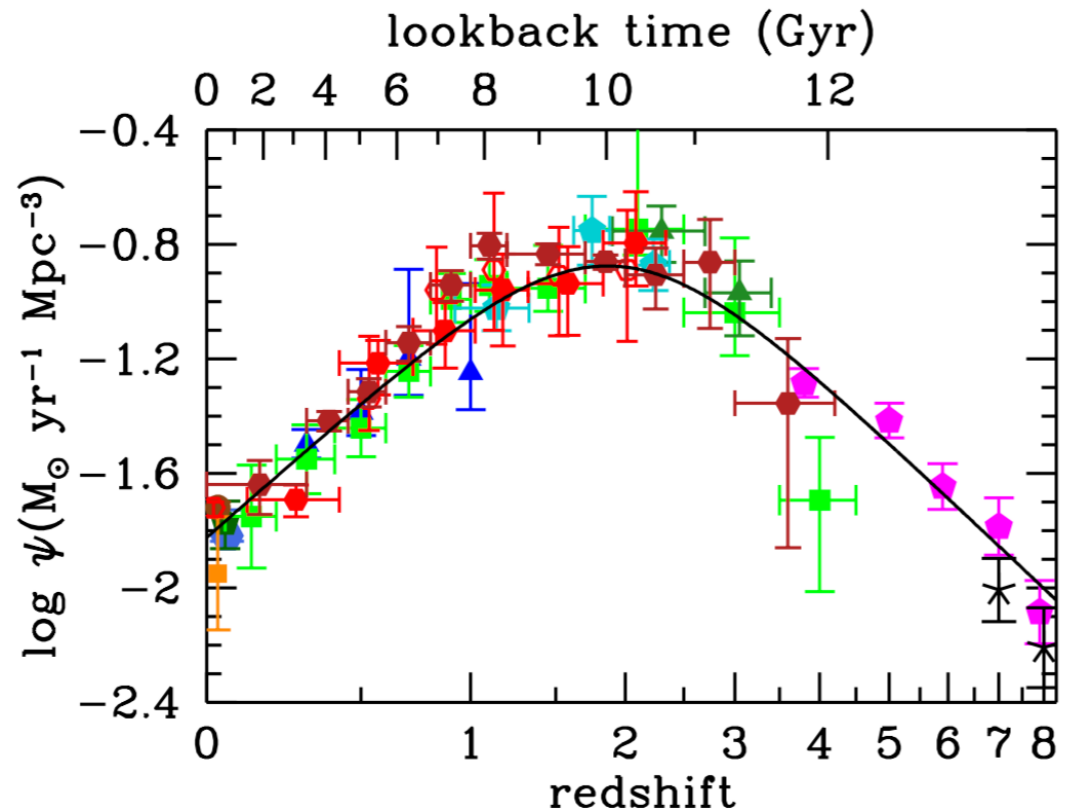


Key requirement: Images that describe the surface brightness distribution of the sky as a function of frequency (coarse).

SKA Continuum survey plans

Main science goal: Study the evolution of star-formation and active galactic nuclei activity across cosmic time.

Methodology: Will be carried out in a tiered survey approach from wide-shallow to narrow-deep.



General user: Continuum science will be the basic observing mode for the SKA and will have extensive general user appeal, requiring additional observations with different field of view and frequency requirements.

SKA Continuum survey plans

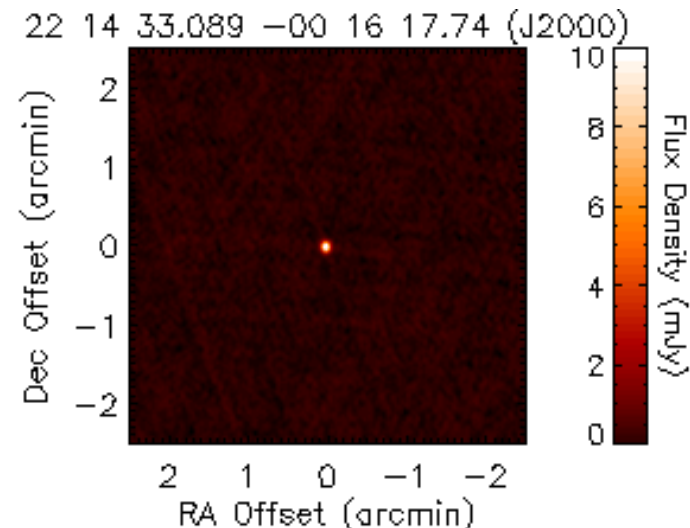
Survey Parameter	Tier 1	Tier 2	Tier 3
Area	1000	3-10	1
Sensitivity (μJy / beam)	1	0.2	0.05
Total time (h)	17200	12900	6560
Time per pointing (h)	8.2	205	3278
Pointing	2097	63	2
Frequency (GHz)	0.95-1.67	0.95-1.67	0.95-1.67
Time resolution (s)	0.13	0.13	0.13
Frequency resolution (kHz)	12.4	12.4	12.4
Taylor Terms	2	2	2
Polaisations	1	1	1
Field of view (deg)	0.70	0.70	0.70
Max baselines (km)	150	150	150
Pixel size (arcsec)	0.1 (25k x 25 k)	0.1 (25k x 25 k)	0.1 (25k x 25 k)

Survey Parameter	Tier 1	Tier 2
Area	1	0.04
Sensitivity (μJy / beam)	0.3	0.04
Total time (h)	1520	3300
Time per pointing (h)	11.8	662
Pointing	130	5
Frequency (GHz)	8.3-13.2	8.3-13.3
Time resolution (s)	0.2	0.2
Frequency resolution (kHz)	157.4	157.4
Taylor Terms	2	2
Polaisations	1	1
Field of view (deg)	0.088	0.088
Max baselines (km)	150	150
Pixel size (arcsec)	0.013 (25k x 25 k)	0.013 (25k x 25 k)

Example of possible continuum imaging data products from the FIRST survey.



Images and catalogues



167 x 167 pixels extracted from FIRST image 22135-00130Z
Brightest pixel is 11.35 mJy/beam at
X, Y = 84, 84 pixels
RA, Dec = 22 14 33.054 -00 16 17.99 (J2000)
RMS noise 0.114 mJy

Example from FIRST survey.

1. Quick look (jpg, png) to see the structure.
2. Downloadable FITS images for analysis.

Image server required so that the imaging data can be inspected:

1. Reliability: Has a real object been found (calibration or deconvolution error)?
2. Significance: Has the object of interest been detected at low significance and not identified in automated detection algorithms ($<6.5\sigma$)?
3. Multi-wavelength: How does the object compare with other wavebands?

Key requirement: VO catalogues specifying the source properties (position, flux-density, size, etc.) and downloadable science analysis (FITS?) images.

Calibration issues

Imaging wide-fields is useful for,

- 1) Efficient all-sky survey
- 2) Looking for rare objects

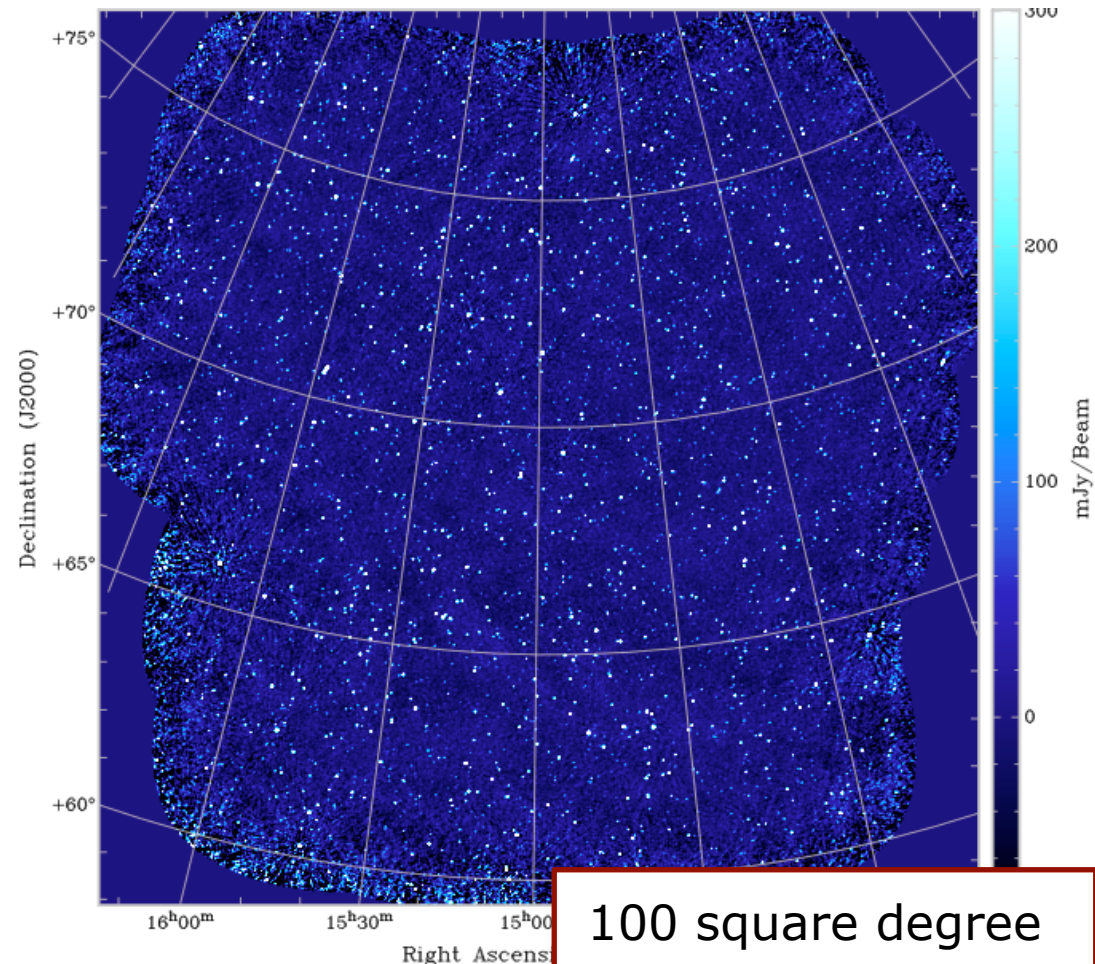
Wide-fields introduce many issues for a good calibration,

- 1) Variable beam power as a function of position results in a more complicated amplitude calibration.
- 2) The phase solutions in one direction cannot be applied to another.
- 3) Sky model is complicated (many sources).

An error in your model
can be absorbed in the
calibration

$$\vec{V}_{ij} = J_{ij} \vec{V}_{ij}^{\text{IDEAL}}$$

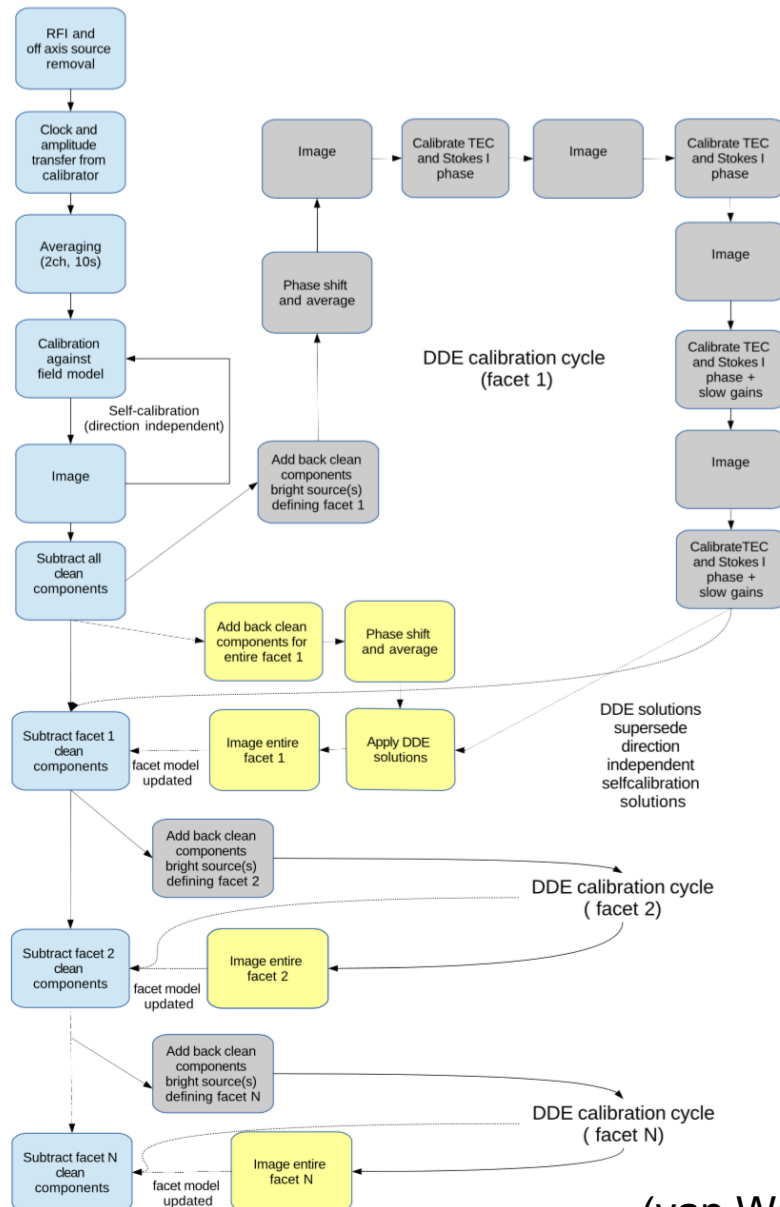
LOFAR MSSS SVF (Heald et al. 2015)



100 square degree
~10 mJy /beam [2
arcmin resolution]

Calibration issues

Sophisticated calibration schemes being developed for LOFAR, MeerKAT, ASKAP.



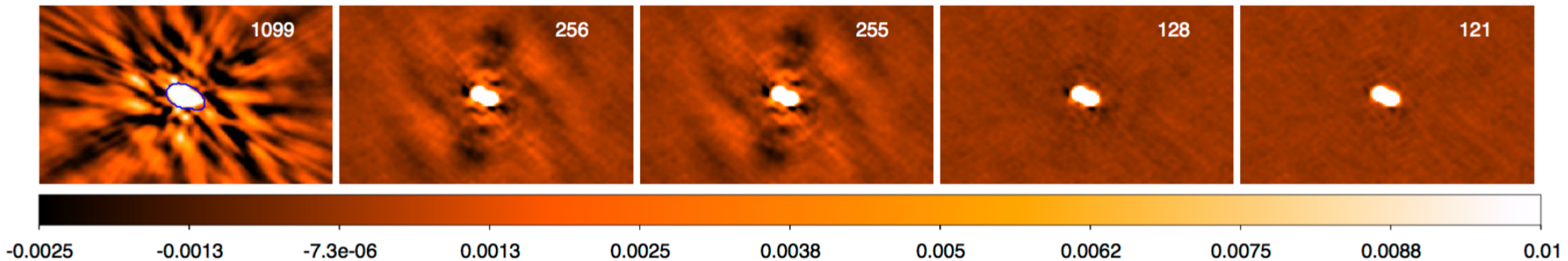
Basic calibration processes within the SDP.

1. RFI mitigation and flagging (AOflagger)
2. Direction independent calibration (GSM?)
3. Direction dependent effects calibration (facet based or all-in-one?)
4. Deconvolution (MS, MFS, compressed sensing?) — dependent on science goal (HI, magnetism, continuum-diffuse, continuum-compact).

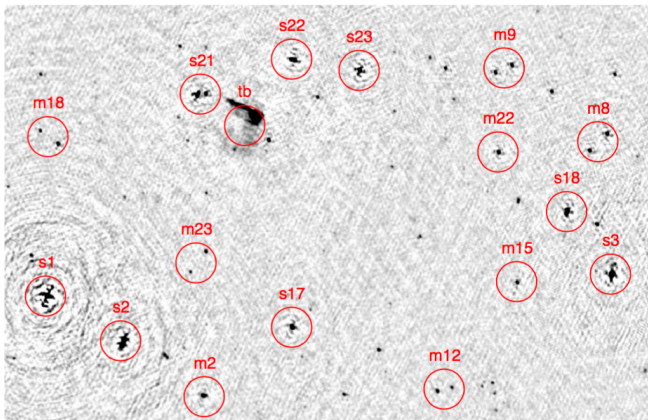
(van Weeren et al. 2016)

Calibration issues

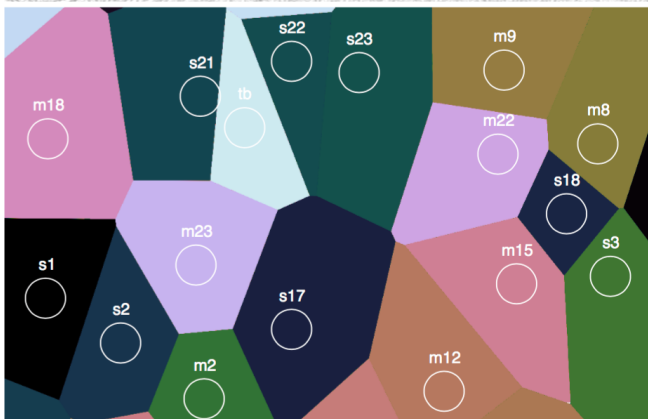
Sophisticated calibration schemes being developed for LOFAR, MeerKAT, ASKAP.



(van Weeren et al. 2016)

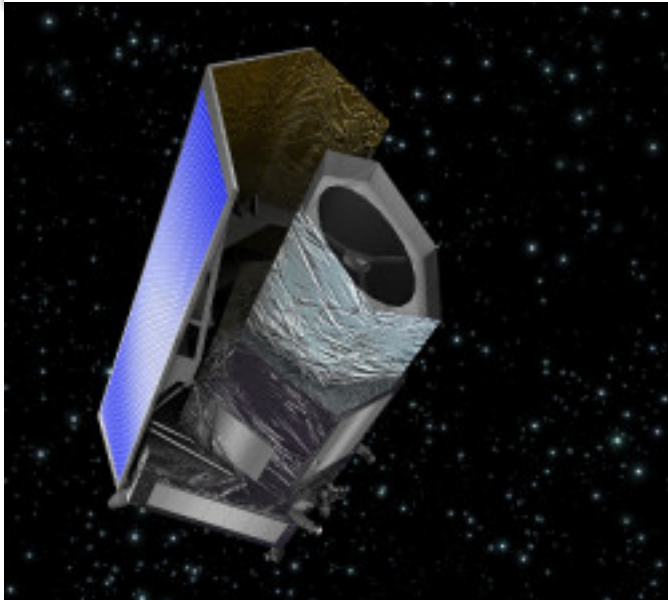


Key requirement: The visibility data (gridded) must be kept for calibration (especially at low frequencies).



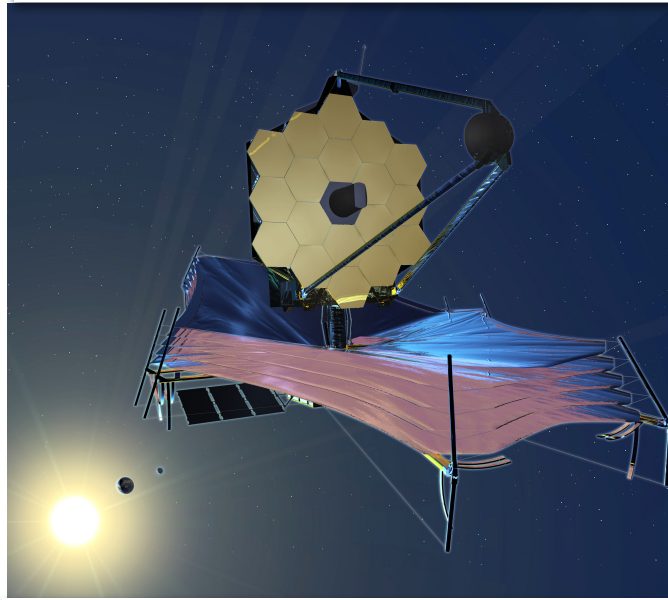
Multi-wavelength synergies

Euclid



- VIS-NIR (0.55–2 μm)
- Stellar emission
- Photometry (1.5×10^9 galaxies)
- Spectroscopy (2×10^7 galaxies)
- Resolution 0.2–0.6 arcsec.
- Wide-field (15000 deg^2)
- Narrow-field ($2 \times >10 \text{ deg}^2$)
- Launch 2020

JWST



- VIS-MIR (0.6–28.5 μm)
- 6.5 m mirror
- Stellar and hot dust emission
- Targeted photometry
- Targeted spectroscopy
- Resolution 0.1–5 arcsec
- Narrow-field ($5\text{--}9 \text{ arcmin}^2$)
- Launch 2018

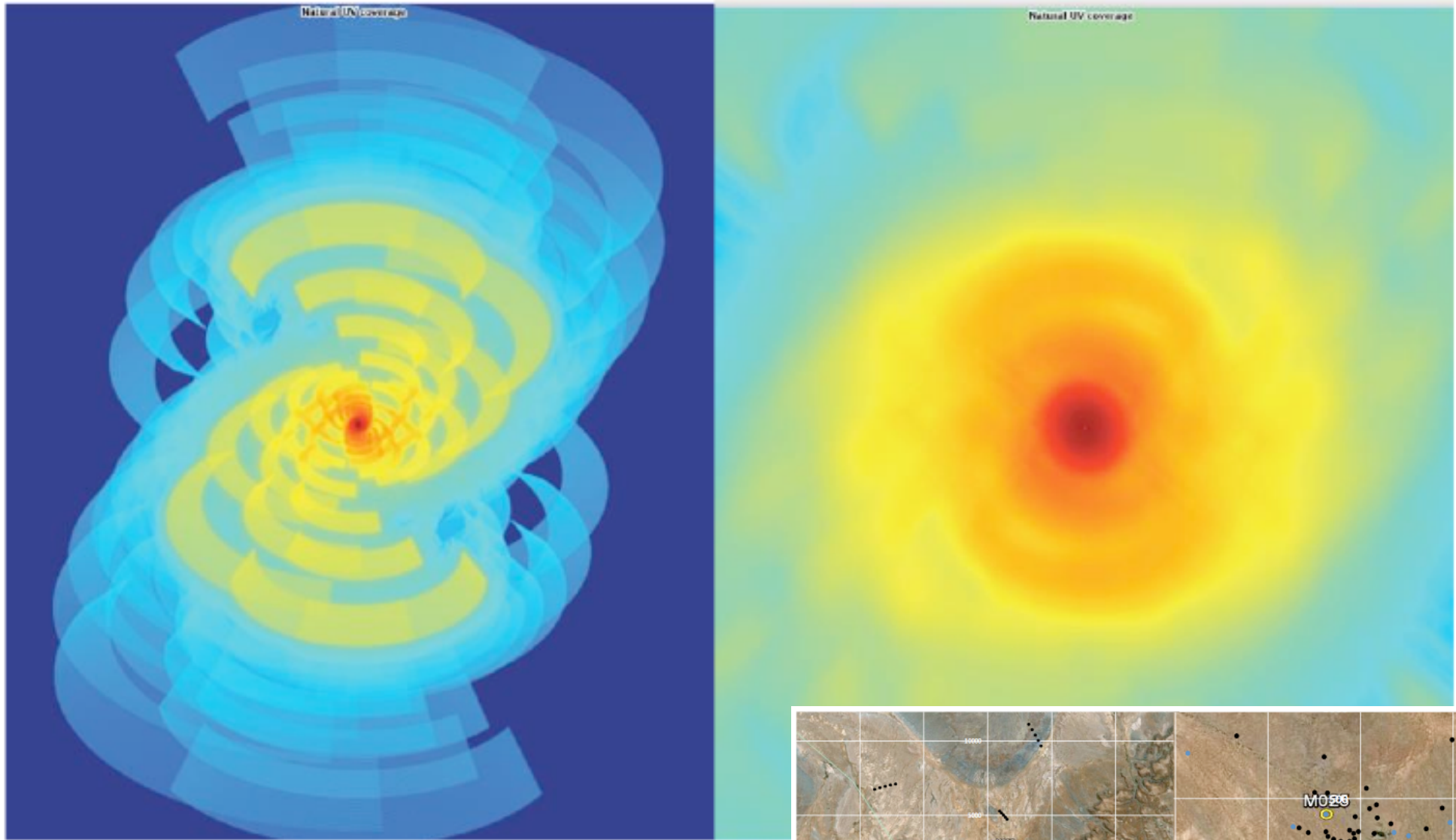
ALMA



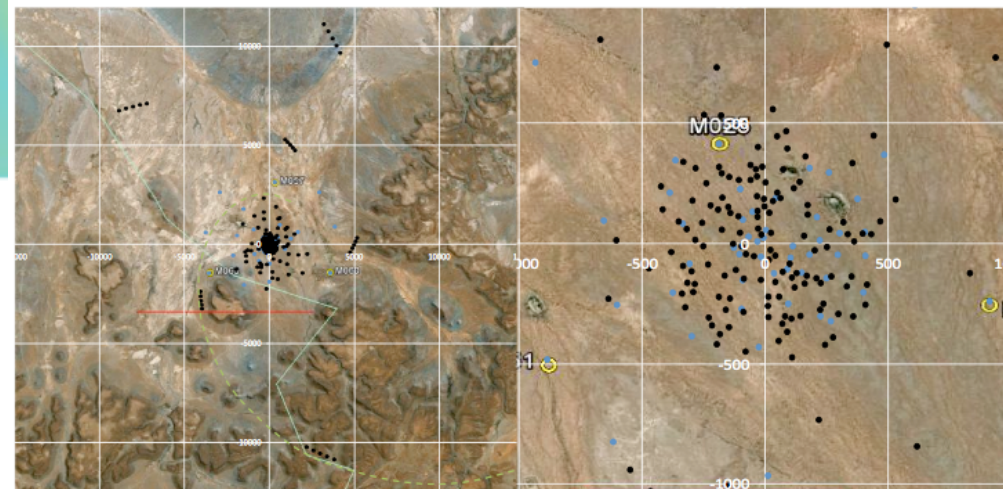
- mm-sub-mm (85—1000 GHz)
- 54 x 12 m and 12 x 7 m dishes
- Heat dust and molecular gas emission.
- Follow-up photometry and spectroscopy
- Resolution 0.01–19 arcsec
- Narrow-field (0.1 arcmin^2)
- Operational!

All a big step forward in resolution (and sensitivity) from e.g. SDSS, HST+Spitzer, SMA+PdB

Re-processing to higher angular resolution (SRC)

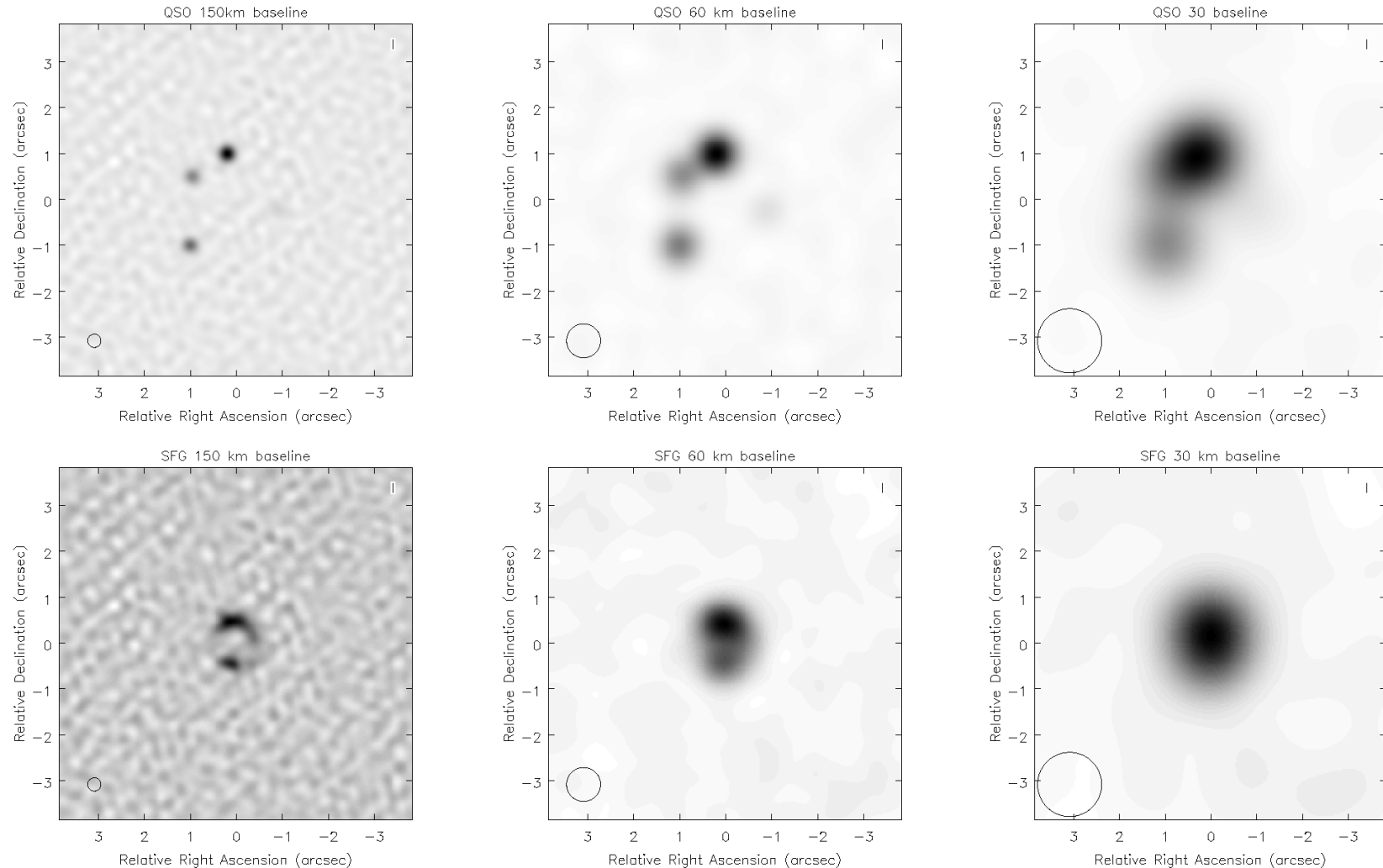


Imaging performance / requirements can be flexible, depending on how the uv-data are used.



Re-processing to higher angular resolution (SRC)

Example of a gravitational lens observed with different visibility weightings.



(McKean et al. 2015)

Desirable requirement: The visibility data (gridded) must be kept and be re-processed for different uv-coverage requirements.

Data products accessed at SRC

Data Product	Description (For each product a QA and Processing Log will also be maintained)
Image Products 1: Image Cubes	1. Imaging data for Continuum, as cleaned restored Taylor term images (n.b. no image products for Slow Transients detection have been specified maps are made, searched and discarded) 2. Residual image (i.e. residuals after applying clean) in continuum 3. Clean component image (or a table, which could be smaller). 4. Spectral line cube after continuum subtracted 5. Residual spectral line image (i.e. residuals after clean applied) 6. Representative Point Spread Function for observations (cutout, small in size compared to the field of view (FoV))
Image Products 2: UV-grids	1. Calibrated visibilities, gridded onto grids at the spatial and frequency resolution required by the experiment. One grid per facet (so this grid is the FFT of the dirty map of each facet). c.f. ECP150007 2. Accumulated Weights for at each uv cell in each grid (without additional weighting applied).
Calibrated Visibilities	Calibrated visibility data (for example for EoR experiments) and direction-dependent calibration information, with time and frequency averaging performed as requested to reduce the data volume.
LSM Catalogue	Catalogue of a subset of the Global Sky Model (GSM) containing the sources relevant for the scheduling block being processed. These are the sources in the FoV, as well as, potentially, strong sources outside of the current FoV. Initially, the LSM is filled from the GSM; during the data processing the sources found in the images are added to the LSM.
Transient Source Catalogue	Time-ordered catalogue of candidate transient objects pertaining to each detection alert from the real-time, so-called, Fast Imaging.

Summary

1. Continuum observing modes and associated data products will be the work horse of the SKA, with the largest range of science goals and users.
2. The Extragalactic Continuum SWG is designing a 3 / 2 tier survey approach at 2 observing frequencies with the SKA.
3. General User experiments will have different science and therefore technical requirements (but will broadly be consistent with the SWG plans).

Key/desirable requirements:

1. Catalogues specifying the source properties (position, flux-density, size, etc.) and downloadable FITS images.
2. Images that describe the surface brightness distribution of the sky as a function of position.
3. Images that describe the surface brightness distribution of the sky as a function of frequency (coarse).
4. The visibility data (gridded) must be kept for calibration (especially at low frequencies).
5. The visibility data (gridded) must be kept and be re-processed for different uv-coverage requirements.