Systematic effects in LOFAR

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Overview

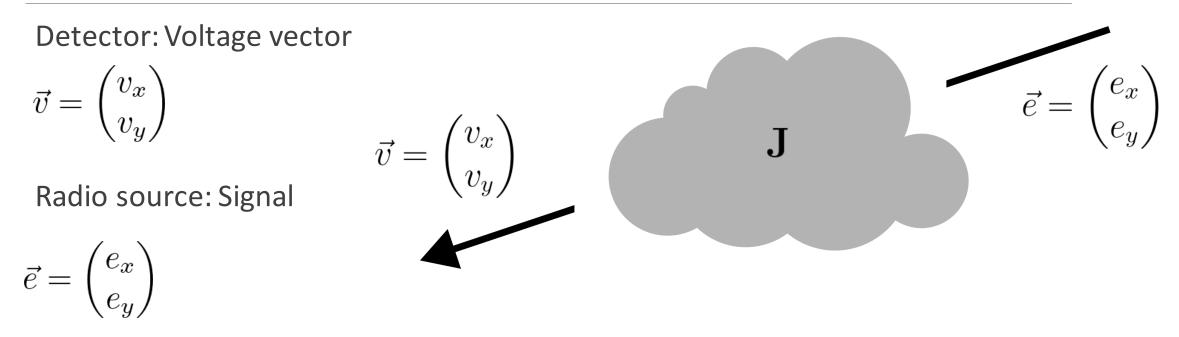
Jones Formalism

Calibration fundamentals

Overview of systematic effects

Tutorial

Linking signal to voltage



Linked by series of matrices: Jones matrix • Each effect has corresponding matrix

 $[\]vec{v} = \mathbf{J}\vec{e}$

Jones Matrices

From signal to voltage: chain of Jones matrices

Note: matrix multiplication in general not commutative!

$$\vec{v} = \mathbf{J}_1 \mathbf{J}_2 \mathbf{J}_3 \dots \mathbf{J}_n \vec{e}$$
$$= \mathbf{J} \vec{e}$$

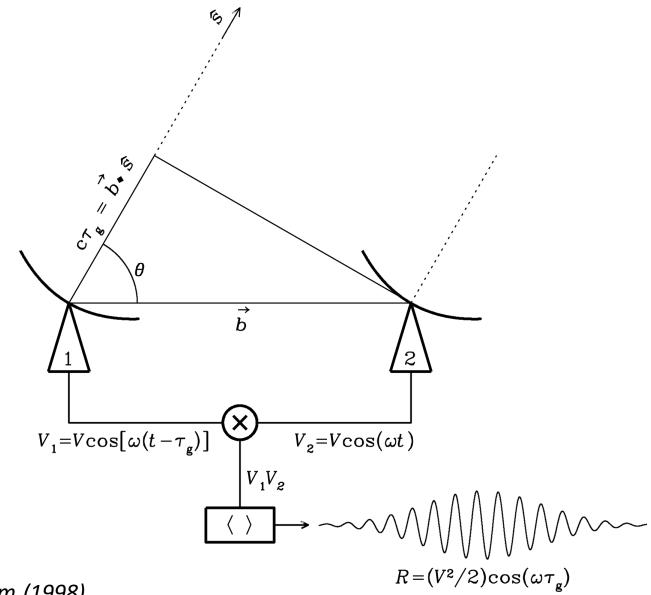
Each effect has it's own Jones matrix

Jones Formalism and visibilities (1)

Link between sky intensity distribution and mutual coherence function: **van Cittert-Zernike theorem** (*Thompson, Moran, Swenson* // *Oei*)

$$\left\langle \vec{E}(\vec{r_1})\vec{E}(\vec{r_2})^{\dagger}\right\rangle \approx \int_{-\infty}^{\infty}\int_{-\infty}^{\infty}\int_{-\infty}^{\infty}I_{\nu}(l,m)e^{-2\pi i(ul+vm)}\mathrm{d}l\mathrm{d}m$$

Sky intensity distribution and mutual coherence function are Fourier pairs!



Condon and Ransom (1998)

Jones Formalism and visibilities (2)

Construction of mutual coherence: Assume *quasi-monochromatic* interferometer

Then two interferometers have E-field:

Multiply, then take time average

(removes fast component)

$$V_1 = V \cos(\omega t)$$
$$V_2 = V \cos(\omega (t - \tau_g))$$
$$\tau_g = \frac{\vec{b} \cdot \hat{s}}{c}$$

$$\mathcal{R}_{c} = \langle V_{1}V_{2}^{\dagger} \rangle = \langle V^{2}\cos(\omega t)\cos(\omega(t-\tau_{g})) \rangle$$
$$= \left\langle \frac{V^{2}}{2} [\cos(2\omega t - \omega\tau_{g}) + \cos(\omega\tau_{g})] \right\rangle$$
$$= \frac{V^{2}}{2} \cos(\omega\tau_{g})$$

Jones Formalism and visibilities (3)

Do the same for sine-part of signal. Complex Visibility:

$$\mathcal{V} = \mathcal{R}_c + i\mathcal{R}_s = Ae^{-i\phi}$$

If you have two feeds, e.g. x and y-feed (polarization), you will get four visibilities per unique pair of antennas: $V_{xx}, V_{xy}, V_{yx}, V_{yy}$

Complex visibility can form a matrix:

$$\mathbf{V} = \langle \vec{v}_1 \vec{v}_2^{\dagger} \rangle = \begin{pmatrix} \mathcal{V}_{xx} & \mathcal{V}_{xy} \\ \mathcal{V}_{yx} & \mathcal{V}_{yy} \end{pmatrix}$$

Jones Formalism and visibilities (4)

How does Jones matrix play into this?

Recall: $\vec{v} = \mathbf{J}\vec{e}$

$$\mathbf{V}_{12} = \langle \vec{v}_1 \vec{v}_2^{\dagger} \rangle = \langle \mathbf{J}_1 \vec{e}_1 (\mathbf{J}_2 \vec{e}_2)^{\dagger} \rangle = \mathbf{J}_1 \langle \vec{e}_1 \vec{e}_2^{\dagger} \rangle \mathbf{J}_2^{\dagger} \quad \langle \vec{e}_1 \vec{e}_2^{\dagger} \rangle \equiv \mathbf{B}$$

N-element interferometer: N^2-N/2 visibilities, N Jones matrices

Radio interferometery measurement equation (RIME)

$$\mathbf{V}_{ij} = \mathbf{J}_i \mathbf{B}_{ij} \mathbf{J}_j^\dagger$$

Calibration

Goal of calibration: Find relevant Jones matrices • Reconstruct B from measured V

Given: a starting model (reference visibilities) Solve: $||\mathbf{V}_{\text{obs},ij} - \mathbf{J}_i \mathbf{V}_{\text{model},ij} \mathbf{J}_j^{\dagger}||$ for $\mathbf{J} = \begin{pmatrix} A_{xx} e^{i\phi_{xx}} & A_{xy} e^{i\phi_{xy}} \\ A_{yx} e^{i\phi_{yx}} & A_{yy} e^{i\phi_{yy}} \end{pmatrix}$

DP3

Strategies: talk by Reinout van Weeren

Calibrators

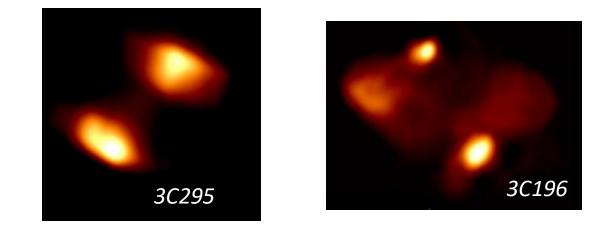
Reference object, we know the structure

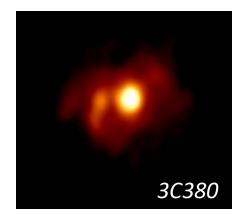
Very bright (high signal to noise)

Compact emission

• Diffuse emission is missed by long baselines

Well defined spectrum (Scaife and Heald, 2012)





Solutions

Calibration generates solutions (complex number) • Each solution (gain) consists of an amplitude and a phase

Solutions: for each time, frequency, polarization, calibration gives amplitude+phase part

Solutions contain both *lonospheric* and *systematic* effects

Instrumental Systematic effects

Type of Jones matrix ^a	$\rm Ph/Amp/Both^b$	Frequency dependency	Direction dependent?	Time dependent?
Scalar	Ph	$\propto u$	No	Yes (many seconds)
Diagonal	Ph	$\propto u$	No	No
Scalar	Ph	$\propto u^{-1}$	Yes	Yes (few seconds)
Rotation	Both	$\propto u^{-2}$	Yes	Yes (few seconds)
Scalar	Ph	$\propto u^{-3}$	Yes	Yes (few seconds)
Diagonal	Amp	_	Yes	Yes (few seconds)
Full-Jones	Both	-	Yes	Yes (minutes)
Diagonal	Amp		No	No
	Jones matrix ^a Scalar Diagonal Scalar Rotation Scalar Diagonal Full-Jones	Jones matrixaScalarPhDiagonalPhScalarPhRotationBothScalarPhDiagonalAmpFull-JonesBoth	Jones matrixadependencyScalarPh $\propto \nu$ DiagonalPh $\propto \nu$ ScalarPh $\propto \nu^{-1}$ RotationBoth $\propto \nu^{-2}$ ScalarPh $\propto \nu^{-3}$ DiagonalAmp-Full-JonesBoth-	Jones matrixadependencydependent?ScalarPh $\propto \nu$ NoDiagonalPh $\propto \nu$ NoScalarPh $\propto \nu^{-1}$ YesRotationBoth $\propto \nu^{-2}$ YesScalarPh $\propto \nu^{-3}$ YesDiagonalAmp-YesFull-JonesBoth-Yes

De Gasperin et al. 2019

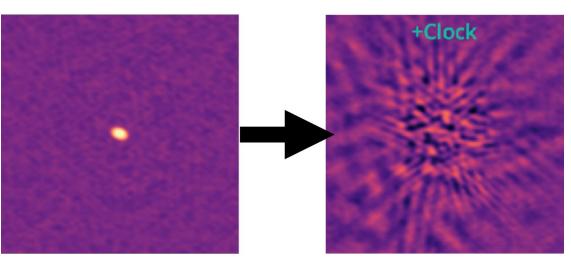
Clock drift

Remote stations have individual clocks, that slowly drift O(10ns/hr)

Introduces scalar phase error: $\Delta \phi = 2 \pi \nu \Delta t$

Scales as $\sim
u$

$$\mathbf{J}_{i,\text{clock}} = e^{2\pi i\nu\Delta t} \begin{pmatrix} 1 & 0\\ 0 & 1 \end{pmatrix}$$



Polarisation misalignment

Small time delay between X- and Y-feeds (on station basis)

$$\mathbf{J}_{i,\text{pol. align}} = \begin{pmatrix} 1 & 0\\ 0 & e^{2\pi i\nu\Delta t} \end{pmatrix}$$

O(ns)

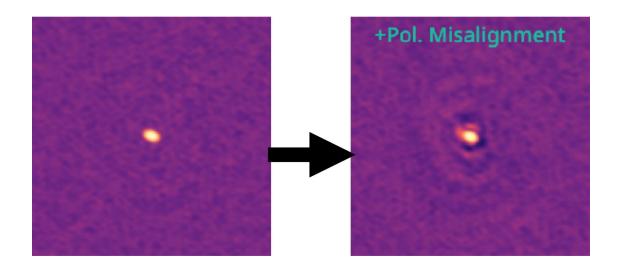


Image credit: Henrik Edler

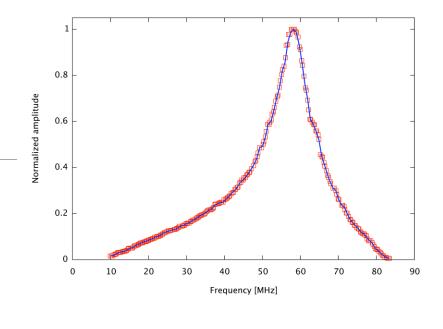
Bandpass

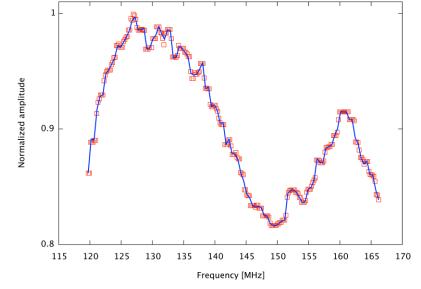
Frequency dependence of instrument response

Time-independent

Real valued Jones matrix:

$$\mathbf{J}_{i,\text{bandpass}} = \begin{pmatrix} A_{xx} & 0\\ 0 & A_{yy} \end{pmatrix}$$





Primary beam

System response of instrument

Direction dependent

Can be directly calculated with Everybeam

Two elements Element beam (Full-Jones)
Array factor (scalar term)

$$\mathbf{J}_{i,\text{beam}} = a_{\text{arr}} e^{i\phi_{\text{arr}}} \begin{pmatrix} A_{xx} e^{i\phi_{xx}} & A_{xy} e^{i\phi_{xy}} \\ A_{yx} e^{i\phi_{yx}} & A_{yy} e^{i\phi_{yy}} \end{pmatrix}$$

Isolating effects - LoSoTo

Lofar Solution Toolkit

Used for manipulating solutions

Solutions: for each time, frequency, polarization, find amplitude+phase part

Fit systematic effects in solutions

Fitting Polarization misalignment

Phase solutions (XX and YY)

Ionosphere and clock effects work on XX and YY identically

Polarization alignment causes a difference between XX and YY

LoSoTo POLALIGN:

Takes long time average of XX-YY

Reduces amount of free parameters

 $n_{\rm freqs} \times n_{\rm time} \times n_{\rm stations} \times 2 \rightarrow n_{\rm stations}$

Fitting bandpass

Bandpass: amplitude effect (different for XX and YY)

LoSoTo Smooth

 $n_{\rm freqs} \times n_{\rm time} \times n_{\rm stations} \times 2 \rightarrow n_{\rm stations} \times n_{\rm freqs} \times 2$

Tutorial

10 min. Calibrator scan of 3C295

Perform (part of) calibrator pipeline

Diagonal solve
$$\mathbf{J} = \begin{pmatrix} A_{xx}e^{i\phi_{xx}} & 0\\ 0 & A_{yy}e^{i\phi_{yy}} \end{pmatrix}$$

Extract bandpass+polarization alignment

(Clock and ionosphere require separate treatment --> Talk by Maaike Mevius)

Software used

https://tikk3r.github.io/flocs/

https://dp3.readthedocs.io/en/stable/

https://github.com/revoltek/losoto/releases

Steps

Use FLOCS (https://tikk3r.github.io/flocs/)

Predict (Converts skymodel to model visibilities)

Solve (Find solutions based on data and model visibilities) • Note: Not completely accurate (no rotation solve)

Extract polarization alignment with LoSoTo

Extract bandpass with LoSoTo