

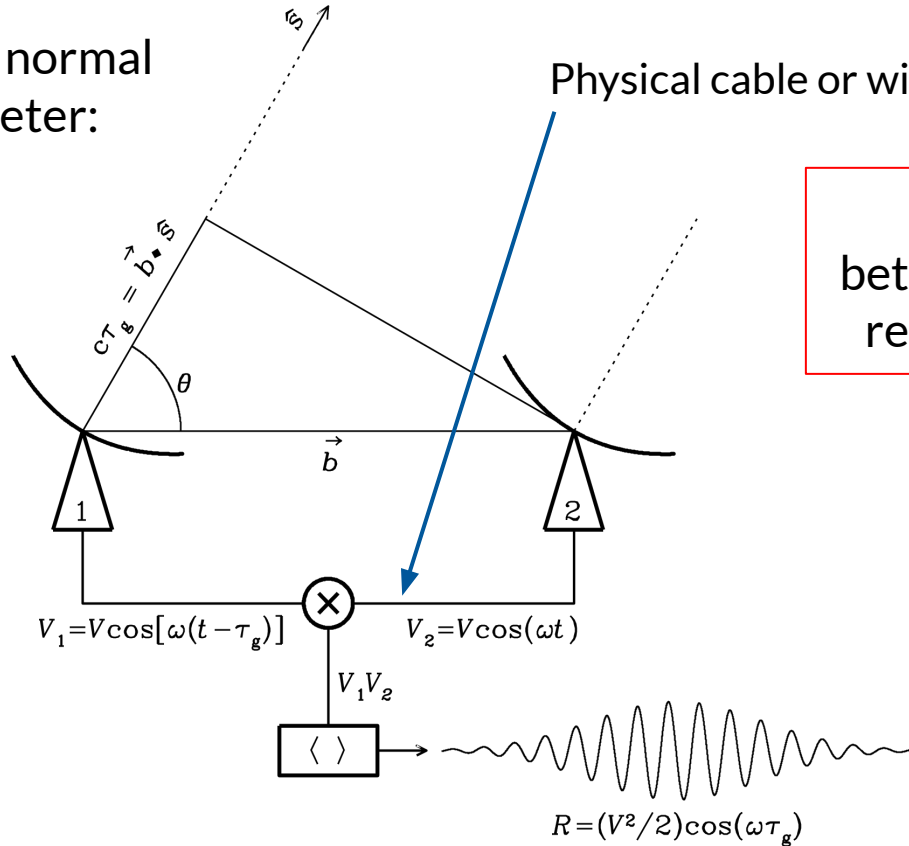
# Very Long Baseline Interferometry with the LOw Frequency ARray (LOFAR)

Roland Timmerman  
Postdoctoral Research Associate



# What is Very Long Baseline Interferometry?

Consider a normal interferometer:



Physical cable or wireless transmission

In VLBI, the separations between antenna are too large, requiring separate recording



# What is Very Long Baseline Interferometry?

## Formally:

Interferometry where the signal of each antenna is recorded using **separate clocks**

## Colloquially:

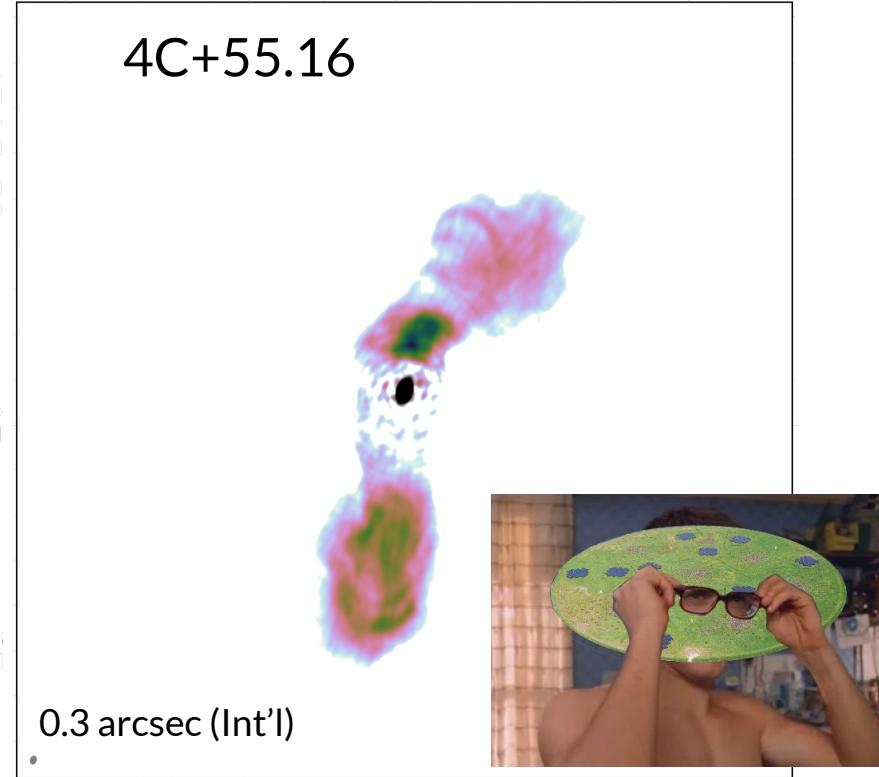
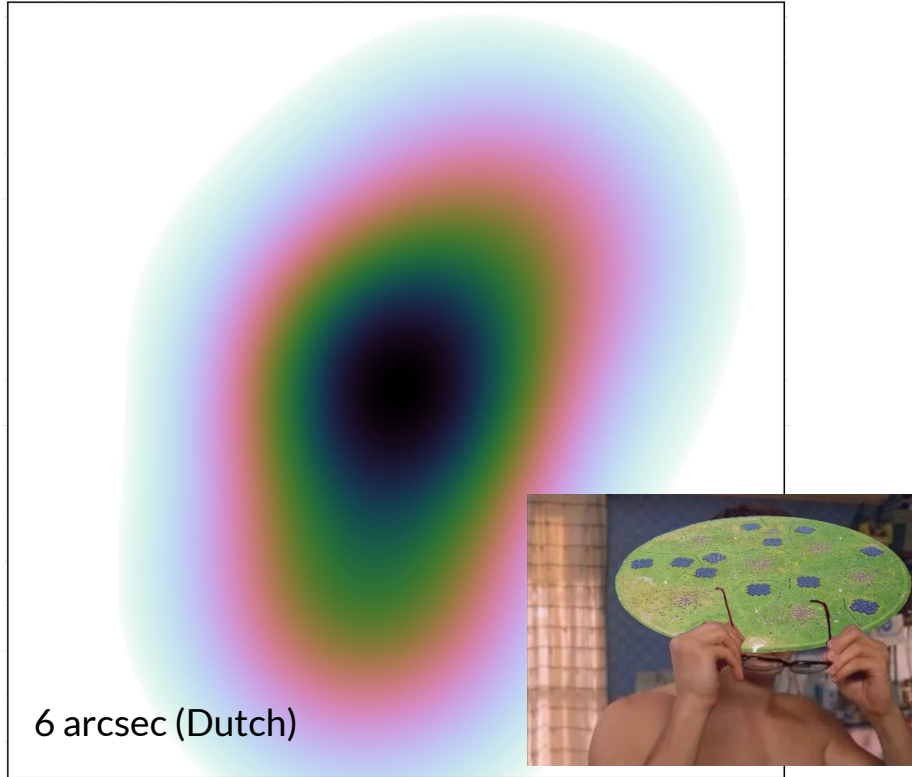
Interferometry with long enough baselines that you get the typical “VLBI problems”:

- Sparse array configurations with low degeneracy
- Decrease in S/N as flux decreases on longer baselines
- Strongly varying atmospheric conditions between the antennas
- Longer baselines increase requirements on imaging and data rates

But all of these problems are worth it, because of the spectacular **angular resolution!**

(Rule of thumb: if you Google for images and you get maps instead of photos, it's probably VLBI)

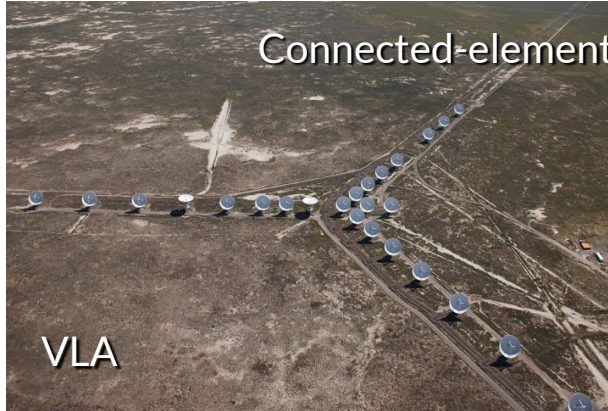
# Dutch LOFAR vs. International LOFAR Telescope





# VLBI: Sparse array configurations

Connected-element interferometers



General considerations:

- Large enough total effective area
- Cost-effective size per antenna
- Sampling of the uv-plane
- Wide variety in spacings
- Minimum baseline tends to be the size of the antenna
- Maximum baseline typically determined by target resolution or practical limits
- Side-lobes suppressed as much as possible
- All of the data also has to be processed...

Plus a lot of other details...

# VLBI: Sparse array configurations

TABLE II  
PERFORMANCE REQUIREMENTS AND RESULTING DESIGN FEATURES  
OF THE VLA

Performance Requirement	Design Feature
1. Angular resolution $\leq 0.6''$ at 6 cm wavelength.	Array arms 21 km long; maximum spacing 36.4 km.
2. Specified resolution to be achieved over declination range $+90^\circ$ to $-20^\circ$ .	Equiangular Y configuration and tracking range $-4^h$ to $4^h$ of hour angle.
3. Variable resolution to allow observation of sources with a range of angular scales.	Four configurations with total range 36:1 in linear scale, requiring rail track and transporters.
4. Map with full resolution to be obtainable from one 8-hour observation.	Use of 27 antennas and configuration designed for optimum (u,v) coverage.
5. Peak sidelobes of synthesized beam not to exceed -16 dB except at declination $-0^\circ$ .	As in 4 above.
6. Antenna beams to allow circular field 1' diameter at shortest wavelength.	Antennas are 25m-diameter shaped parabolic reflectors.
7. Sensitivity to be sufficient for detection of source of flux density $10^{-4}$ Jy.	Size of antennas, system noise temperatures, and $8^h$ observing time.
8. Ability to measure complete polarization characteristics.	Oppositely polarized feeds with separate receiving channels for each output.
9. Several wavelength bands to be available under computer control.	Offset feeds, rotating sub-reflector, and front ends for several bands mounted in one Dewar.
10. Spectroscopic as well as continuum observations to be possible.	Digital spectral correlator using recirculation principle.



## General considerations:

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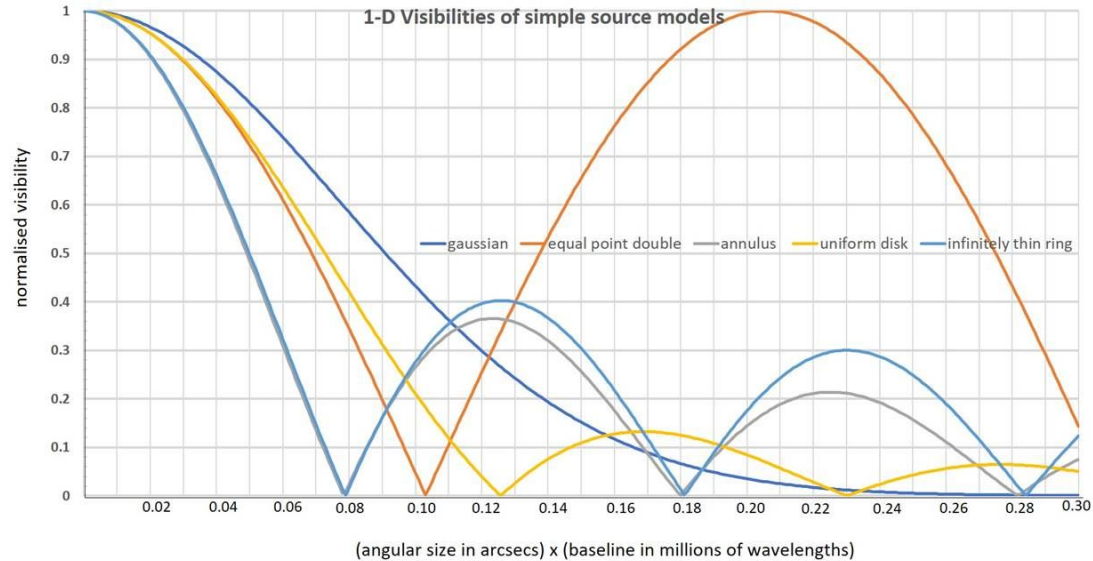
# VLBI: Sparse array configurations



- Cost per antenna typically high (Separate clocks, infrastructure, etc...)
  - Strong geographical constraints (Oceans, mountains, country borders, political and economic situations...)
  - Maximum baseline determined by size of our planet
- Typically fewer stations, less optimal configurations, sparse coverage

# VLBI: Decreasing S/N at high resolutions

Remember: visibilities probe the **Fourier transform** of the sky brightness distribution

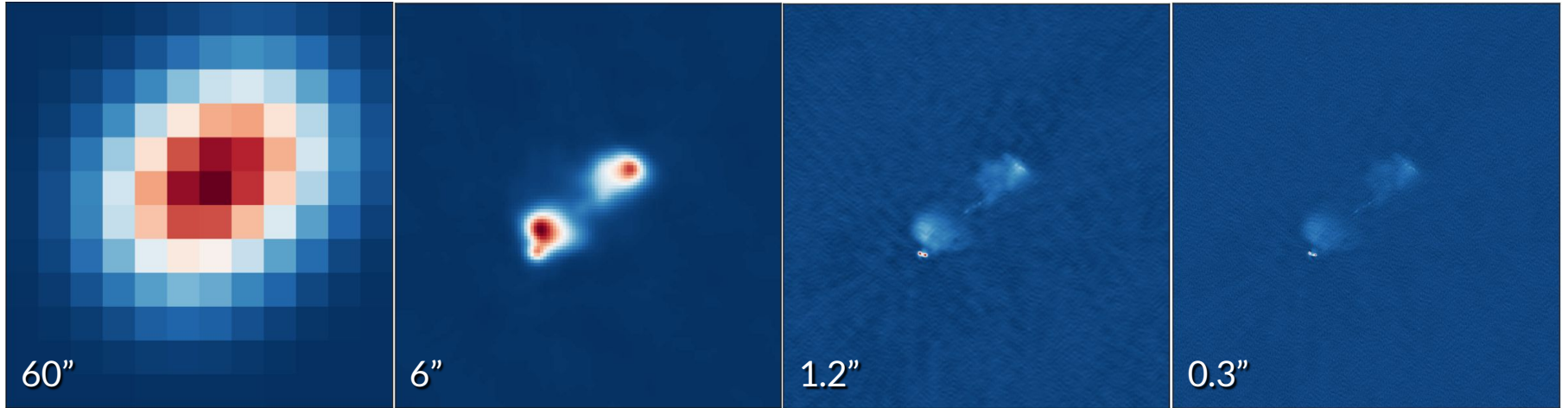


Only a perfect point source has as much flux on a long baseline as on a short baseline



# VLBI: Decreasing S/N at high resolutions

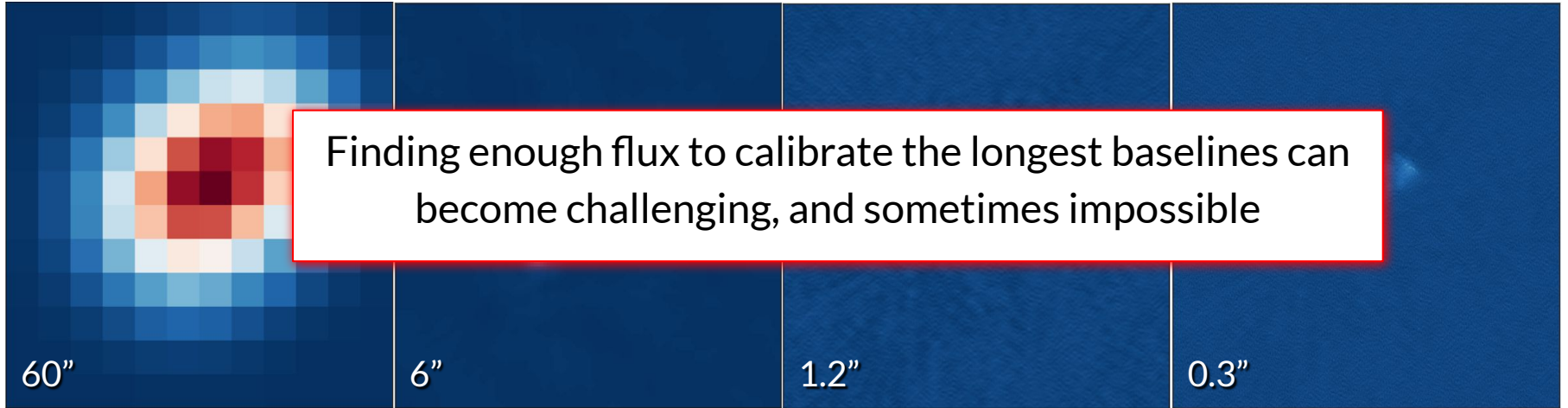
But wait... it's actually even worse!



Higher resolution → Smaller synthesized beam (i.e. resolution or pixels)  
→ The same total intensity is distributed over more resolution elements  
→ The intensity per resolution element is reduced

# VLBI: Decreasing S/N at high resolutions

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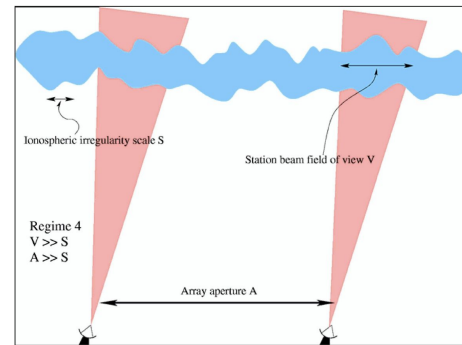
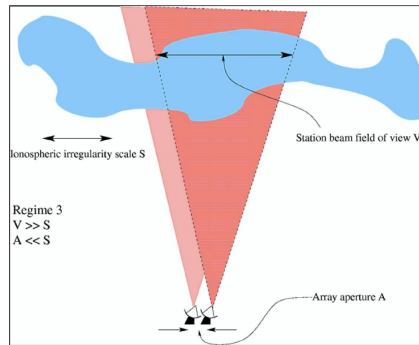
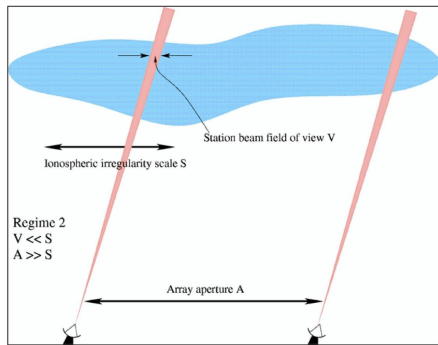
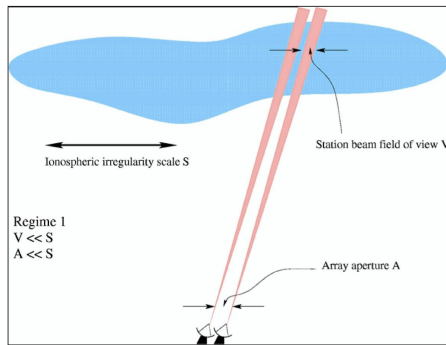


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# VLBI: Strongly varying atmospheric conditions

The four regimes:

(Credit: Wijnholds et al., 2010)

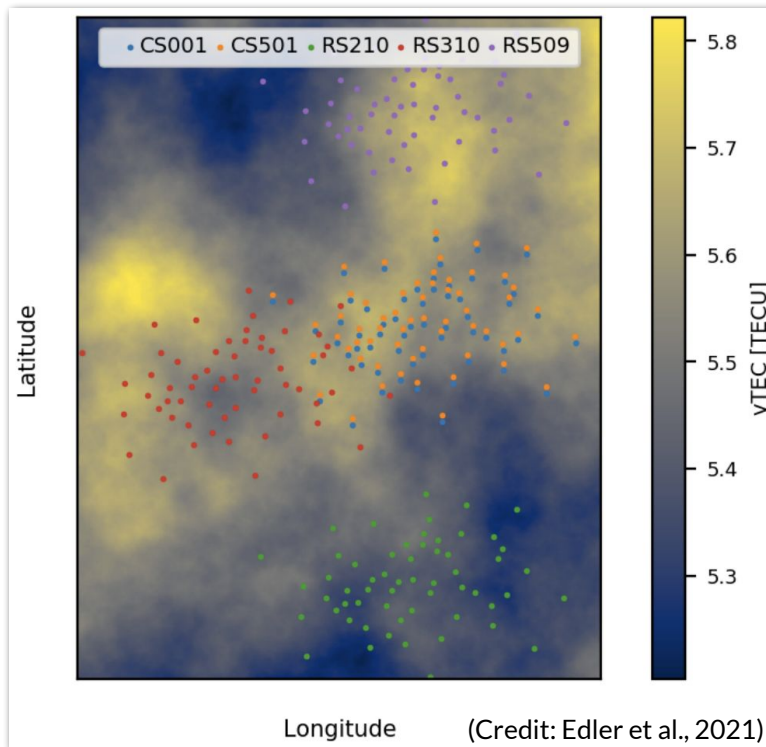


LOFAR core

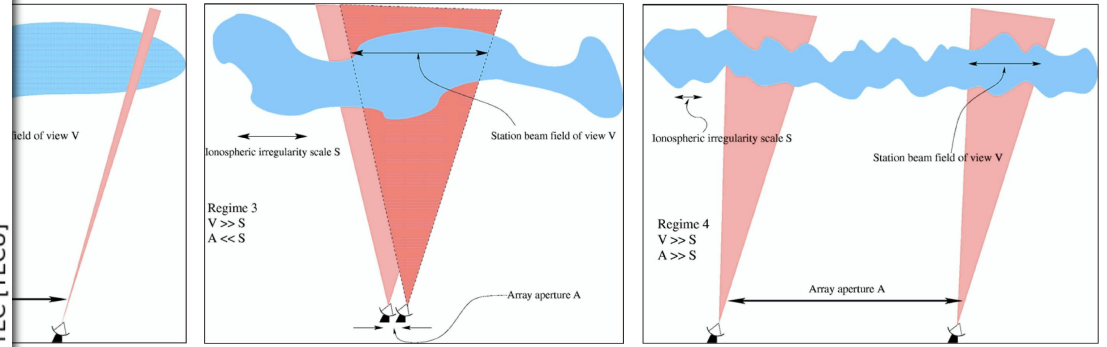
Long-baseline LOFAR

↑  
Also the most difficult one...

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LOFAR core

Long-baseline LOFAR

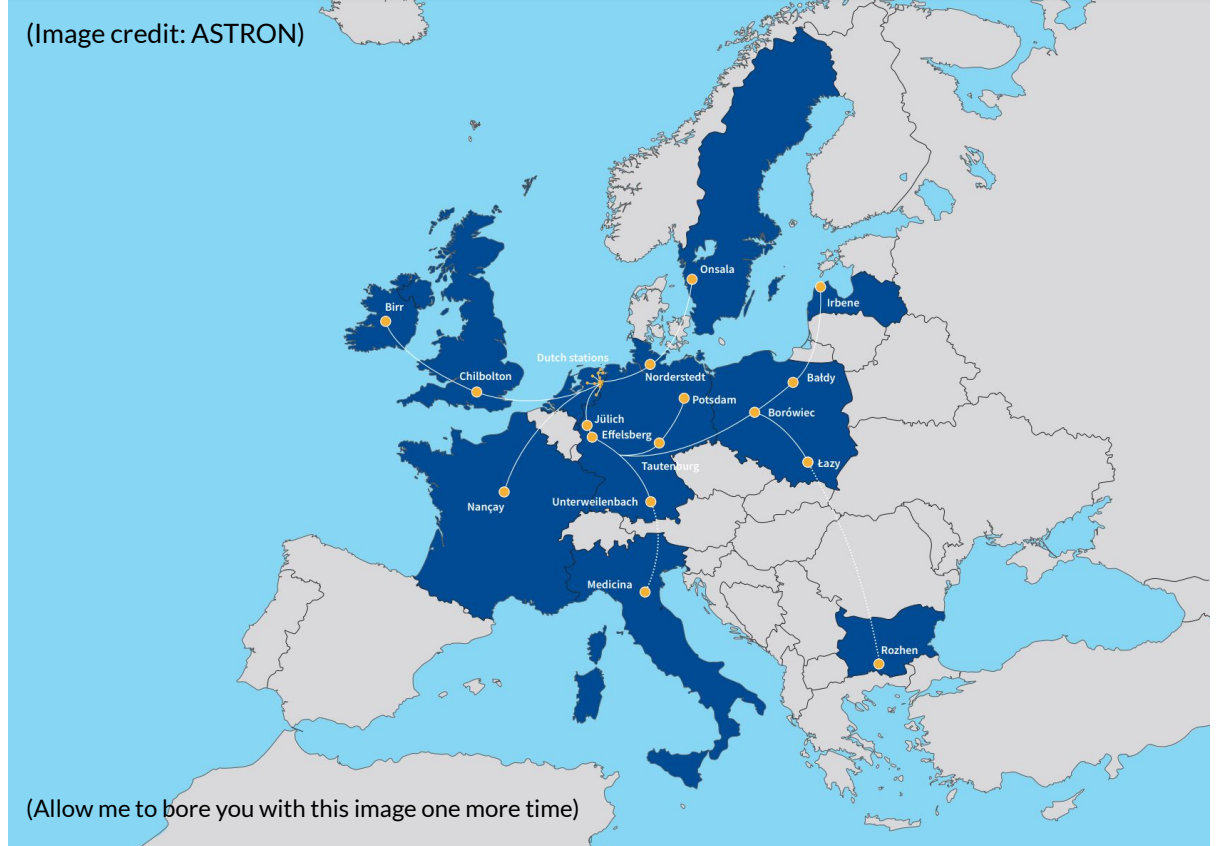
The ionosphere as seen by LOFAR strongly varies across the Field of View

Also the most difficult one...

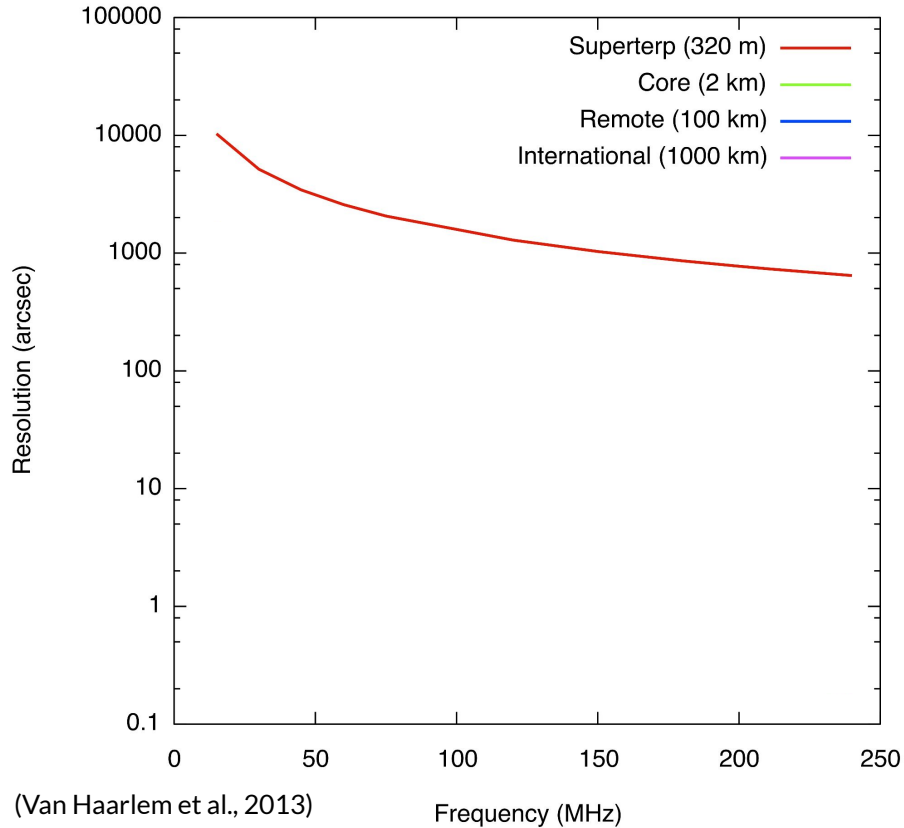


# The International LOFAR Telescope

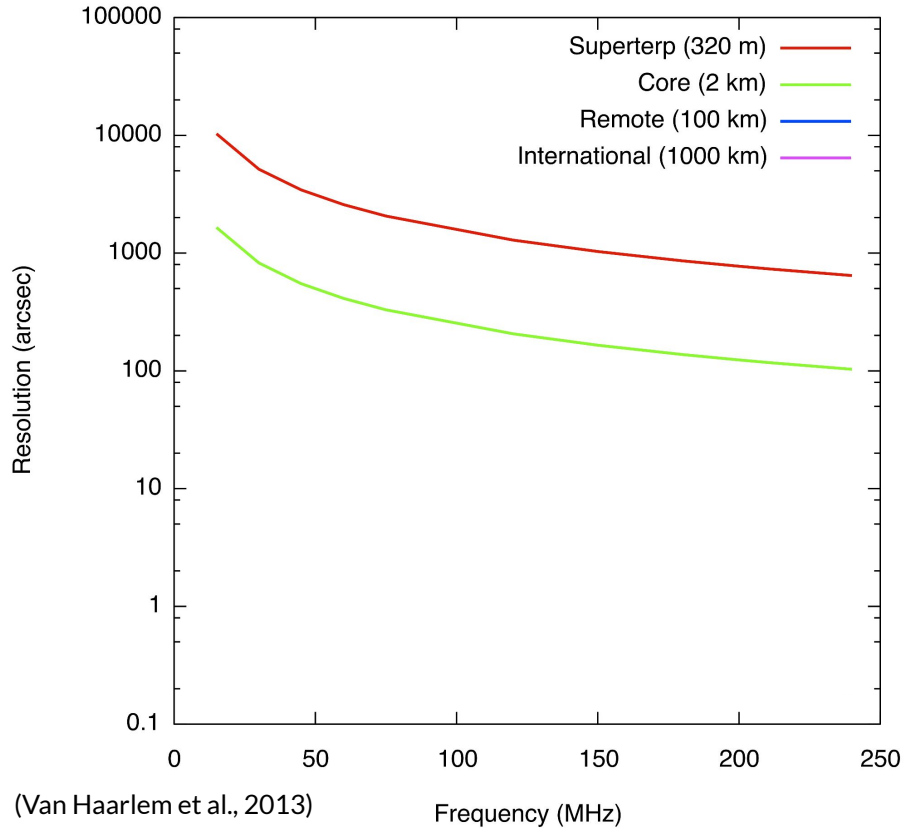
- Low-frequency phased array
  - LBA: 10-90 MHz
  - HBA: 110-240 MHz
- Baselines from 68 m to ~1890 km  
(soon even more!)
- Multi-beam observing capabilities
- Wide field of view
- LOFAR 2.0 upgrade incoming!



# The International LOFAR Telescope

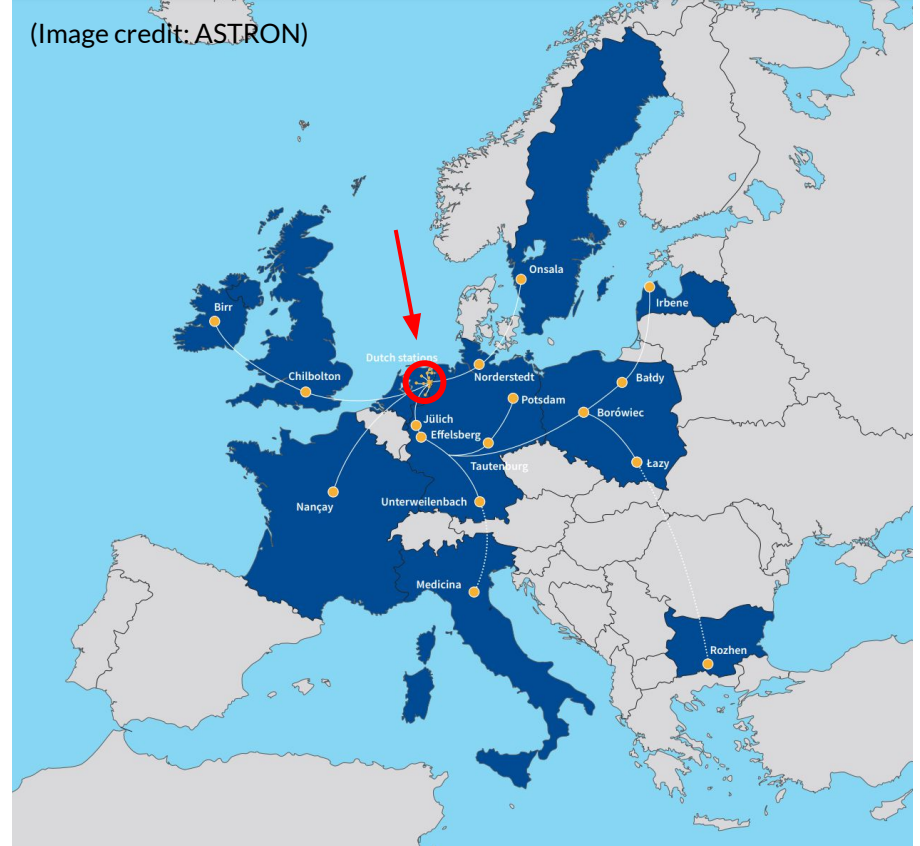
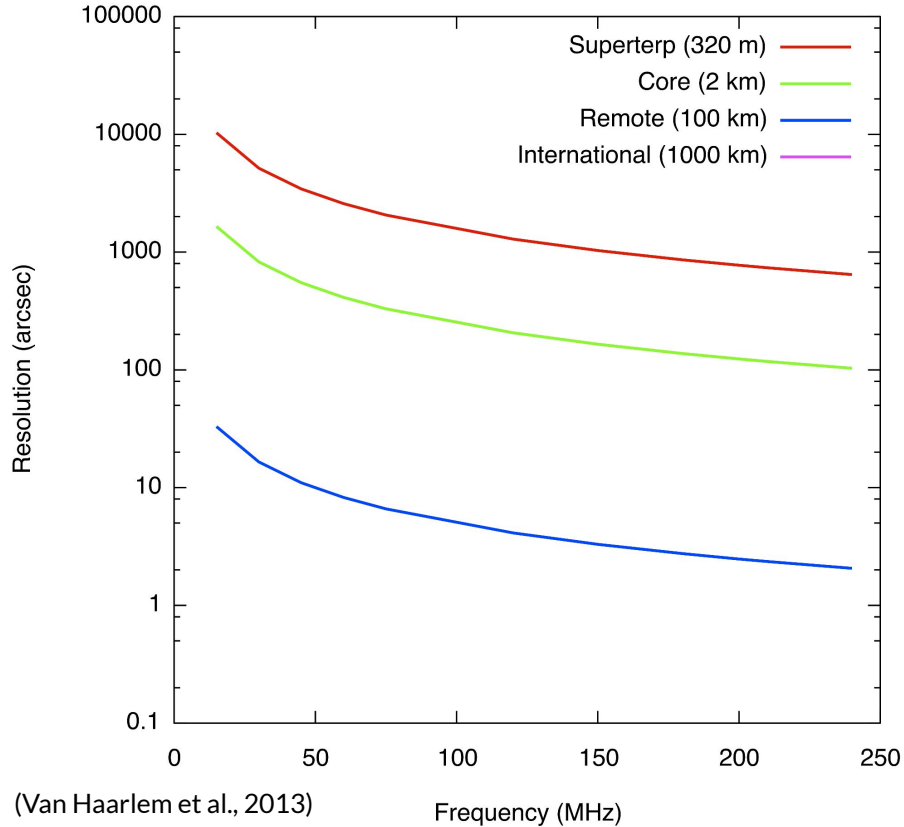


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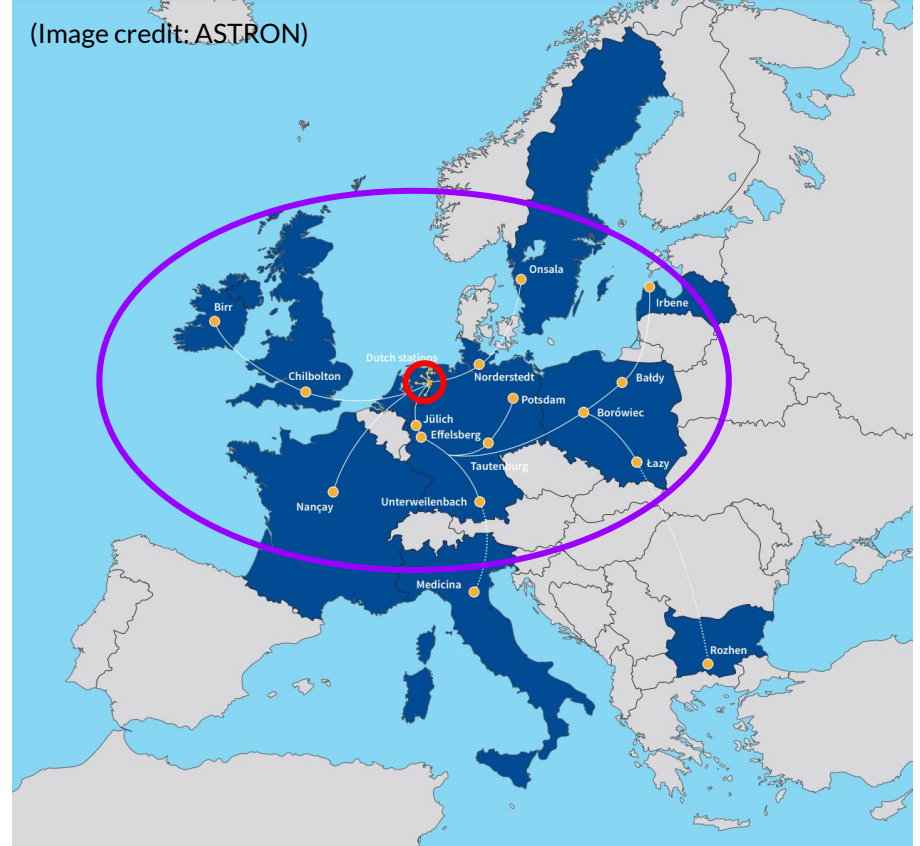
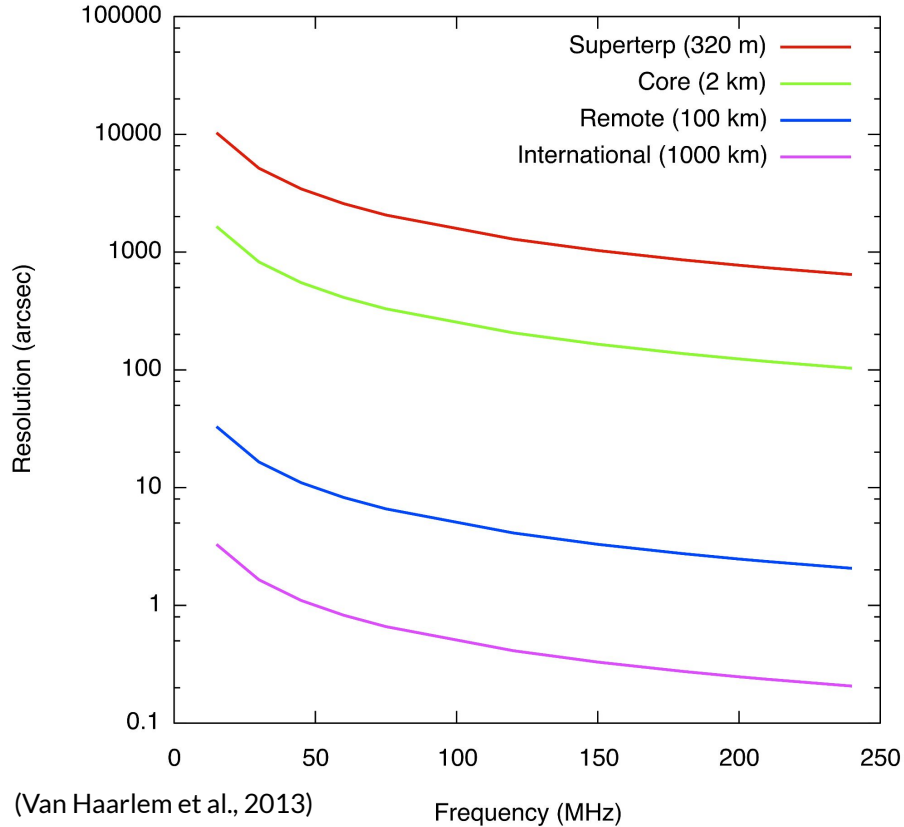


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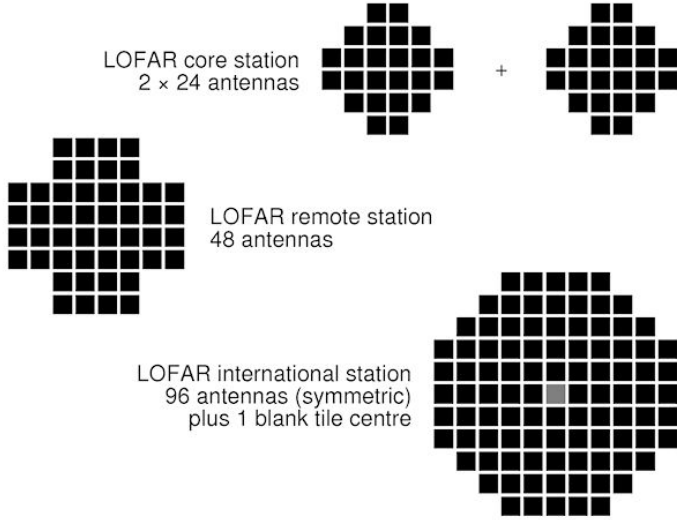




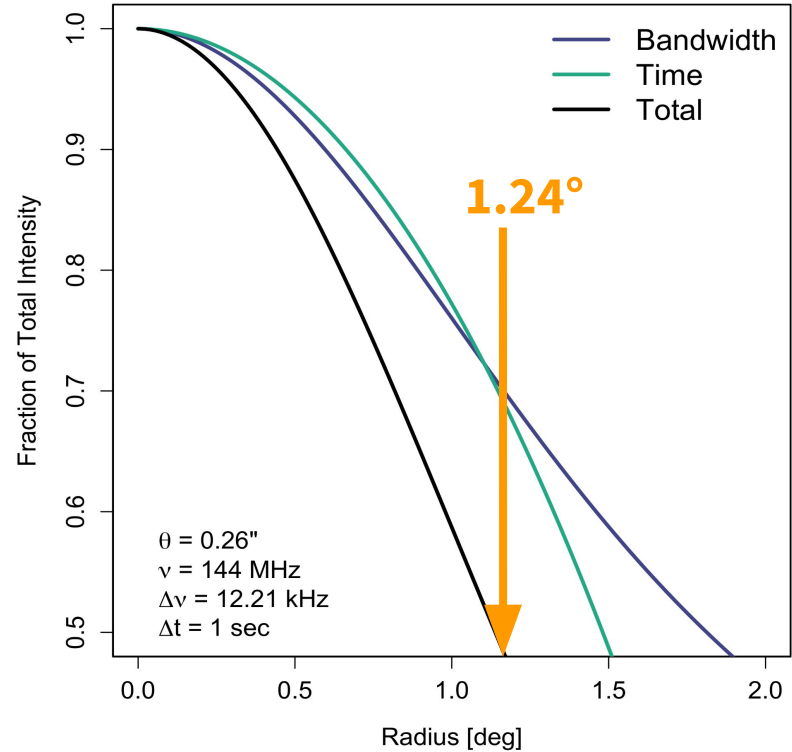
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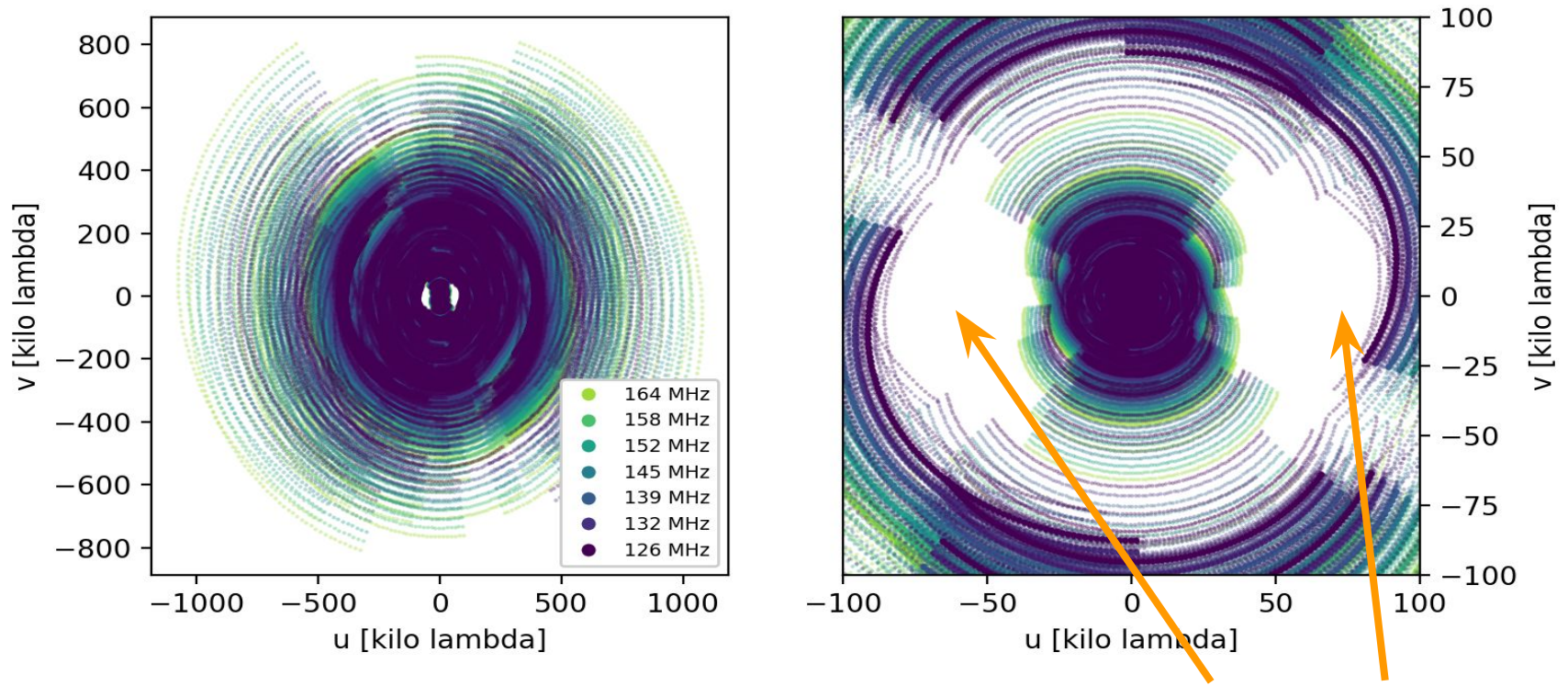
# The International LOFAR Telescope



The Field of View (FoV) of the international stations is narrower than that of the Dutch stations!



# The International LOFAR Telescope



(It's actually in North Holland and Germany...)

The “Belgian gap”

# Low radio frequencies

Standard (high freq.) VLBI uses **fringe fitting**

$$\Delta\phi_{\nu,f} = \phi_0 + \left( \frac{\delta\phi}{\delta\nu} \Delta\nu + \frac{\delta\phi}{\delta t} \Delta t \right)$$

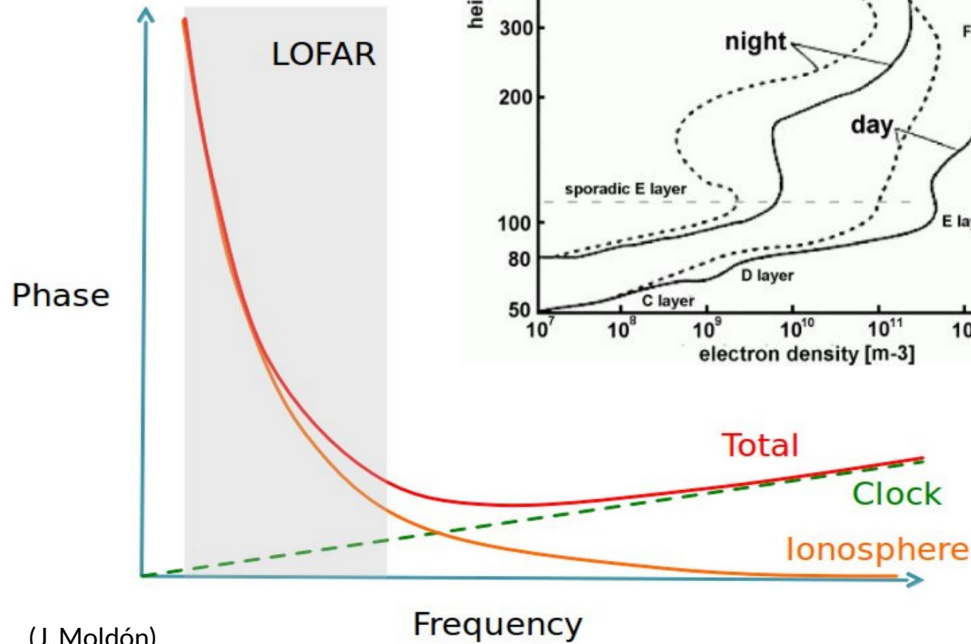
$\phi_0 \equiv$  the **phase** error at  $t_0, \nu_0$

$\frac{\delta\phi}{\delta\nu} \equiv$  **delay** or delay residual  **Dispersive** (e.g. ionosphere)  
**Non-dispersive** (e.g. clock errors)

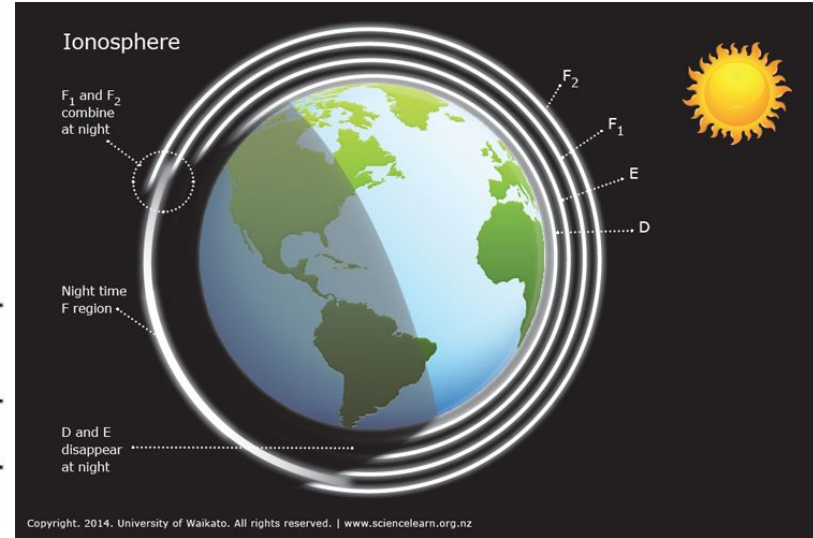
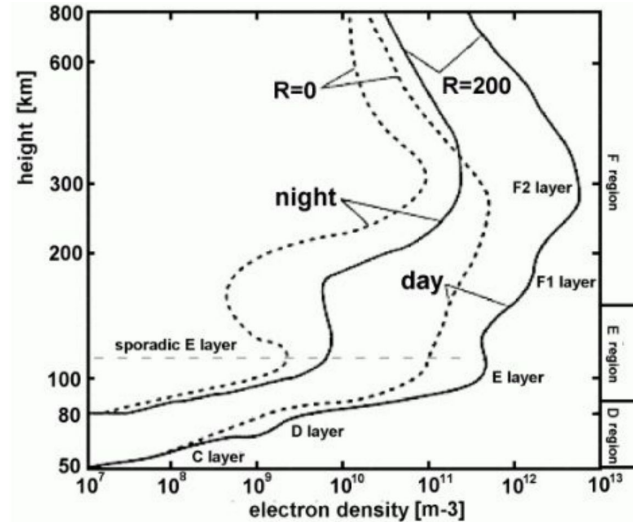
$\frac{\delta\phi}{\delta t} \equiv$  **rate**, delay rate, or delay residual



# Low radio frequencies

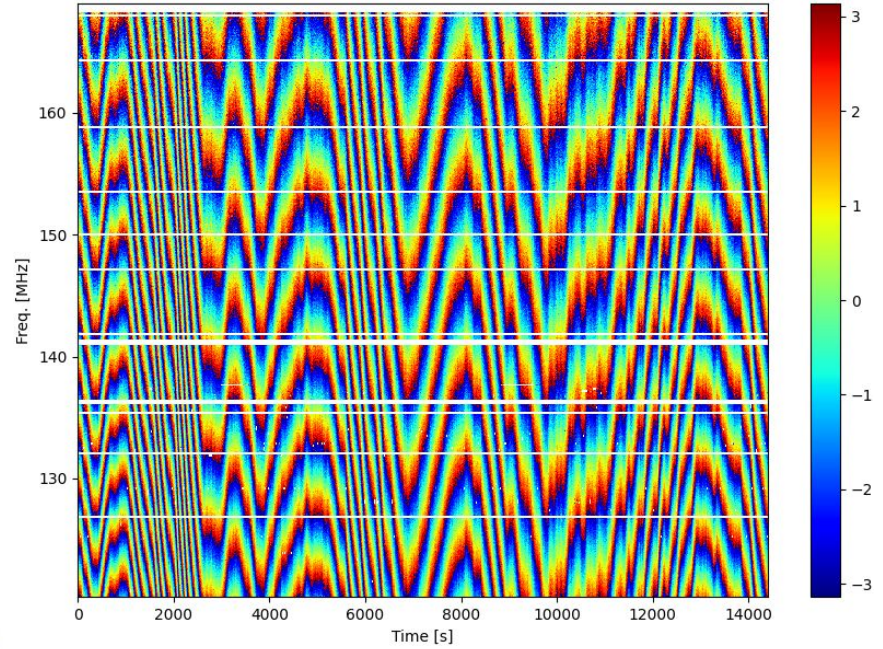
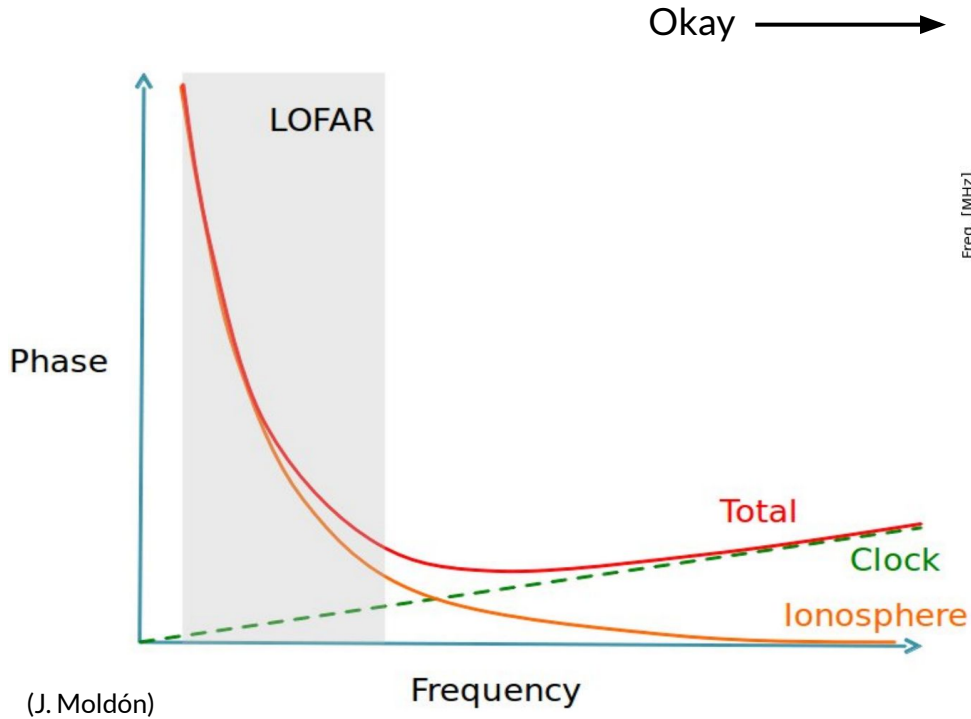


(J. Moldón)

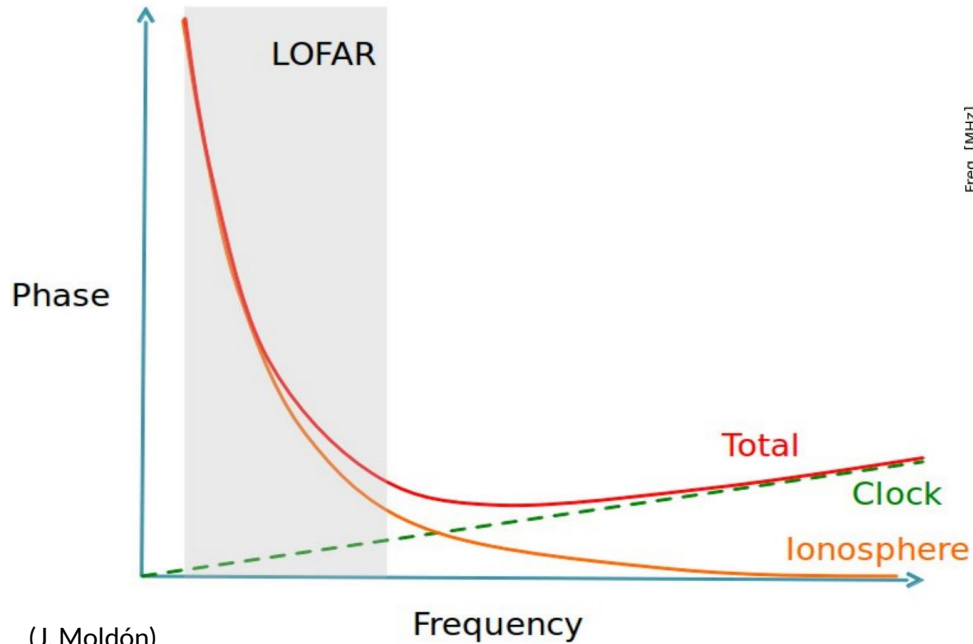


LOFAR is dominated by **dispersive delays** caused by the ionosphere, which scale as  $\phi \propto \nu^{-1}$

# Low radio frequencies

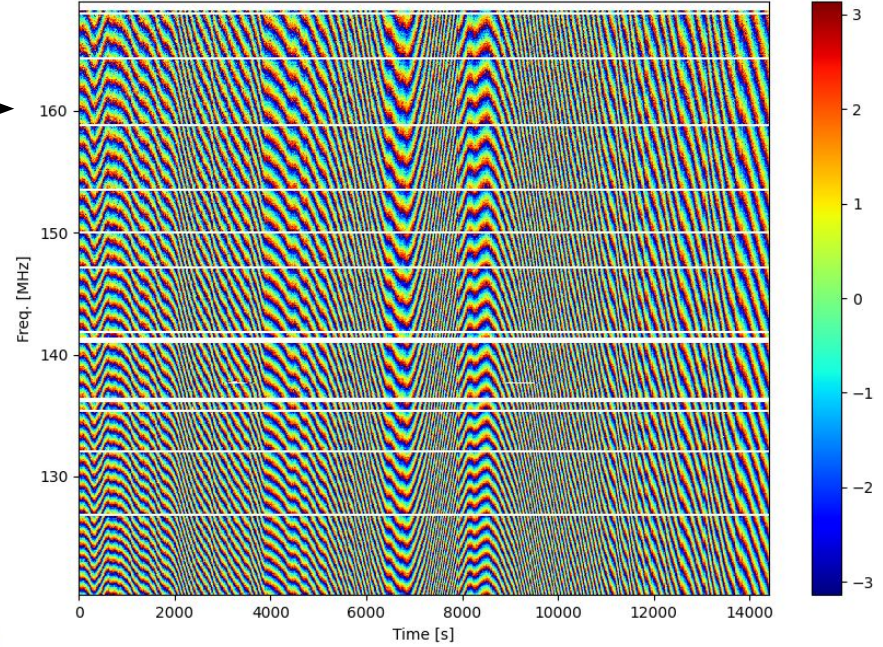


# Low radio frequencies



(J. Moldón)

Bad →





# The solar cycle

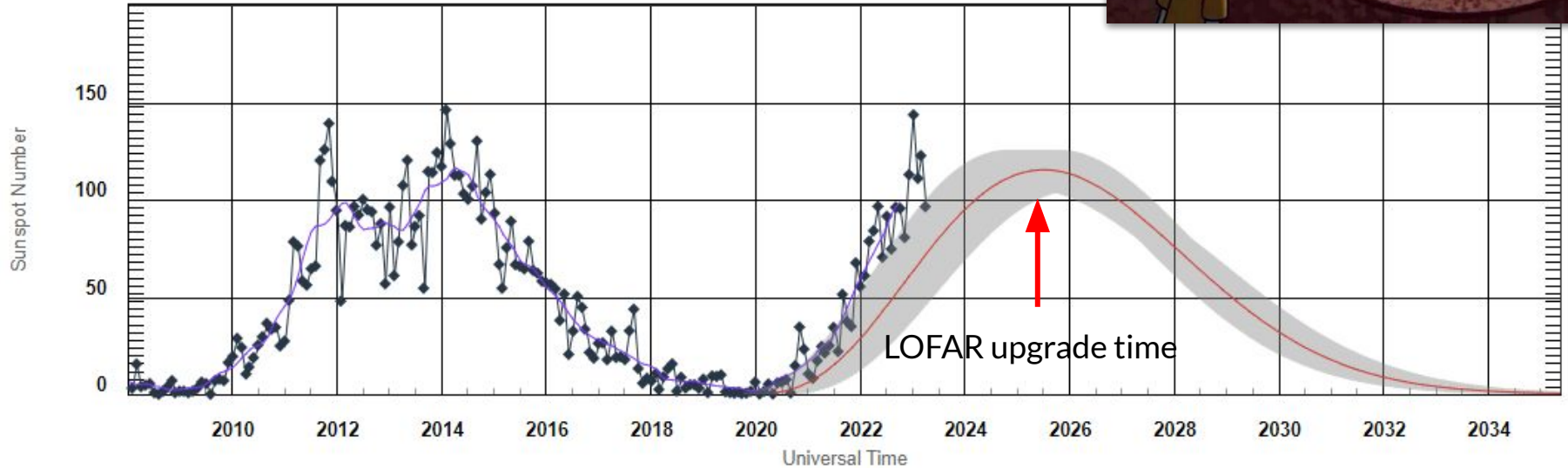
More active Sun

→ more active ionosphere

→ higher calibration difficulty

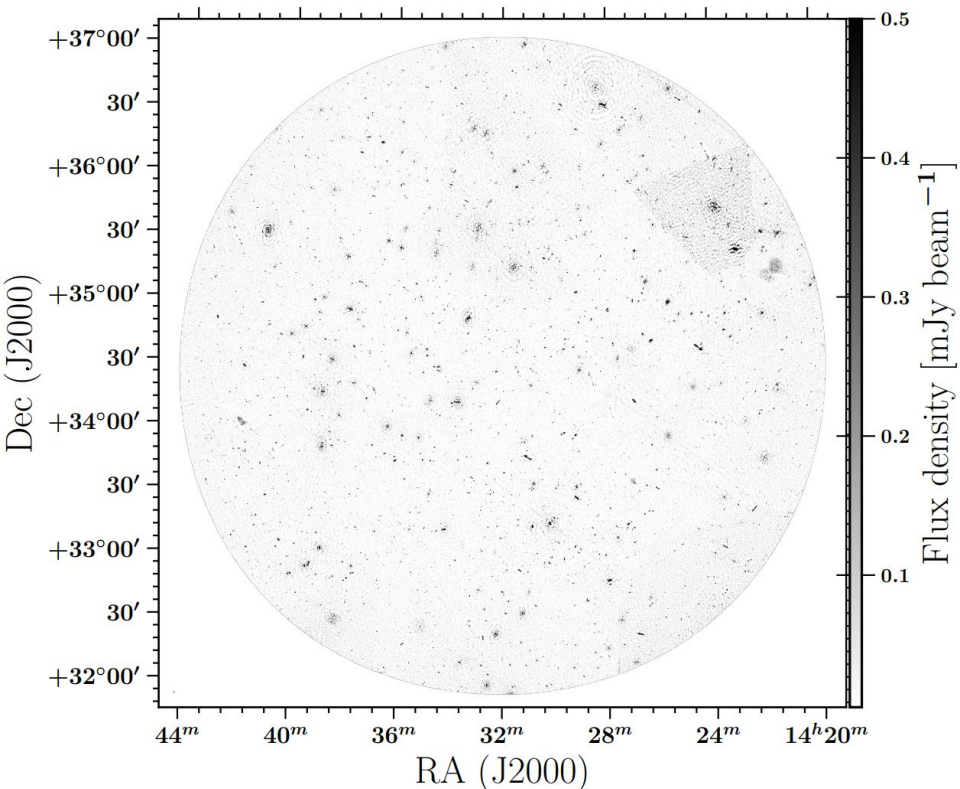


ISES Solar Cycle Sunspot Number Progression





# Low radio frequencies



(Retana-Montenegro et al., 2018)

## Large Field of Views

→ Strong interference from nearby sources

(even up to ~30 degrees away!)

To make it worse: the heterogeneous array has different FoVs!

Dutch array: ~2.5 degree radius  
Int'l array: ~1.2 degree radius

# The Long Baseline Calibrator Survey

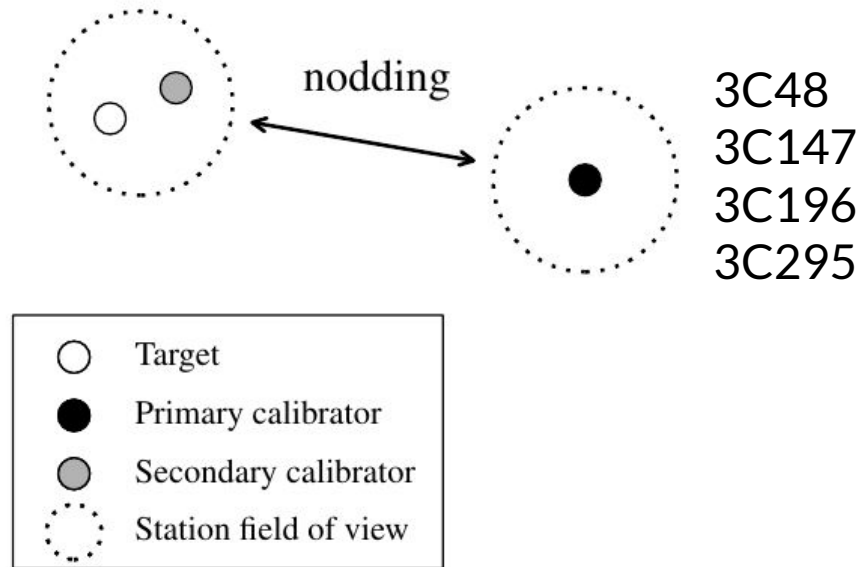
LOFAR can observe both its science target and a calibrator at the same time

LBCS source selection:

- Compact in WENSS (above 30° N)
- Compact in NVSS (below 30° N)
- Also detected by VLSSr, MSSS or TGSS
- The VLBA calibrators

A good in-field calibrator is both **bright** at low radio frequencies ( $\geq 0.2$  Jy) and **compact** at angular scales of 0.3 arcseconds.

LBCS source (in-field or delay calibrator)



# The Long Baseline Calibrator Survey

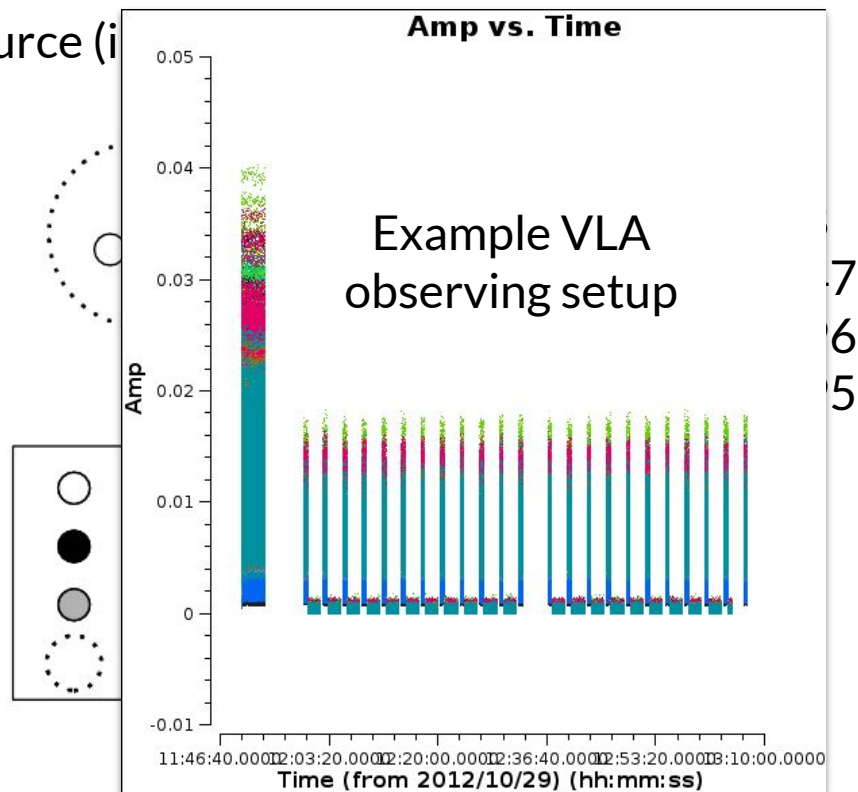
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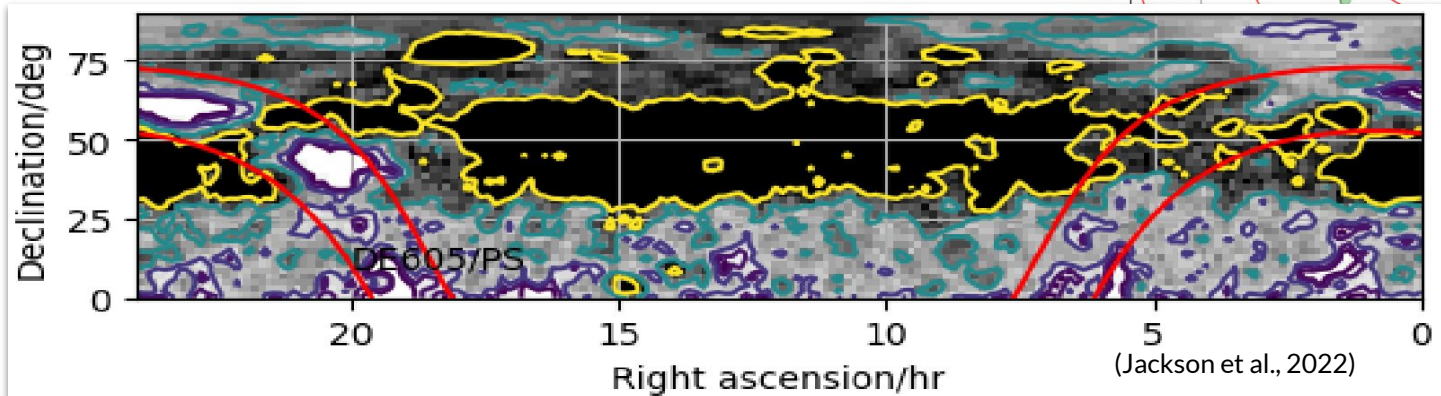
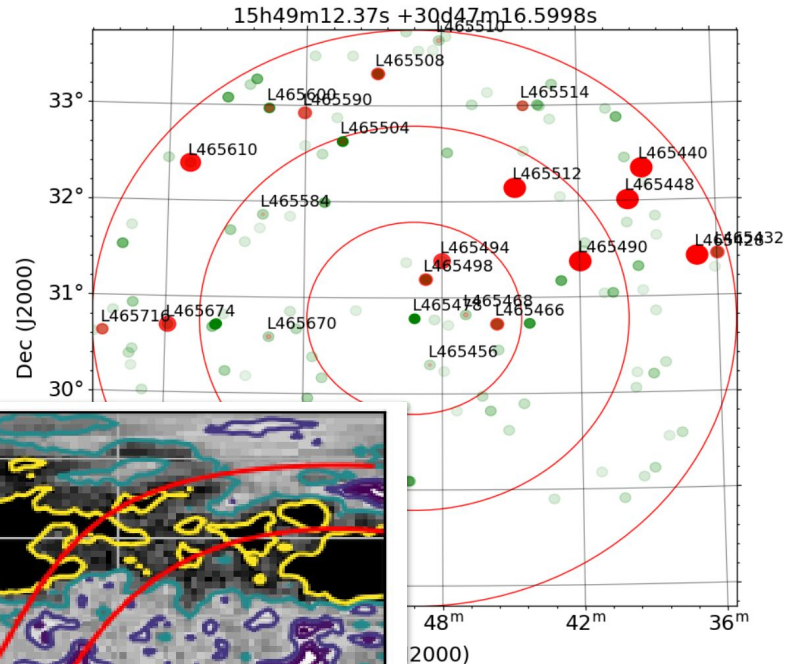
LBCS source (i



# The Long Baseline Calibrator Survey

Typically, you will find ~1 in-field calibrator per square degree

Though sometimes you can be unlucky...  
(especially towards low Dec. and the Galactic Plane)





# Intermezzo: some practicalities...



lofar-surveys.org/lbcs.html

## Long-baseline calibrator survey

The Long-Baseline Calibrator Survey (LBCS) is aimed at identifying suitable sources for calibrating the highest-resolution observations made with the significant correlated flux density at frequencies around 110–190 MHz on scales of a few hundred milliarcseconds. For a description of the survey see [\(2022\)](#).

Data products from the survey are available on this site. You may [download the full catalogue](#), search the catalogue in a particular region of

### HTML table

Enter a position and radius in decimal degrees to search the catalogue:

RA:  DEC:  Radius:

### FITS table

Enter a position and radius in decimal degrees to search the catalogue:

RA:  DEC:  Radius:

Fill in the coordinates of your observation phase center

NOT your target  
(unless they're the same)

# Intermezzo: some practicalities...

## LBCS position search

Results for co-ordinates 140.0, 45.0

See below the table for column descriptions

Search:

Observation	RA	Dec	Date	Time	Goodness	Flags	FT_goodness	Quality	Separation	Downloads
L334374	09:20:10.10	45:19:43.8	2015-03-18	20:32:53	PPP-PPPPP----	A	999-99599----	53	0.33017	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L393295	09:20:58.42	44:41:54.4	2015-07-30	12:02:05	PPPPPPPPPP----	A	999999998----	28	0.34745	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L393359	09:22:43.41	44:52:11.0	2015-07-30	12:20:10	PSPSPSPSX----	O	644493421----	46	0.49930	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L393195	09:21:35.96	44:13:59.1	2015-07-30	11:52:00	XXXXXXXXXX----	A	100040001----	33	0.81802	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L334364	09:15:53.93	45:24:06.0	2015-03-18	20:32:53	XXX-XXXXX----	O	209-40004----	53	0.82659	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L394043	09:24:45.01	45:11:59.2	2015-07-30	11:03:44	XXXXXXXXXX----	O	210120110----	26	0.86172	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L334380	09:16:27.32	45:36:26.5	2015-03-18	20:32:53	PPP-PPPPP----	A	999-99689----	53	0.87026	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L334398	09:21:35.33	45:54:14.9	2015-03-18	20:32:53	PSP-PXXXP----	O	936-91229----	53	0.94610	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L393377	09:25:34.77	44:41:32.5	2015-07-30	12:20:10	PPPPSPSXX----	O	656694431----	46	1.03570	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L393301	09:15:28.96	44:16:38.3	2015-07-30	12:02:05	XXXXXXXXXX----	O	100100000----	28	1.08073	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>
L334390	09:16:06.01	45:52:16.3	2015-03-18	20:32:53	SXX-PXXXS----	O	404-90009----	53	1.10769	<a href="#">P</a> <a href="#">L</a> <a href="#">P</a> <a href="#">R</a> <a href="#">D</a> <a href="#">L</a> <a href="#">E</a>

P: good; S: marginal; X: bad

FT goodness: higher is better

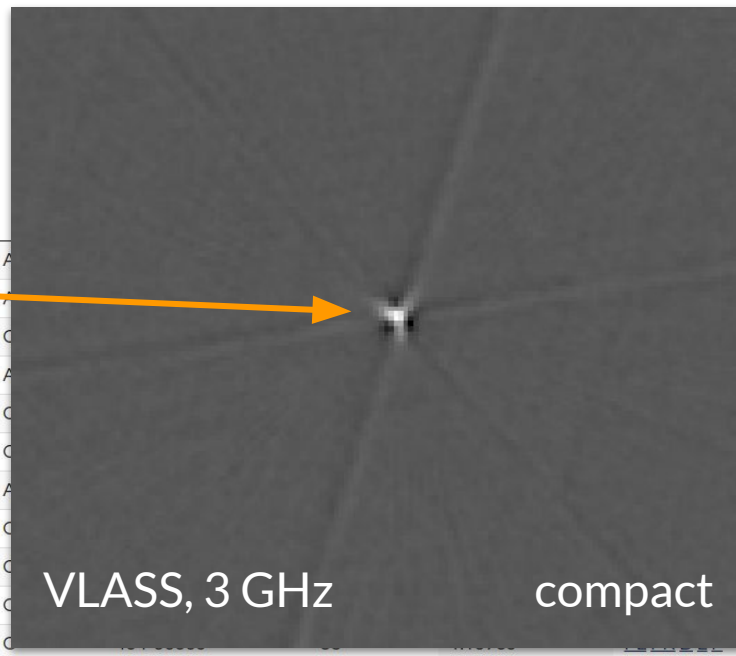
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L334398	09:21:35.33	45:54:14.9	2015-03-18	20:32:53	PSP-PXXXP----
L393377	09:25:34.77	44:41:32.5	2015-07-30	12:20:10	PPPPSPXX-----
L393301	09:15:28.96	44:16:38.3	2015-07-30	12:02:05	XXXXXXXXX----
L334390	09:16:06.01	45:52:16.3	2015-03-18	20:32:53	SXX-PXXXS----



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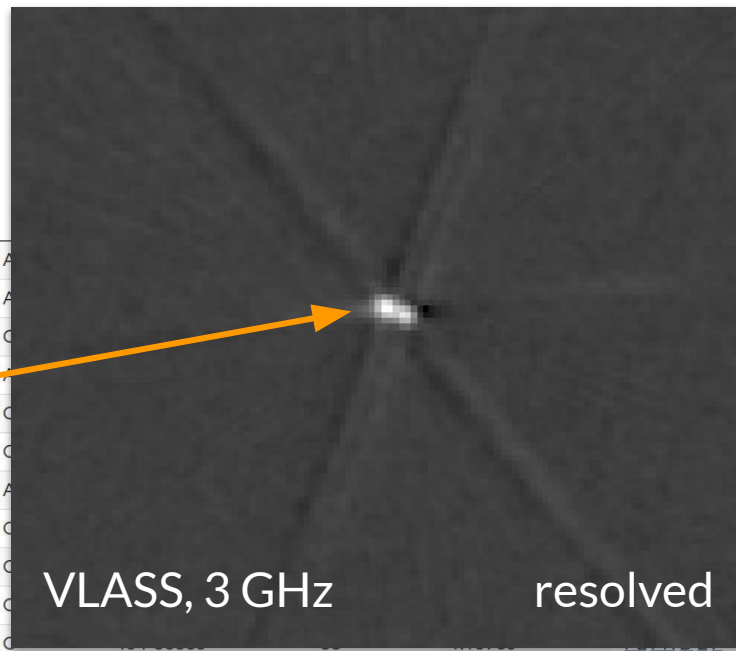
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L393301	09:15:28.96	44:16:38.3	2015-07-30	12:02:05	XXXXXXXXX----
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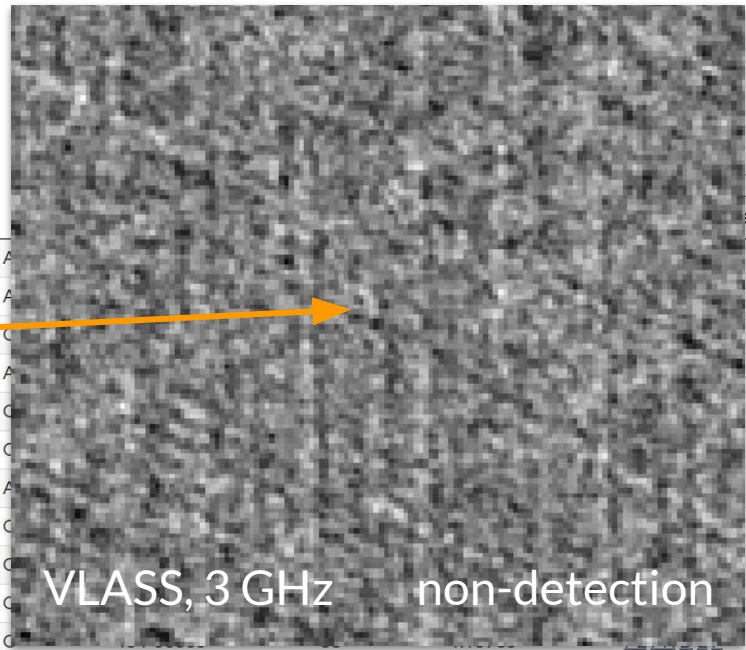
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See below the table for column descriptions

Observation	RA	Dec	Date	Time	Goodness
L334374	09:20:10.10	45:19:43.8	2015-03-18	20:32:53	PPP-PPPPP----
L393295	09:20:58.42	44:41:54.4	2015-07-30	12:02:05	PPPPPPPPP----
L393359	09:22:43.41	44:52:11.0	2015-07-30	12:20:10	DSPSPSPSX----
L393195	09:21:35.96	44:13:59.1	2015-07-30	11:52:00	XXXXXXXXX----
L334364	09:15:53.93	45:24:06.0	2015-03-18	20:32:53	XXX-XXXXX----
L394043	09:24:45.01	45:11:59.2	2015-07-30	11:03:44	XXXXXXXXX----
L334380	09:16:27.32	45:36:26.5	2015-03-18	20:32:53	PPP-PPPPP----
L334398	09:21:35.33	45:54:14.9	2015-03-18	20:32:53	PSP-PXXXP----
L393377	09:25:34.77	44:41:32.5	2015-07-30	12:20:10	PPPPSPSPX----
L393301	09:15:28.96	44:16:38.3	2015-07-30	12:02:05	XXXXXXXXX----
L334390	09:16:06.01	45:52:16.3	2015-03-18	20:32:53	SXX-PXXXS----



P: good; S: marginal; X: bad

FT goodness: higher is better

# The in-field calibrator

Performing the calibration consists of a few ingredients:

- **Reducing the interference** from nearby sources as much as possible
  - Clean fields are preferred
  - Narrow down the FoV
- Providing a **good starting model**
  - Point source
  - VLASS model (in facetselfcal)
  - Custom model
- Configuring the **best calibration steps**
  - Not too much, not too little...

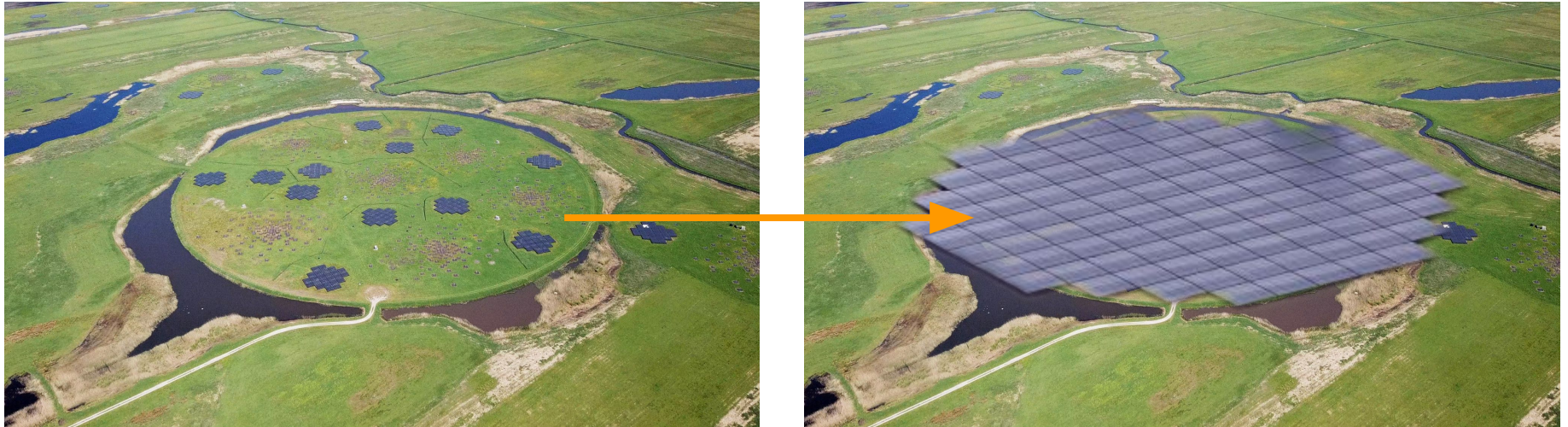


Note that your target could also be the in-field!

# The in-field calibrator

Reducing the interference from nearby sources:

- Coherently phase up the core stations to form a single superstation:

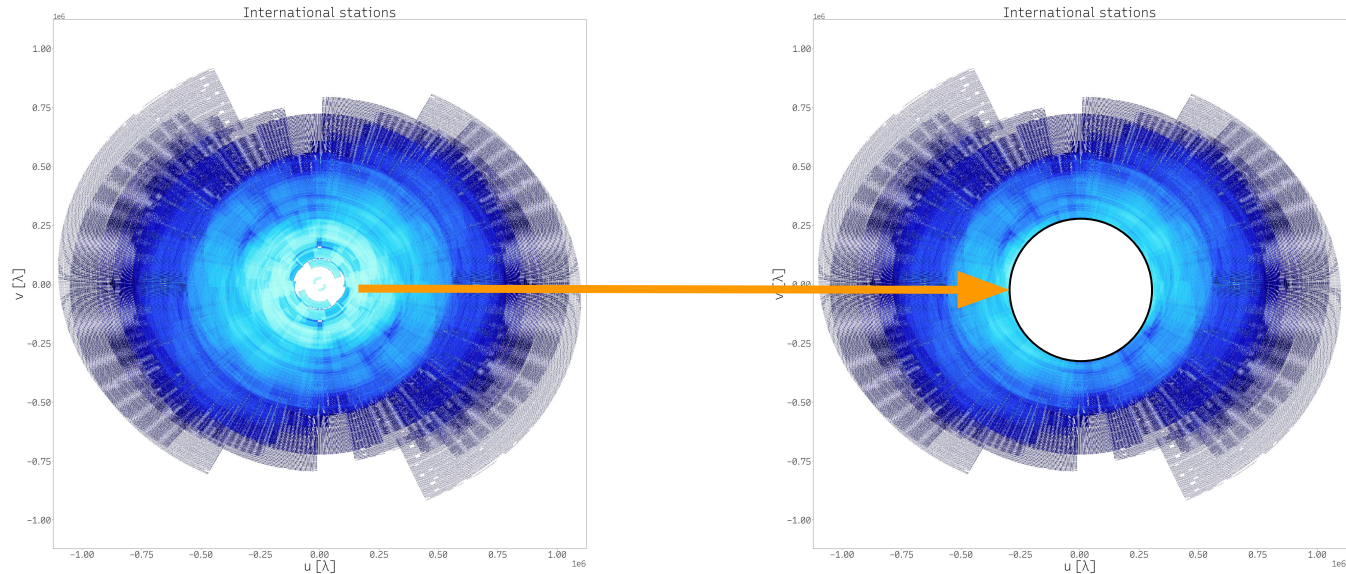


\*actually not just the **superterp** but all of the **core** stations

# The in-field calibrator

Reducing the interference from nearby sources::

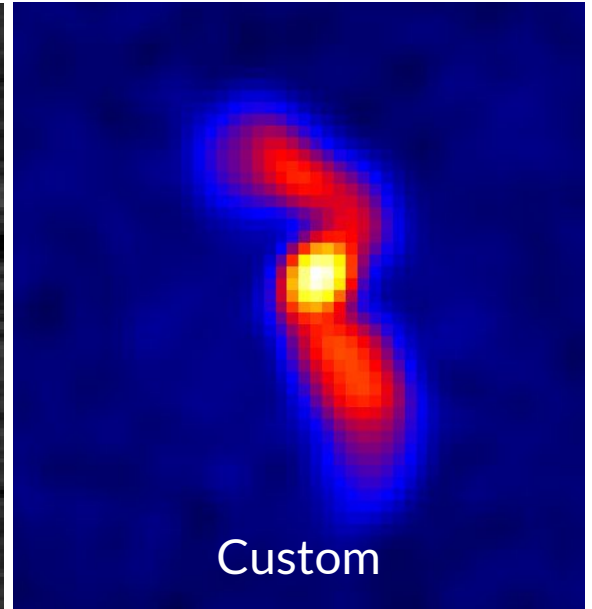
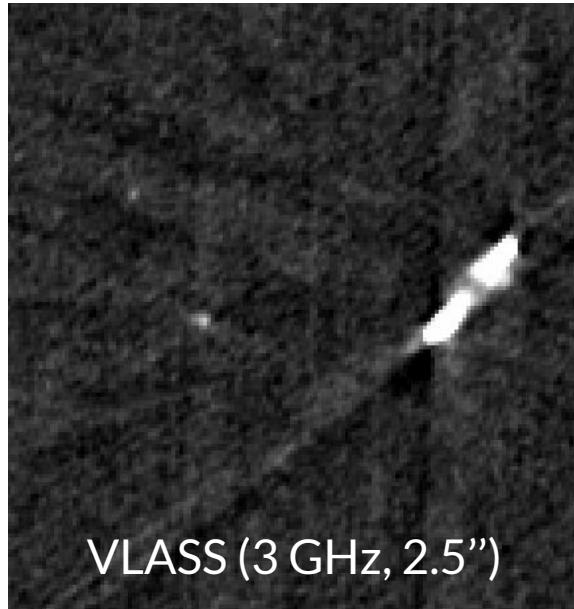
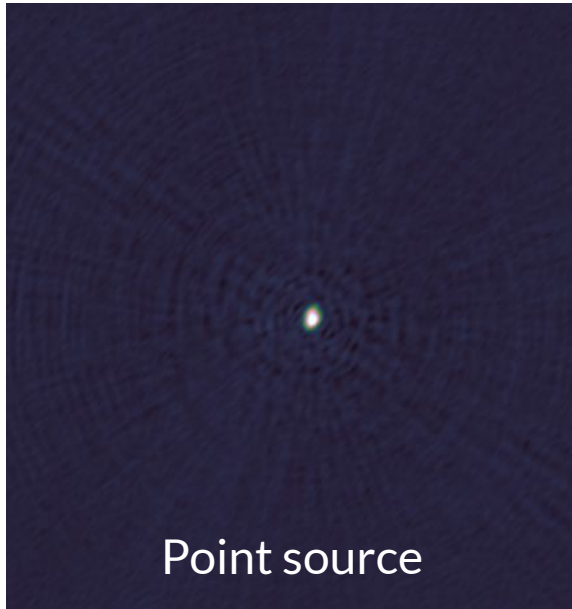
- Coherently phase up the core stations to form a single superstation:
- Performing additional averaging and apply a uv-cut to suppress environment





# The in-field calibrator

Providing a good starting model:



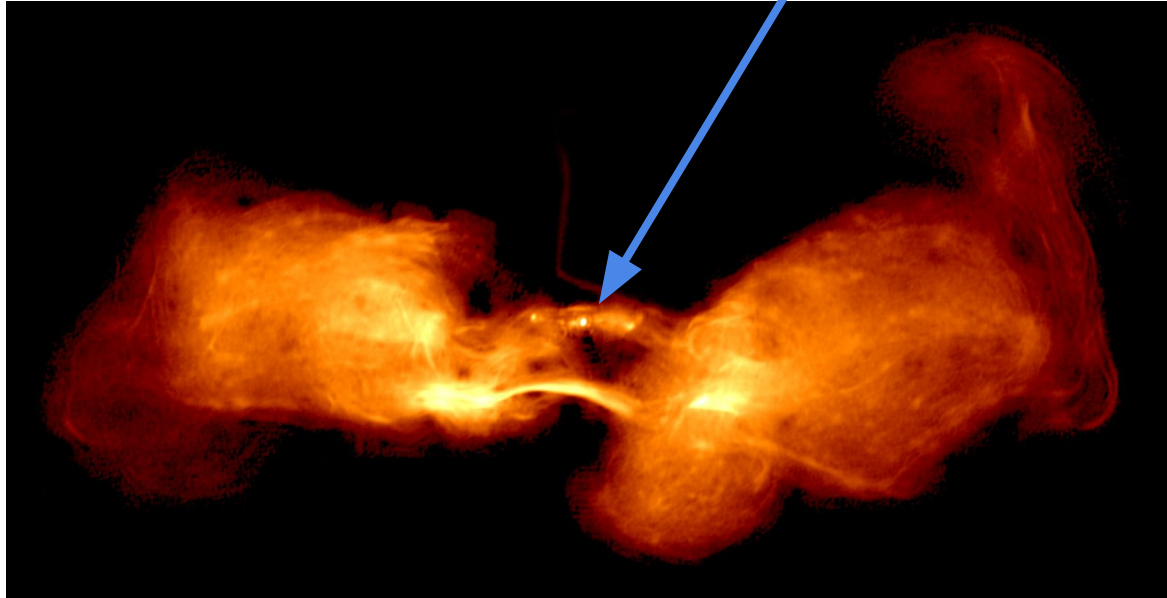
The point source model is often more successful than you might expect

# The in-field calibrator

Providing a good starting model:

There's the AGN = point source

(The AGN is brighter than represented by this color map...)



The point source model is often more successful than you might expect

# The in-field calibrator

Configuring the right calibration steps:

The strategy needs to be motivated by what **physically affects the data!**  
Real but messy > Fake but pretty

## The standard recipe

Nr	Step	Time interval	Freq. interval
1	scalarphasediff	Minutes	>10 MHz
2	scalarphase (Int'l stations)	1 integration	~2 MHz
3	scalarphase (Dutch stations)	1-4 integrations	>10 MHz
4	scalarcomplexgain	~hours	>10 MHz

\*with the complexgain step typically starting only after a few cycles

# Tutorial prep: facetselfcal overview

How to actually run the script:

```
python3 facetselfcal.py --imsize=1024 -i selfcal_run0 --pixelscale=0.075
--robust=-0.5 --skymodelpointsources=1 --uvmin=40000
--soltype-list="['scalarphasediff','scalarphase','scalarphase','scalarcom
plexgain']" --soltypecycles-list="[0,0,0,2]"
--solint-list="['2min','32s','32s','1h']" --nchan-list="[1,1,1,1]"
--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```



# Tutorial prep: facetselfcal overview

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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Image size

# Tutorial prep: facetselfcal overview

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```

Image name

# Tutorial prep: facetselfcal overview

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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Pixel scale (in arcseconds)

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--soltype-list="['scalarphasediff','scalarphase','scalarphase','scalarcomplexgain']" --soltypecycles-list="[0,0,0,2]"
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```



uv weighting scheme



# Tutorial prep: facetselfcal overview

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--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Starting sky model

# Tutorial prep: facetselfcal overview

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--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
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--resetsols-list="[None, 'alldutch', None, None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Minimum baseline length (in  $\lambda$ )

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
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```

Steps per self-cal cycle

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Which cycle each step is enabled



# Tutorial prep: facetselfcal overview

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--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```



Solution interval for each calibration step

# Tutorial prep: facetselfcal overview

How to actually run the script:

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python3 facetselfcal.py --imsize=1024 -i selfcal_run0 --pixelscale=0.075
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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Freq. channel interval for each calibration step

# Tutorial prep: facetselfcal overview

How to actually run the script:

```
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--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```



Frequency smoothing of solutions per step

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--solint-list="['2min','32s','32s','1h']" --nchan-list="[1,1,1,1]"
--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

To convert linear to circular polarization



# Tutorial prep: facetselfcal overview

How to actually run the script:

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--solint-list="['2min','32s','32s','1h']" --nchan-list="[1,1,1,1]"
--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Antenna constraints to apply to each step

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="['None','alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

Which solutions to reset after derivation

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--soltype-list="['scalarphasediff','scalarphase','scalarphase','scalarcom
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--solint-list="['2min','32s','32s','1h']" --nchan-list="[1,1,1,1]"
--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

After how many cycles to stop

# Tutorial prep: facetselfcal overview

How to actually run the script:

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--soltype-list="['scalarphasediff','scalarphase','scalarphase','scalarcom
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--smoothnessconstraint-list="[20.0,1.0,10.0,20.0]" --docircular
--antennaconstraint-list="['alldutch',None,None,None]"
--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```

How much freq. averaging to perform

# Tutorial prep: facetselfcal overview

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--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```




How much time averaging to perform



# Tutorial prep: facetselfcal overview

How to actually run the script:

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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```



To phase-up a set of antennas

# Tutorial prep: facetselfcal overview

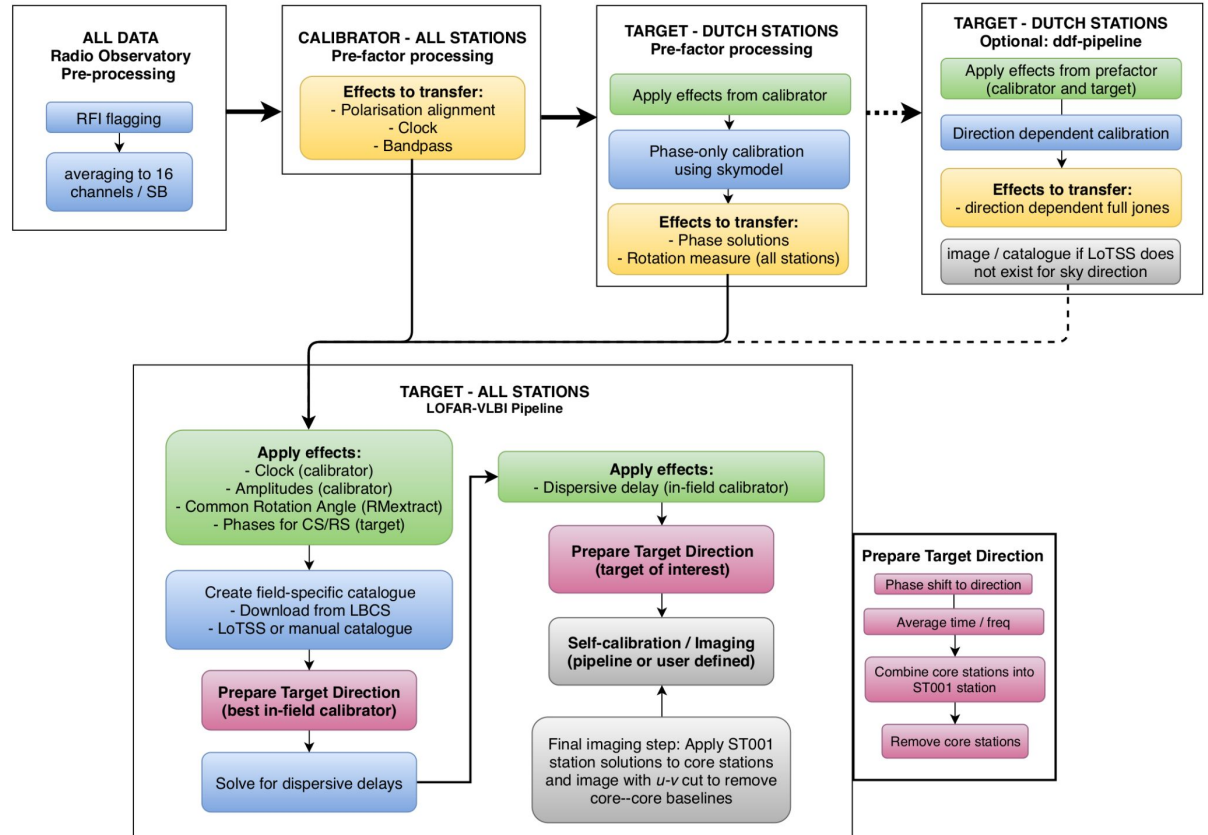
How to actually run the script:

```
python3 facetselfcal.py --imsize=1024 -i selfcal_run0 --pixelscale=0.075
--robust=-0.5 --skymodelpointsources=1 --uvmin=40000
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--resetsols-list="[None,'alldutch',None,None]" --stop=12 --avgfreqstep=4
--avgtimestep=4 --phaseupstations='core' your_dataset.ms
```



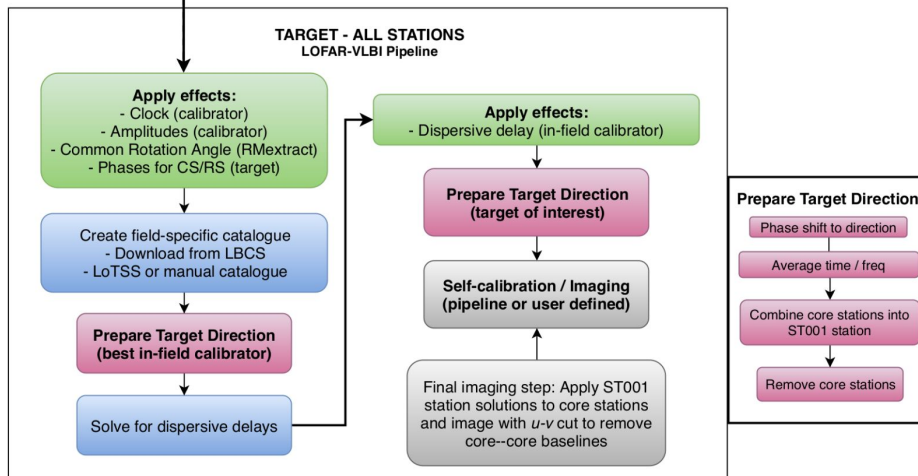
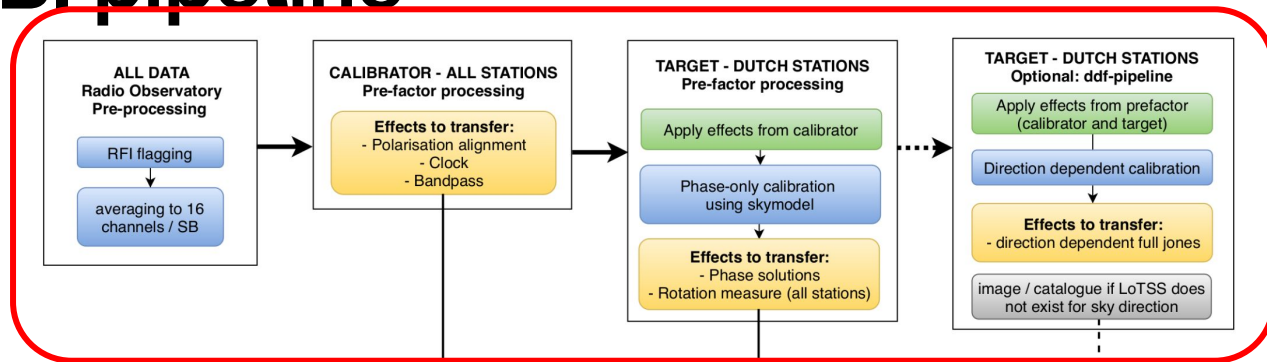
Your Measurement Set

# The LOFAR-VLBI pipeline

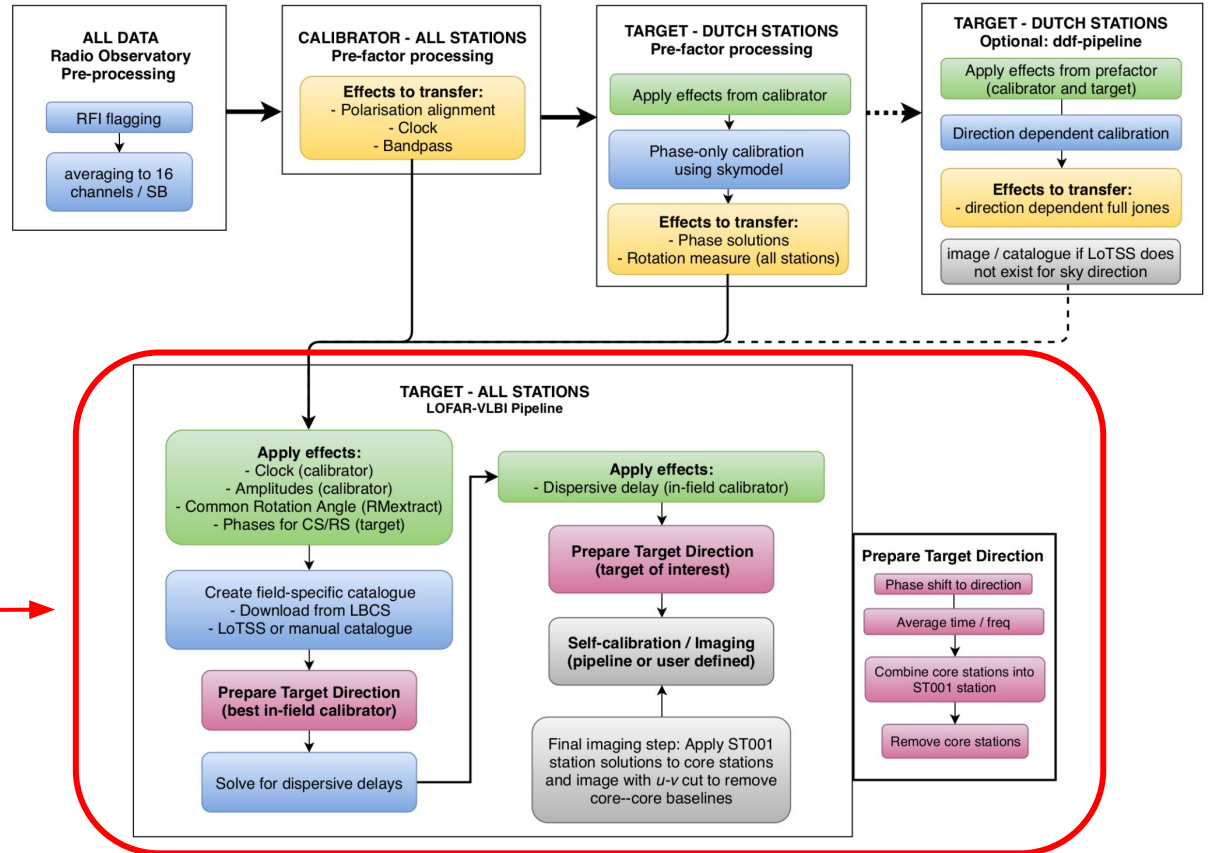


# The LOFAR-VLBI pipeline

Standard Dutch  
array processing



# The LOFAR-VLBI pipeline



LOFAR-VLBI Pipeline →

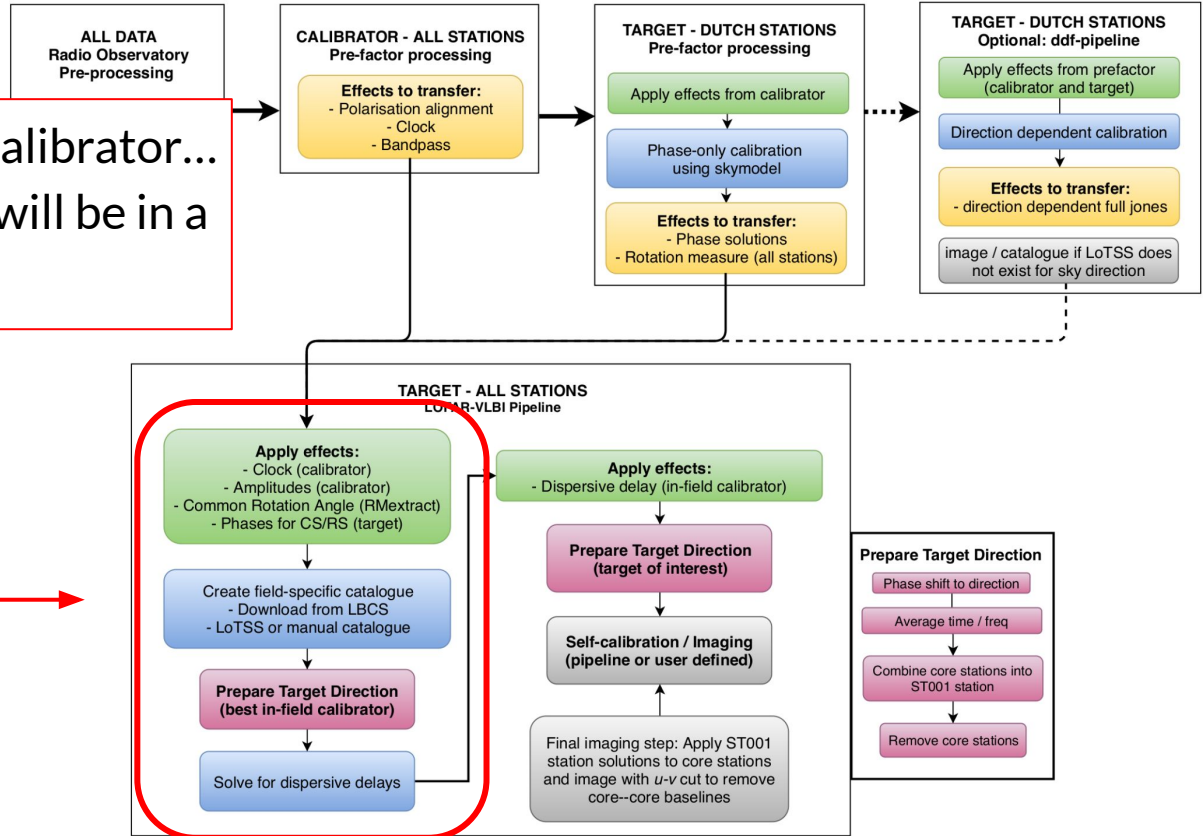
Available on GitHub:  
[github.com/lofar-vlbi](https://github.com/lofar-vlbi)



# The LOFAR-VLBI pipeline

Once you have the in-field calibrator...  
calibrated, most of the FoV will be in a  
good shape

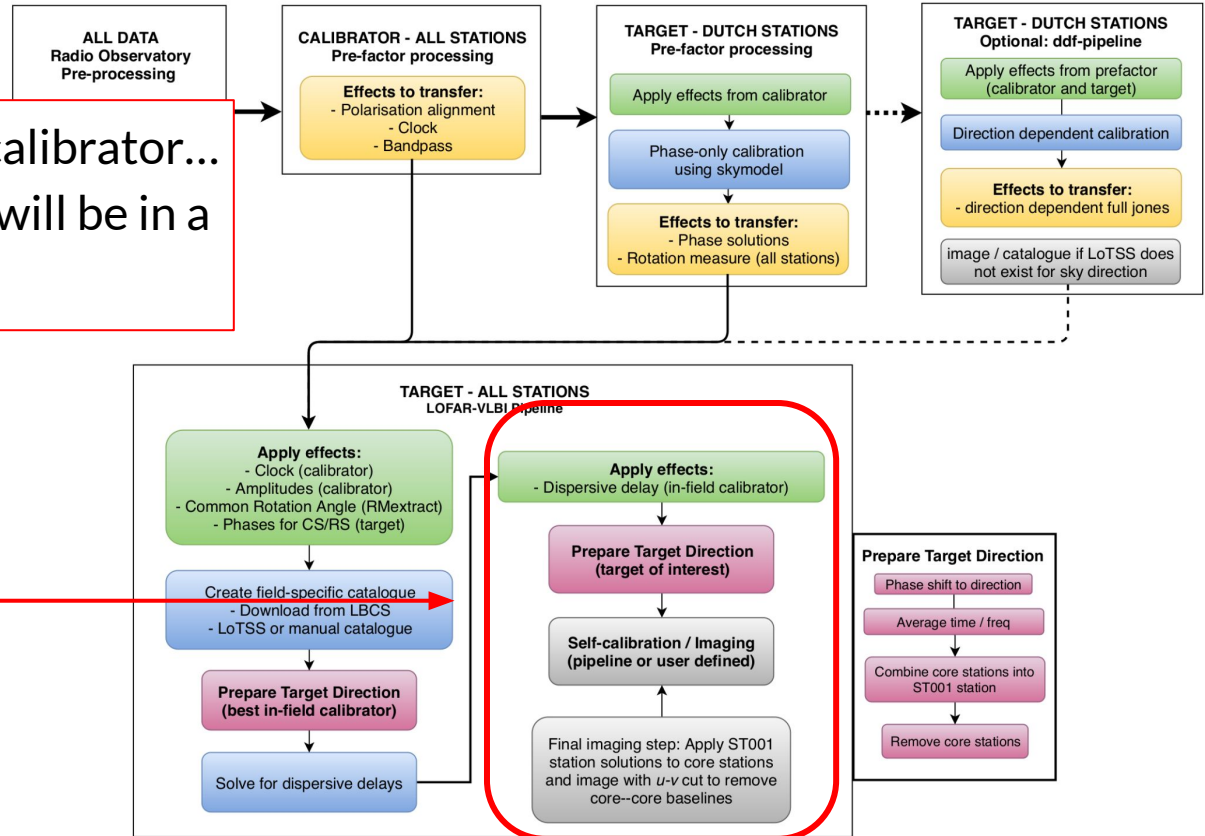
Solve for dispersive delays using  
in-field calibrator source



# The LOFAR-VLBI pipeline

Once you have the in-field calibrator...  
calibrated, most of the FoV will be in a  
good shape

Apply solutions and perform final  
self-calibration on target



# Finally: enjoy your high-resolution images!!

