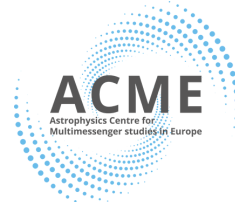


# VLBI observations: From scheduling to data reduction

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# The path towards a good image

VLBI data as provided by the current observatories need to be calibrated.  
Still a semi-manual process in many cases...

- ◉ *A-priori gain calibration*
- ◉ *Flagging*
- ◉ *Phase calibration*
- ◉ Imaging/cleaning
- ◉ Self-calibration & more imaging

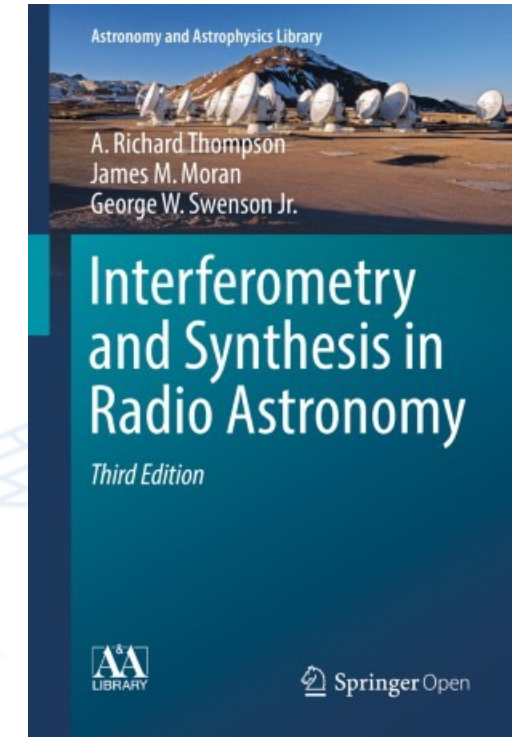




# In this lecture...

This is not a deep lecture on fundamentals of radio interferometers but...

A few slides to get the main concepts you need to be aware of (and how to apply them)!



[Interferometry and Synthesis  
in Radio Astronomy](#)





**JIVE**

Joint Institute for VLBI  
ERIC







Target

Ionosphere

Troposphere

$$CT_{geo} = \vec{b} \cdot \vec{s}$$

$\theta$

$\vec{b}$

$$V_1 = V e^{-i2\pi\omega(t-\tau_1)}$$

$$V_2 = V e^{-i2\pi\omega(t-\tau_2)}$$

$$\langle V_1 V_2^* \rangle$$

$$V_{12} = \frac{V^2}{2} e^{i2\pi\omega\tau_0}$$



# Interferometers



## Visibilities

- ☑ Complex numbers:  $V_{i,j}(u, v)$
- ☑ Baseline vector:  $\mathbf{b}_{i,j} = \lambda(u, v, w) = \mathbf{r}_i - \mathbf{r}_j$
- ☑ Sky intensity:  $I_v(l, m)$

$$V_{i,j}(u, v) = \int I_v(l, m) e^{-2\pi i (ul + vm)} dl \, dm$$



# The interferometer measurement equation



Gain amplitude and phase

Baseline-based errors

Errors due to elevation

Opacity and path length variation

$$V_{i,j}^{\text{obs}} = M_{i,j} B_{i,j} G_{i,j} D_{i,j} E_{i,j} P_{i,j} T_{i,j} V_{i,j}^{\text{true}}$$

Bandpass response

Instrumental polarization

Change in parallactic angle



# The interferometer measurement equation

It's all about phases

$$\tau_{\text{obs}} = \tau_{\text{geom}} + \tau_{\text{src}} + \tau_{\text{trop}} + \tau_{\text{iono}} + \tau_{\text{instr}} + \epsilon_{\text{noise}}$$

Source/Station/Earth orientation  
(correlator)

Source structure

Propagation  
(calibration)

Instrumental effects

# Phase evolution



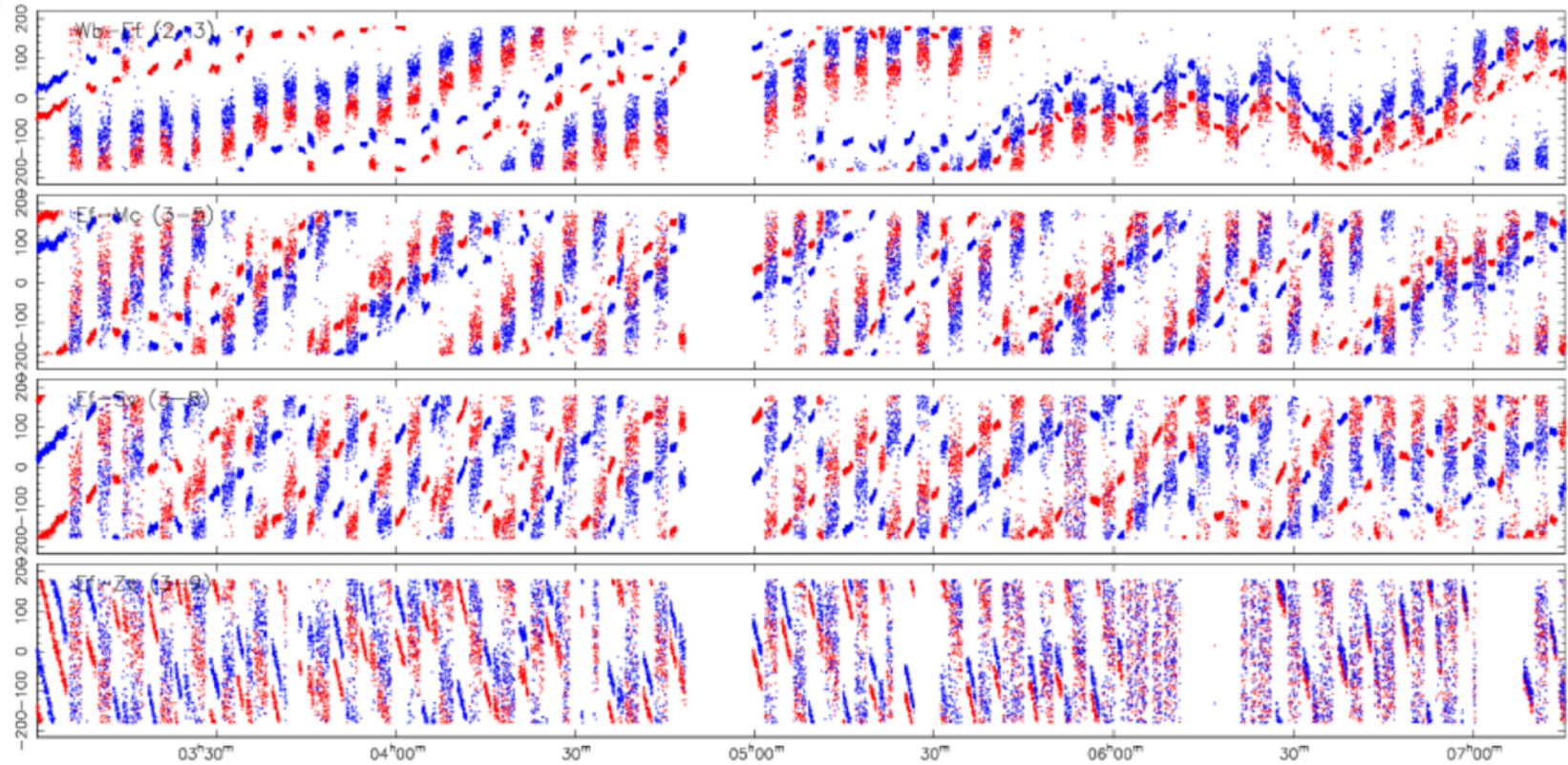
Phases may evolve faster with time for longer baselines.

Phases:  $\varphi$

Delays:  $\frac{\partial \varphi}{\partial \omega}$

Rates:  $\frac{\partial \varphi}{\partial t}$

(fringe-fitting)



Point-like source at the phase center (phases should be zero!)





# The need for additional sources

Bright (high S/N) and compact sources are mandatory for calibration purposes.

**Target:** faint or resolved? —> requires a nearby phase-calibrator source.

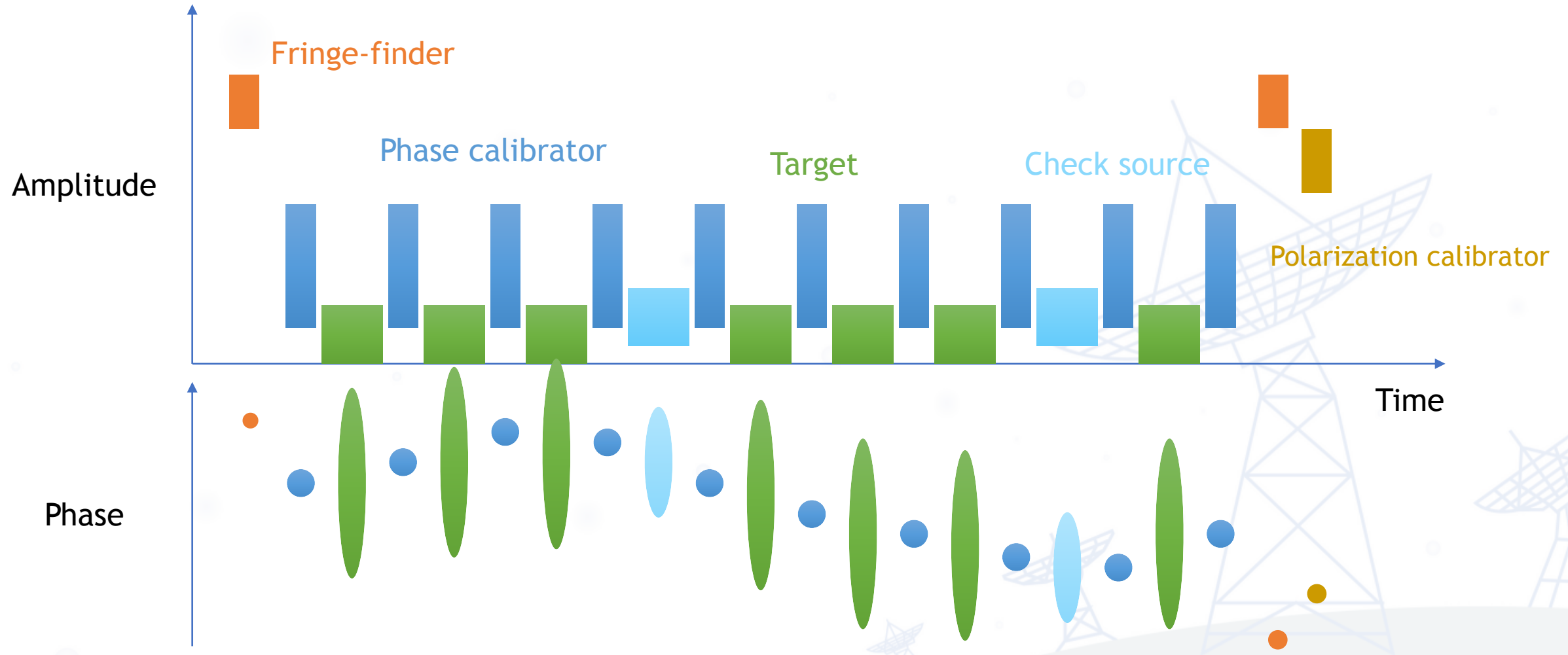
Absolute astrometry? —> requires a nearby calibrator source.

**Phase calibrator:** strong and compact source within a few degrees.

**Fringe-finders** (bandpass calibrators): strong sources, can be farther away.

**Polarization calibration?** —> unpolarized calibrator or with known polarization degree

# A typical VLBI observation







# Calibrating your data

It all comes down to have a good calibration strategy

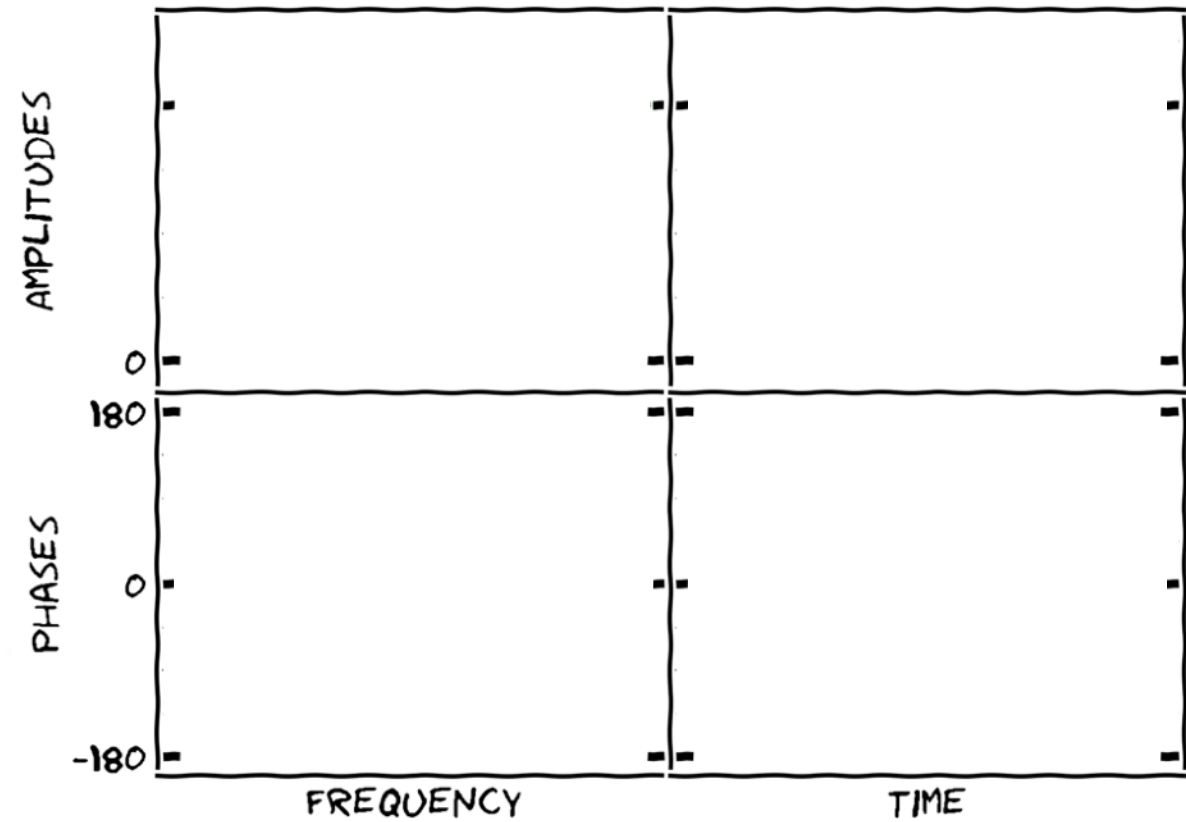


# Calibrating your data



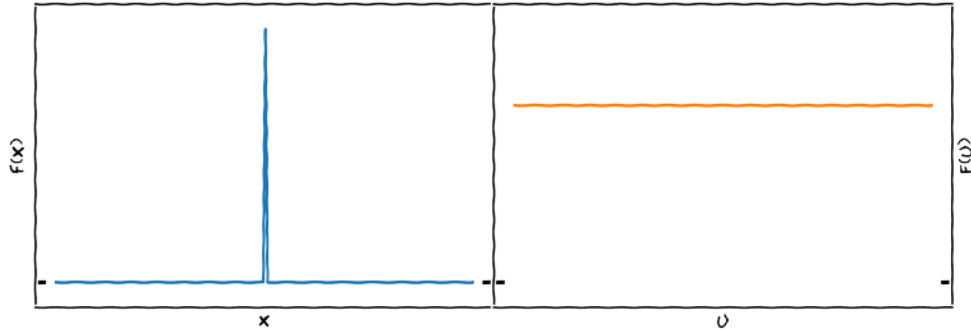
Let's remember Fourier transforms and amplitudes and phases...

*If we have a point-like source right at the phase center, it will look like... (for a given baseline)?*

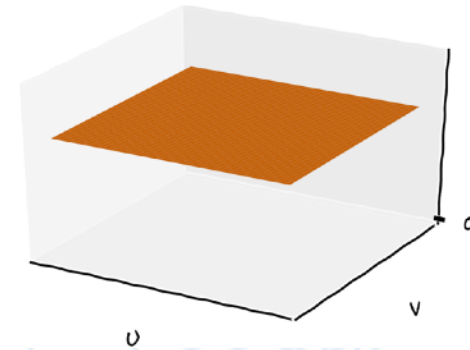
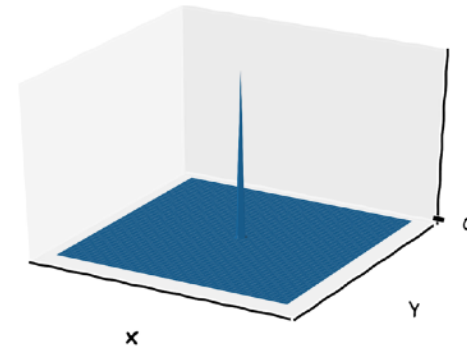




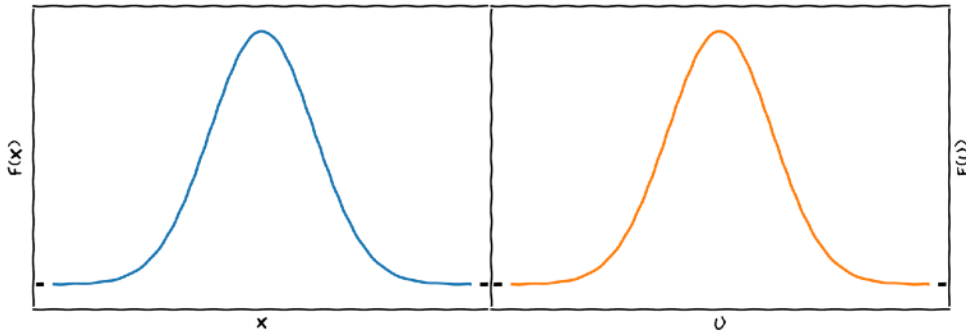
# [Reminder] Fourier transforms



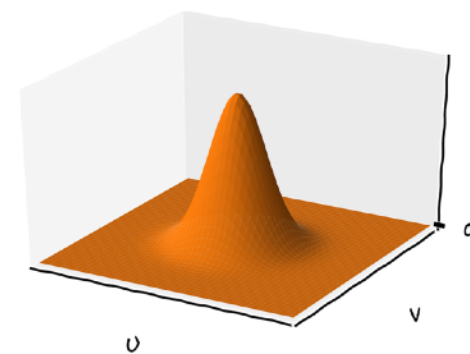
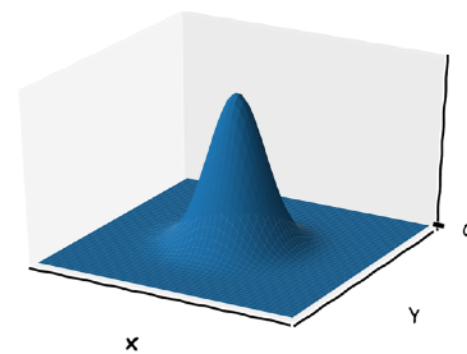
A Delta function is transformed into a constant.  
\* If offset from  $x = 0$ , then into a sinusoidal function.



A 2D Delta function is transformed into a plane (any  $U, V$  point sees the same value).



A Gaussian function is transformed into another Gaussian function.



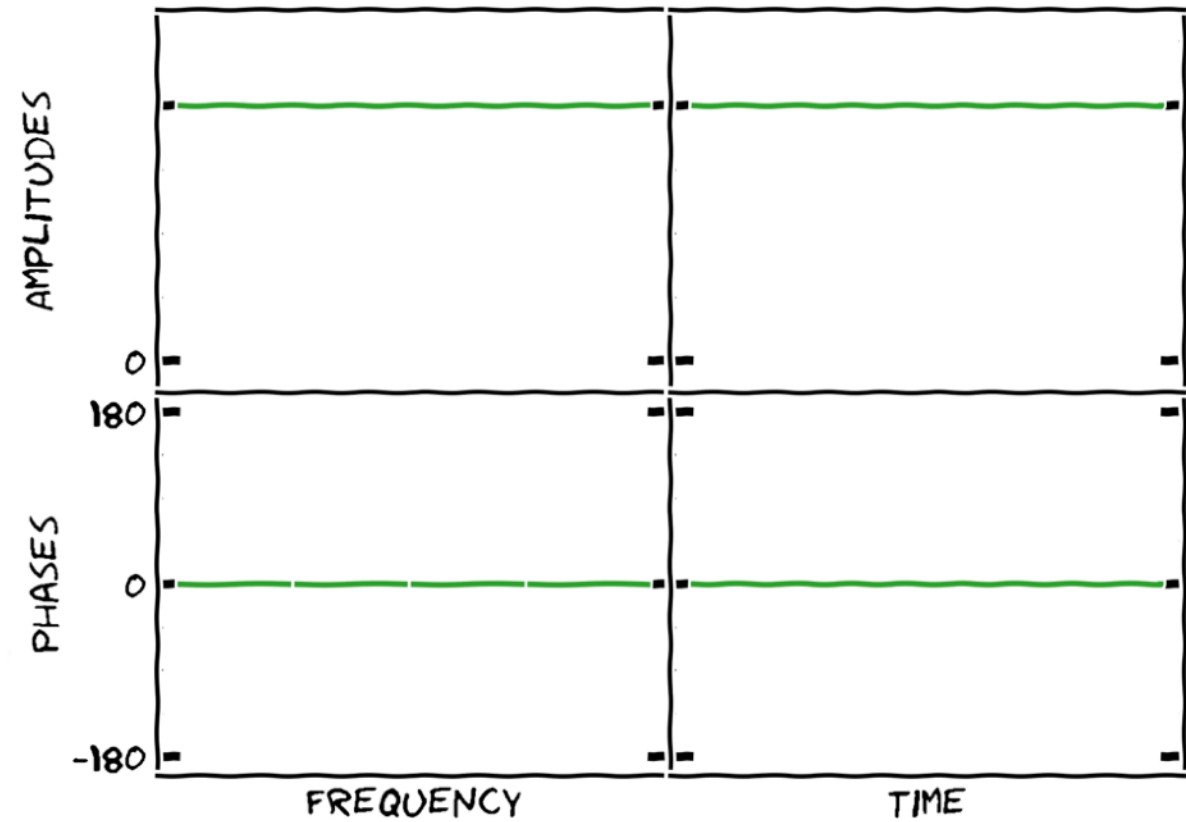
A 2D Gaussian function is transformed into a 2D Gaussian.

# Calibrating your data



Let's remember Fourier transforms and amplitudes and phases...

*If we have a point-like source right at the phase center, it will look like... (for a given baseline)?*

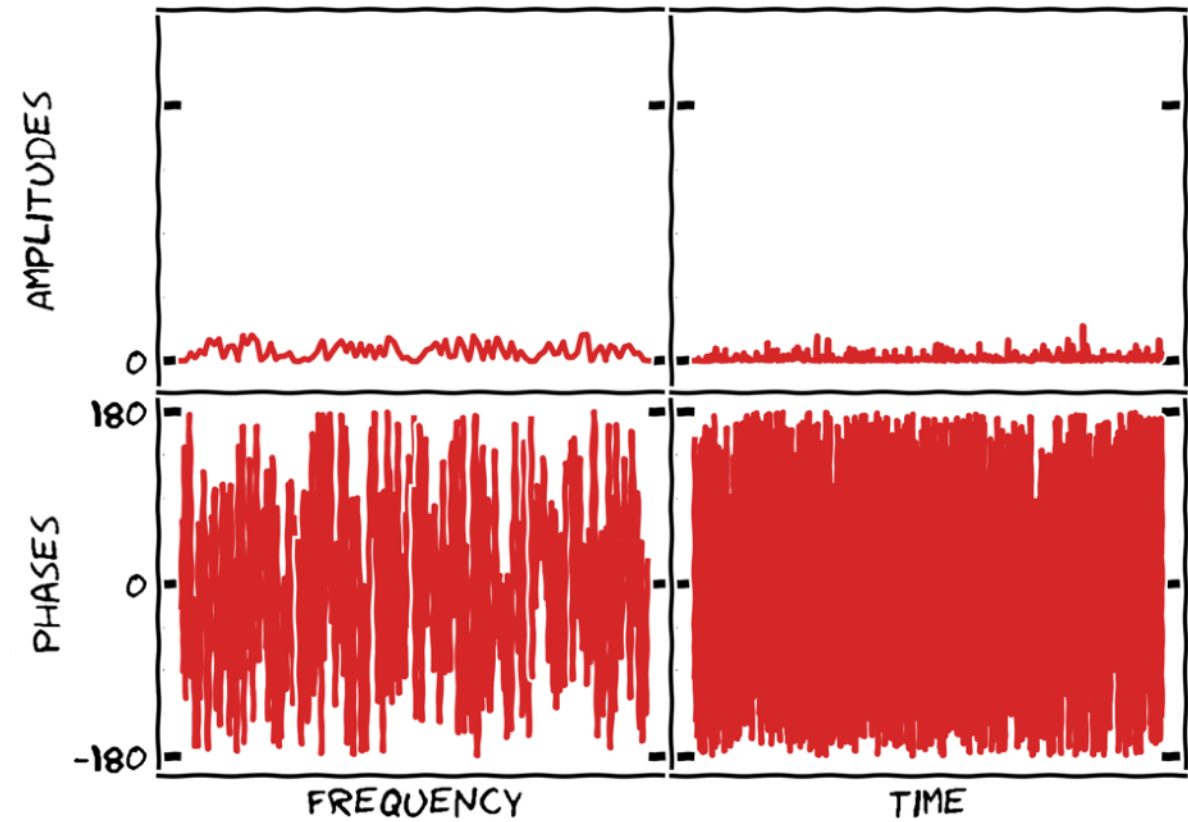




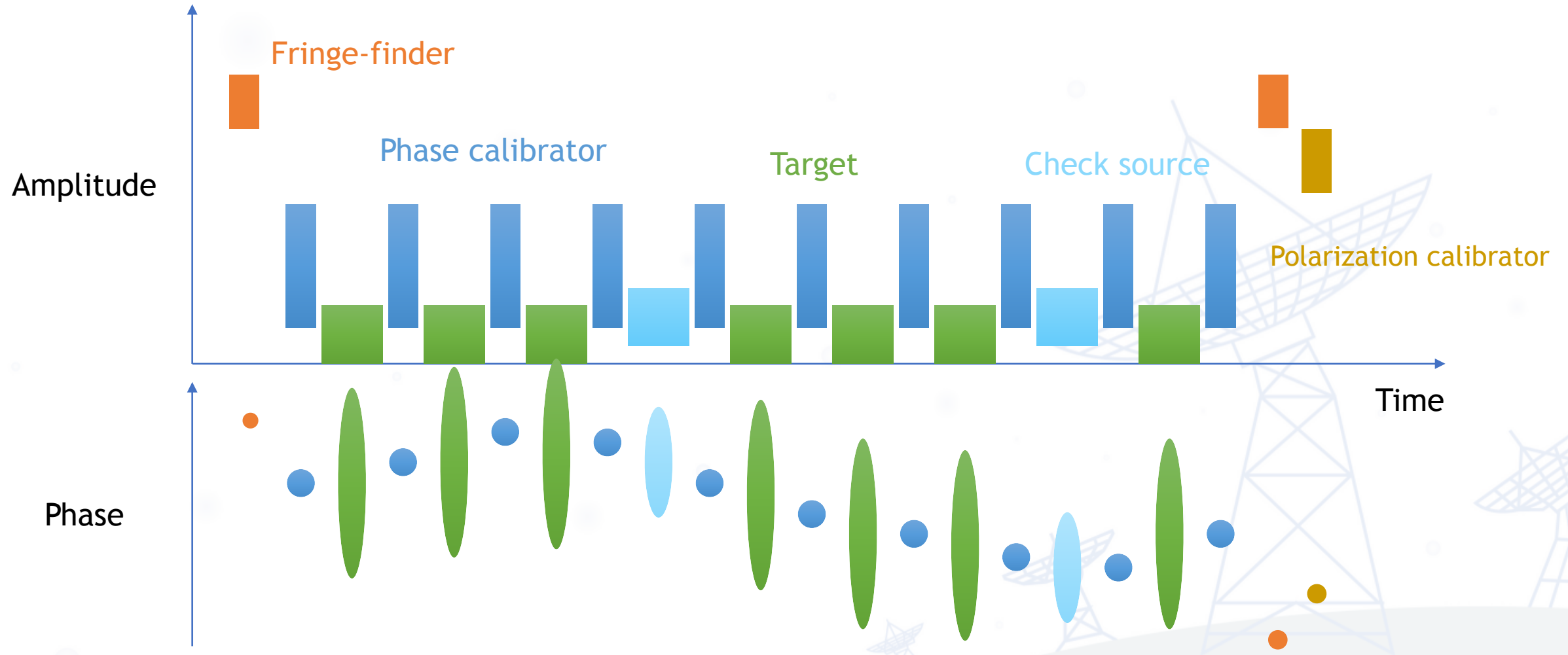
# Calibrating your data



*But in general this will be your target!*



# A typical VLBI observation

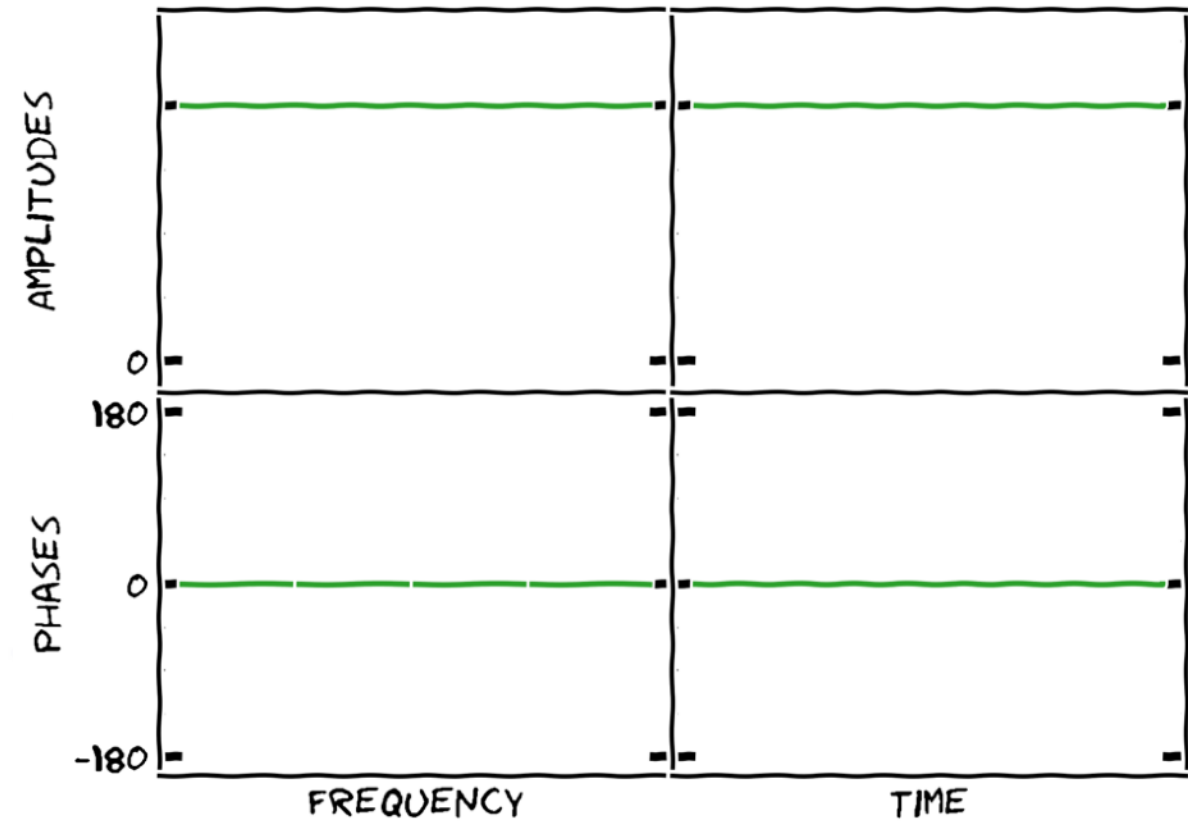




# Calibrating your data



*Our perfect point-like source in “real” data*



# Calibrating your data

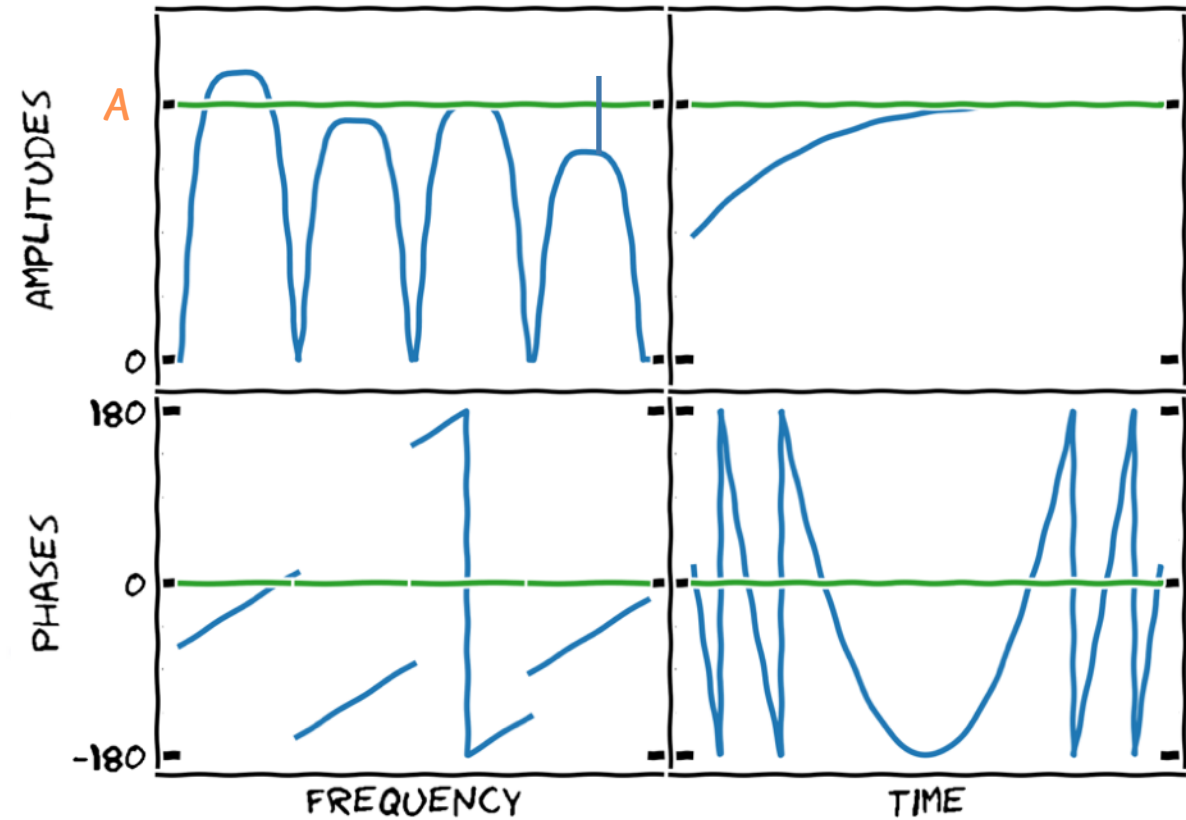
## A-priori gain calibration

Telescopes record *temperatures* or *voltages*, but not **Jansky units**.

Necessity to apply a conversion to the amplitudes in our visibilities.

Connected interferometers rely on **amplitude calibration sources**.

VLBI relies on **system temperatures**.



# Calibrating your data

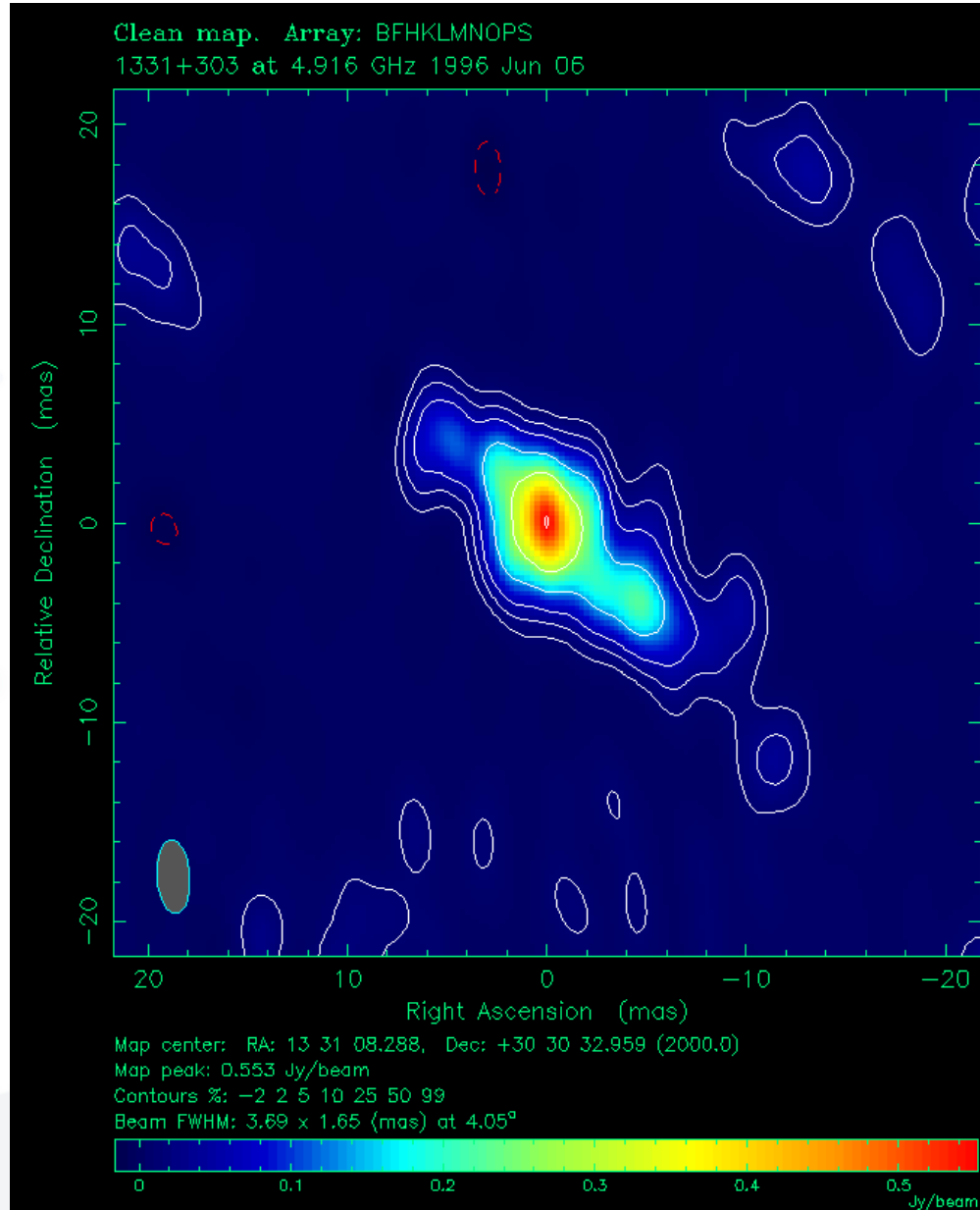
## A-priori gain calibration

### Amplitude calibration sources:

A source that has a known *flux* and does not vary in time.

### In VLBI:

- Most of the sources are resolved to some extent.
- The compact ones are typically highly variable.





# Calibrating your data

## A-priori gain calibration

### System temperature:

“Power” measured by the station only from the system noise.

### System Equivalent Flux Density (SEFD).

Flux density of a fictitious source delivering the same power as the system noise.

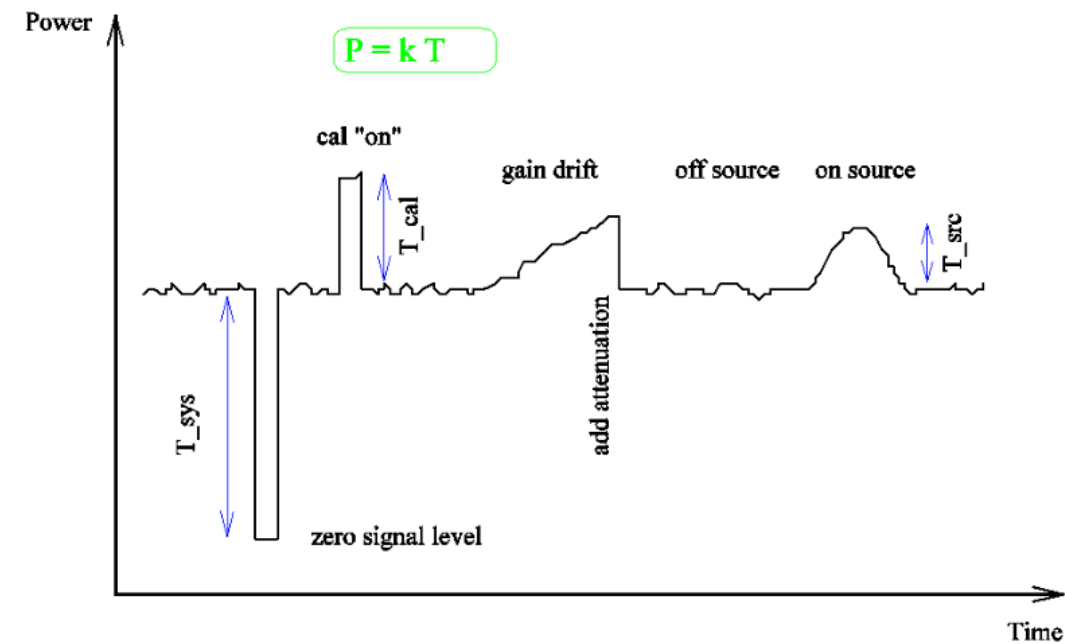
### Gain (or sensitivity):

Increase in *Temperature* for a source of 1 Jy.

Absolute gain: DPFU (degrees per flux unit)

Gain curve: dependency with zenith angle (elevation, etc...).

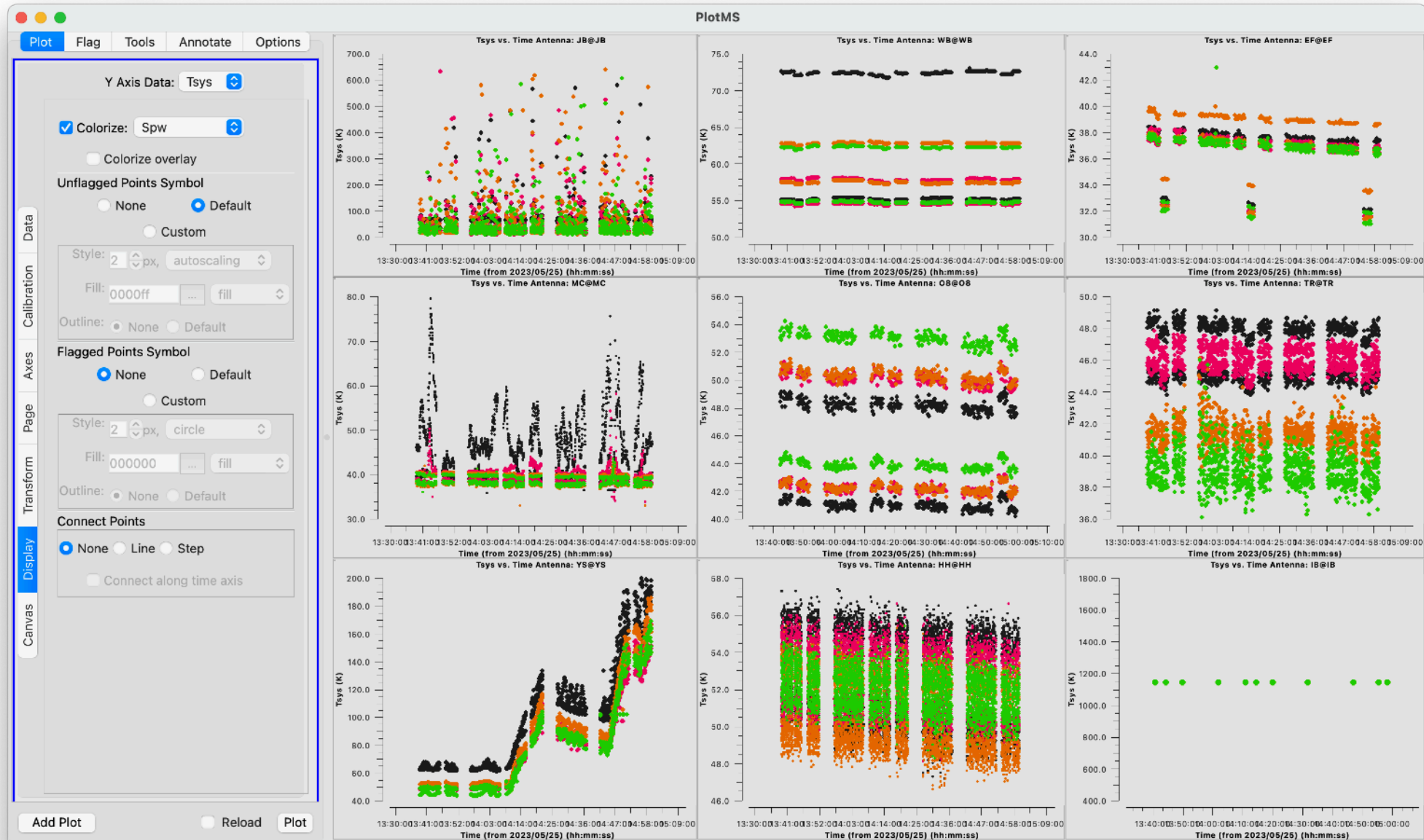
$$\text{SEFD} = \frac{T_{\text{sys}}}{\text{DPFU} \cdot g(z)}$$



Always ~10-15% uncertainty  
in the absolute scale!

# Calibrating your data

## A-priori gain calibration

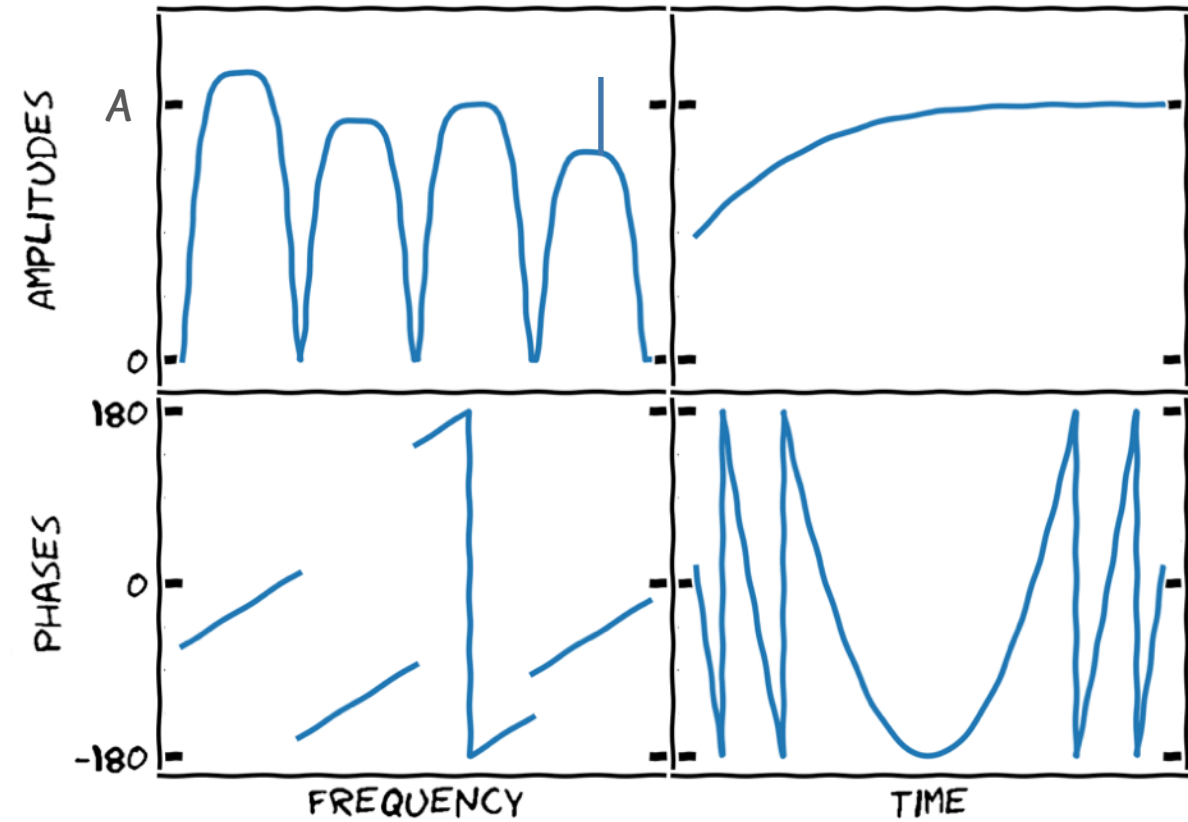


# Calibrating your data

A-priori gain calibration



*Our perfect point-like source in “real” data*





# Calibrating your data

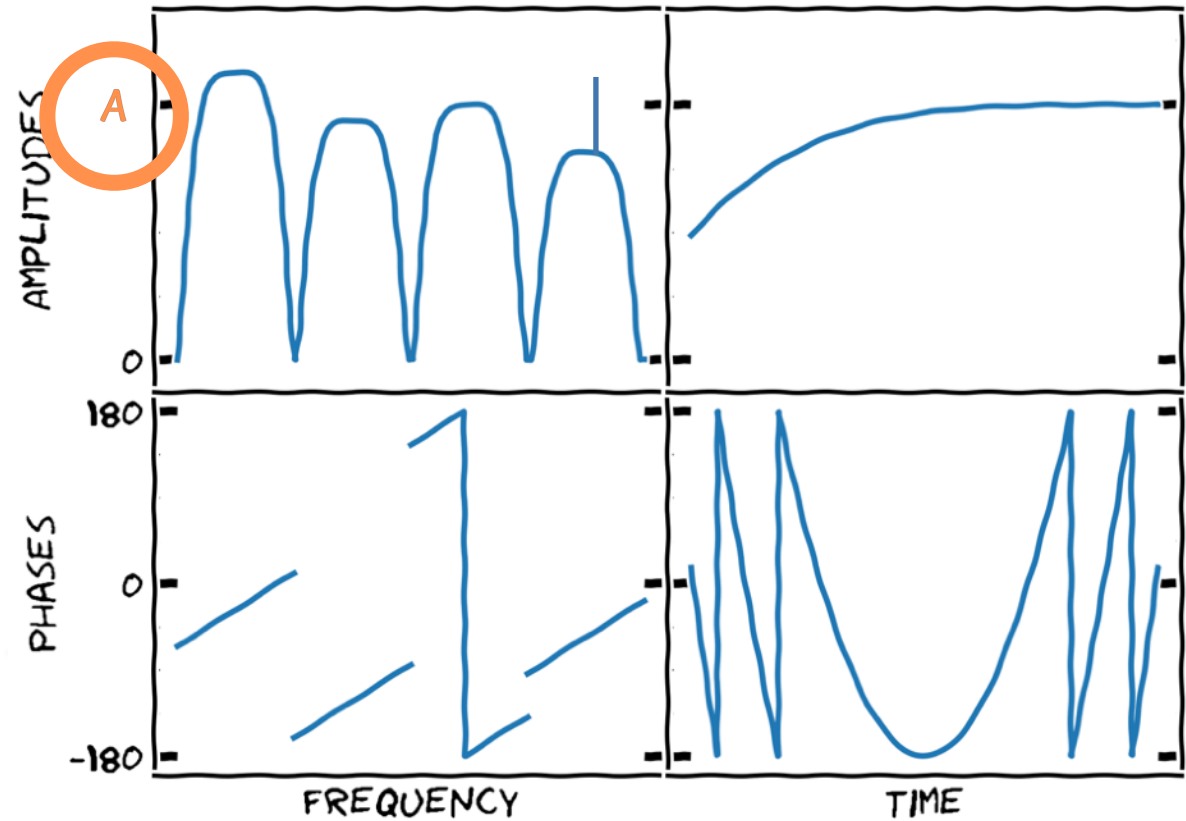
## A-priori gain calibration

In EVN data, the  $T_{\text{sys}}$  and gain curve (GC) information is included in the MS data (unless observations are before January 2022).

You can directly create a calibration table:

```
gencal(vis='n23c2.ms',  
       caltable='n23c2.tsys',  
       caltype='tsys',  
       uniform=False)
```

```
gencal(vis='n23c2.ms',  
       caltable='n23c2.gcal',  
       caltype='gc')
```



# Calibrating your data

Ionospheric calibration (only if you observe at < 5 GHz)

The ionosphere contributes to the light path.

And it's a  $\propto \nu^2$  relation.

→ There are maps of the ionospheric total electron content (TEC) across the world, that can minimize this contribution.

→ Or via dispersive fringe fit.

```
from casatasks.private import tec_maps
```

```
tec_maps.create(vis='n23c2.ms',  
                doplot=True,  
                imname='n23c2.iono')
```

```
gencal(vis='n23c2.ms',  
        caltable='n23c2.tecim',  
        infile='n23c2.iono.IGS_TEC.im',  
        caltype='tecim')
```

```
> calibration table 'n23c2.tecim'.
```

---

Or in **fringefit** (see later) with the option:

```
paramactive=[True, True, True]
```



# Calibrating your data

## Parallactic angle correction

For alt-azimutal telescope mounts, the sky rotates along the observation.

This needs to be taken into account.

No single step in CASA, but **keep the following parameter during all main calibration steps:**

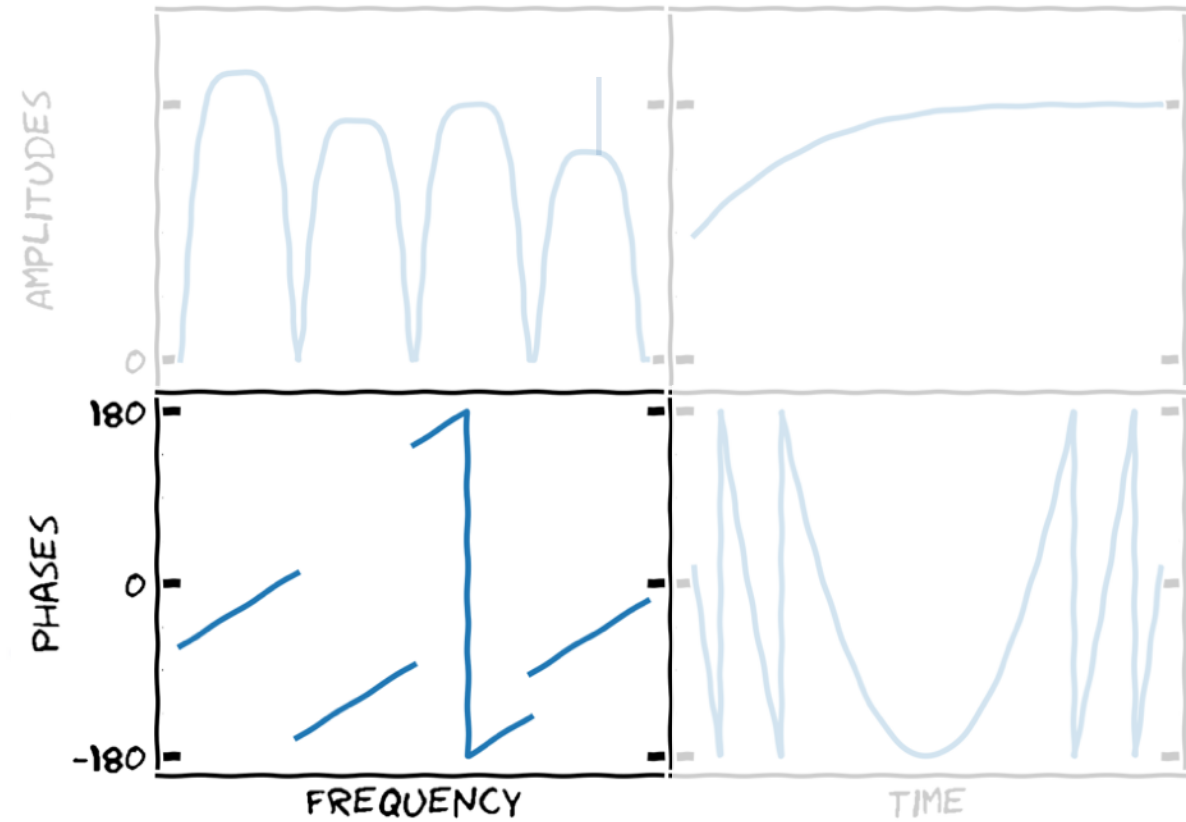
`parang=True`



# Calibrating your data



*Let's start with these phases  
at a particular time...*





# Calibrating your data

## Instrumental delay calibration

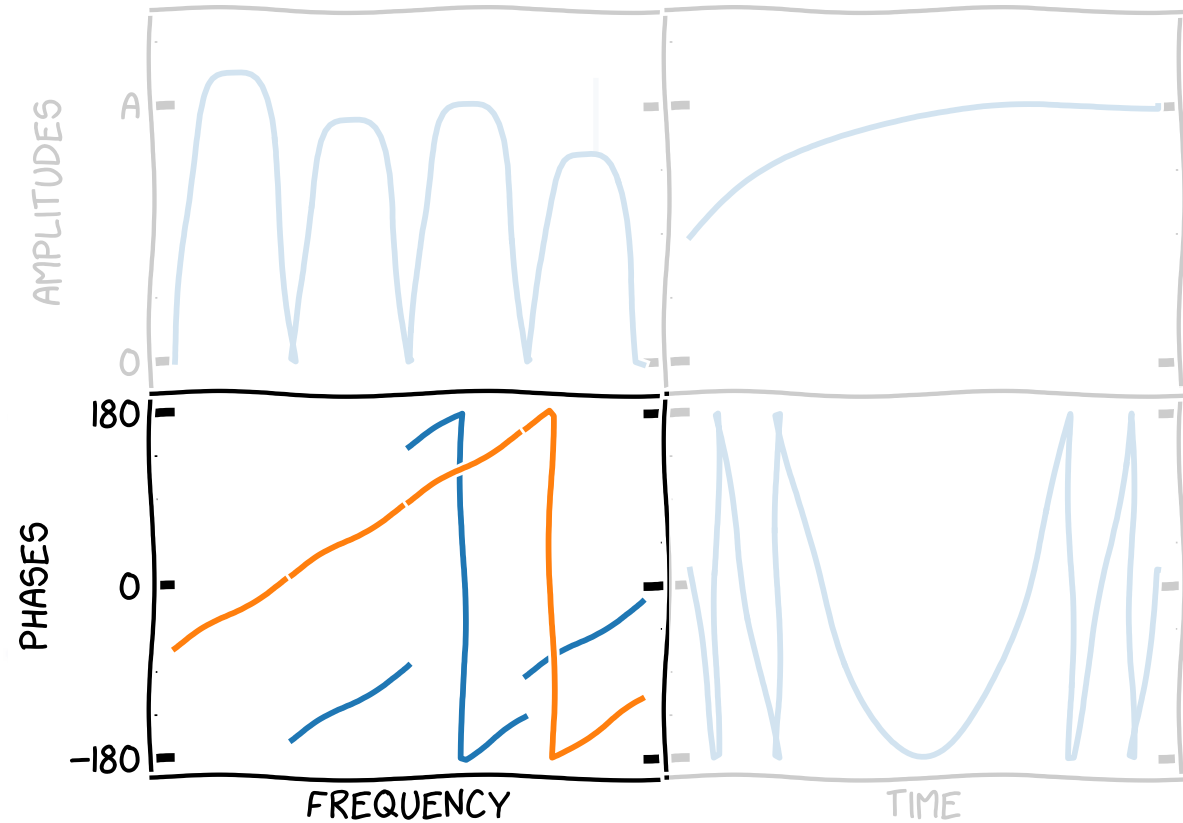
Phase jumps between (some) subbands.

Signal paths go through different hardware.

These jumps should be consistent along the observation.

→ Pick up just a single scan on the brightest source (e.g. fringe finder). *All antennas must be present.*

```
fringefit(vis='n23c2.ms',  
          caltable='n23c2.sbd',  
          field='J0854+2006',  
          timerange='14:00:00~14:01:00',  
          solint='inf',  
          zerorates=True,  
          refant='EF',  
          minsnr=10,  
          gaintable=['n23c2.gcal', 'n23c2.tsys'],  
          interp=['nearest', 'nearest,nearest'],  
          parang=True)
```



# Calibrating your data

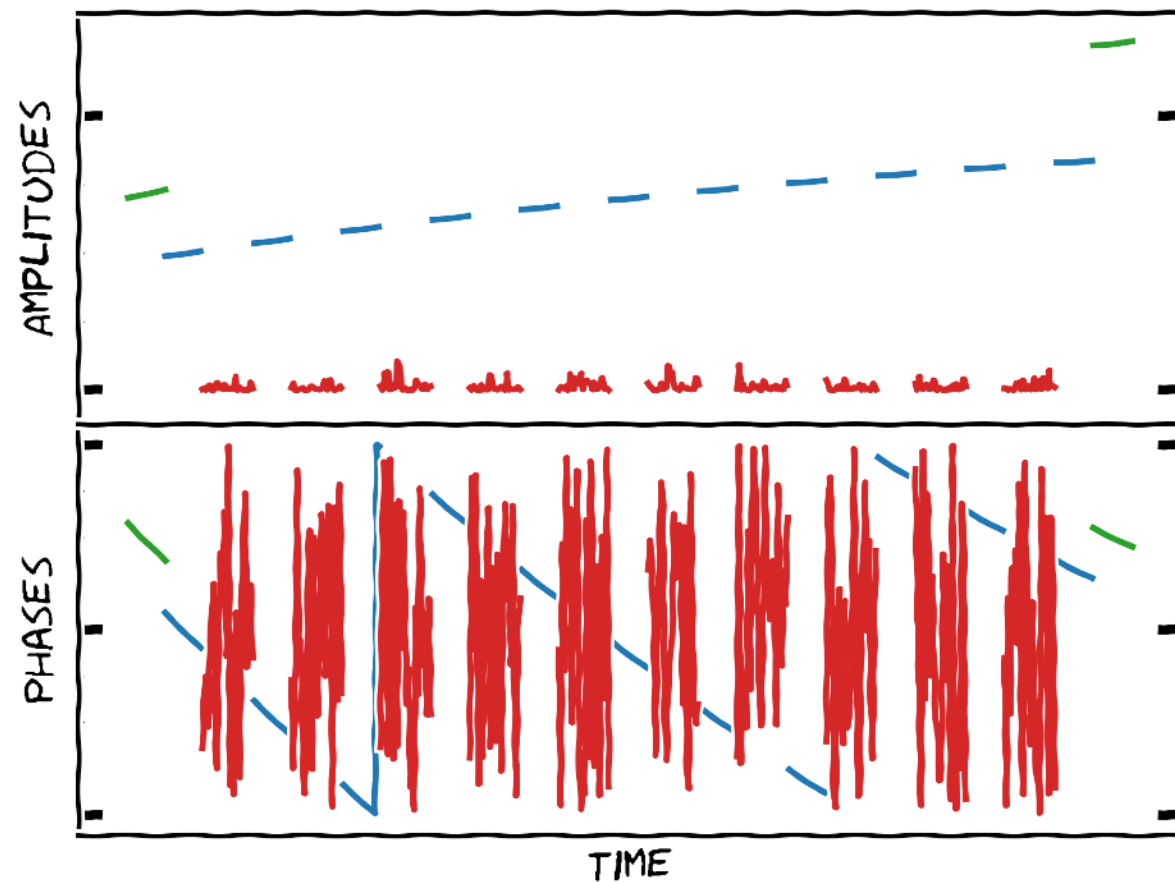
## Multi-band delay (global fringe-fit) calibration

Frequency- and time-dependent phase calibration.

Fit the evolution of delays and rates for each calibrator source along the observation.

Corrections depend on the propagation effects (atmosphere).

```
fringefit(vis='n23c2.ms',  
          caltable='n23c2.mbd',  
          field='J0854+2006',  
          timerange='',  
          solint='60s',  
          zerorates=False,  
          refant='EF',  
          combine='spw',  
          minsnr=5,  
          gaintable=['n23c2.gcal', 'n23c2.tsys', 'n23c2.sbd'],  
          interp=['nearest', 'nearest,nearest', 'nearest'],  
          parang=True)
```



# Calibrating your data

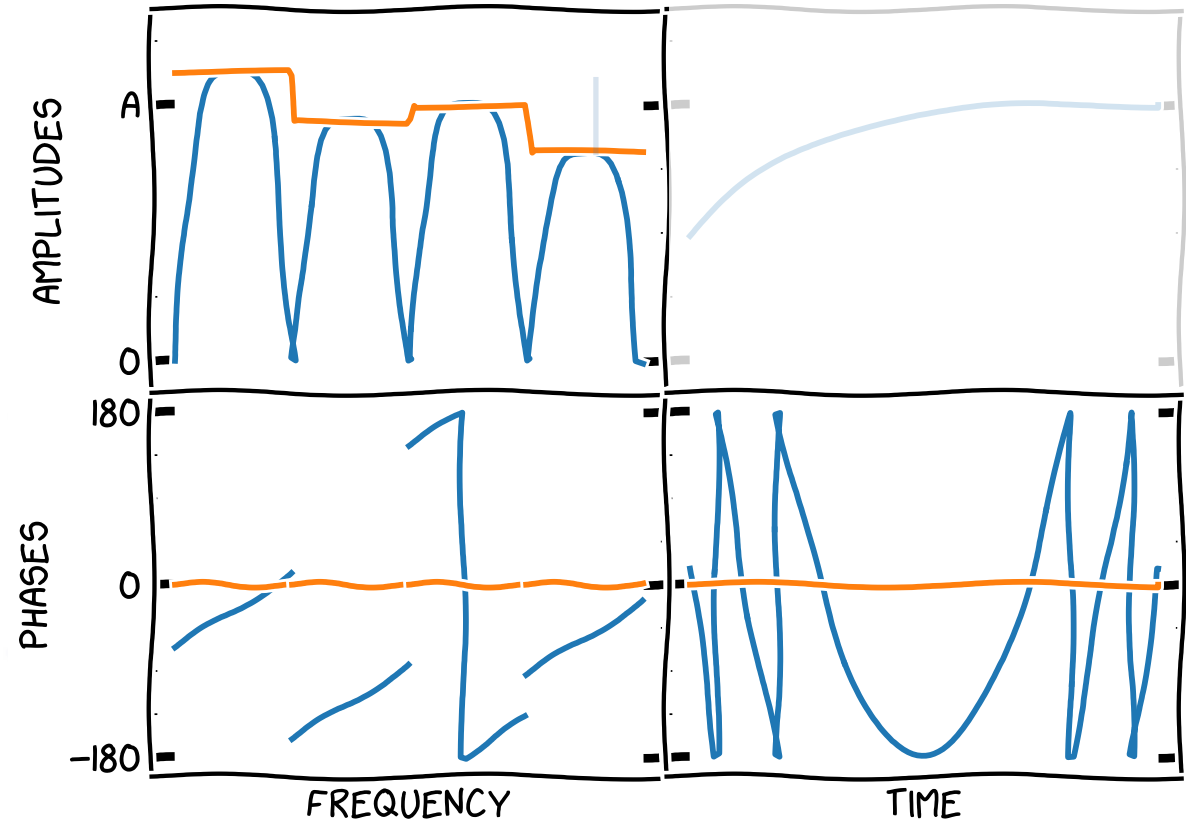
## Bandpass calibration

Correct for the effect of the bandpass in the different subbands.

**Instrumental effect.** Constant in time/source (but different for each observation).

Use the brightest source for that (highest S/N)  
→ fringe finder(s).

```
bandpass(vis='n23c2.ms',  
         caltable='n23c2.bpss',  
         field='J0854+2006',  
         solnorm=True,  
         solint='inf',  
         refant='EF',  
         bandtype='B',  
         gaintable=['n23c2.gcal', 'n23c2.tsys', 'n23c2.sbd', 'n23c2.mbd'],  
         interp=['nearest', 'nearest', 'nearest', 'linear'],  
         spwmap=[[ ], [ ], [ ], [0,0,0,0]],  
         parang=True)
```



# Calibrating your data

## Apply calibration and split

Once you apply the calibration, it is recommended to **split** (**mstransform**) the data to generate a MS with a single source and all calibration applied (thus *CORRECTED\_DATA* -> *DATA*).

But **keep in mind**: if you average in frequency/time, then your field of view (FoV) is more limited.

For compatibility with **Difmap** (if you are going to use it), then:

```
mstransform(vis='n23c2.ms',  
            outputvis='n23c2.J0905+2052.ms',  
            field='J0905+2052',  
            datacolumn='corrected',  
            keepflags=False,  
            chanaverage=True,  
            chanbin=64)
```

```
exportuvfits(vis='n23c2.J0905+2052.ms',  
            fitsfile='n23c2.J0905+2052.uvfits',  
            datacolumn='data',  
            combinespw=True,  
            padwithflags=True,  
            multisource=False)
```





# Calibrating your data

## Self-calibration

A second-order calibration for the phases.

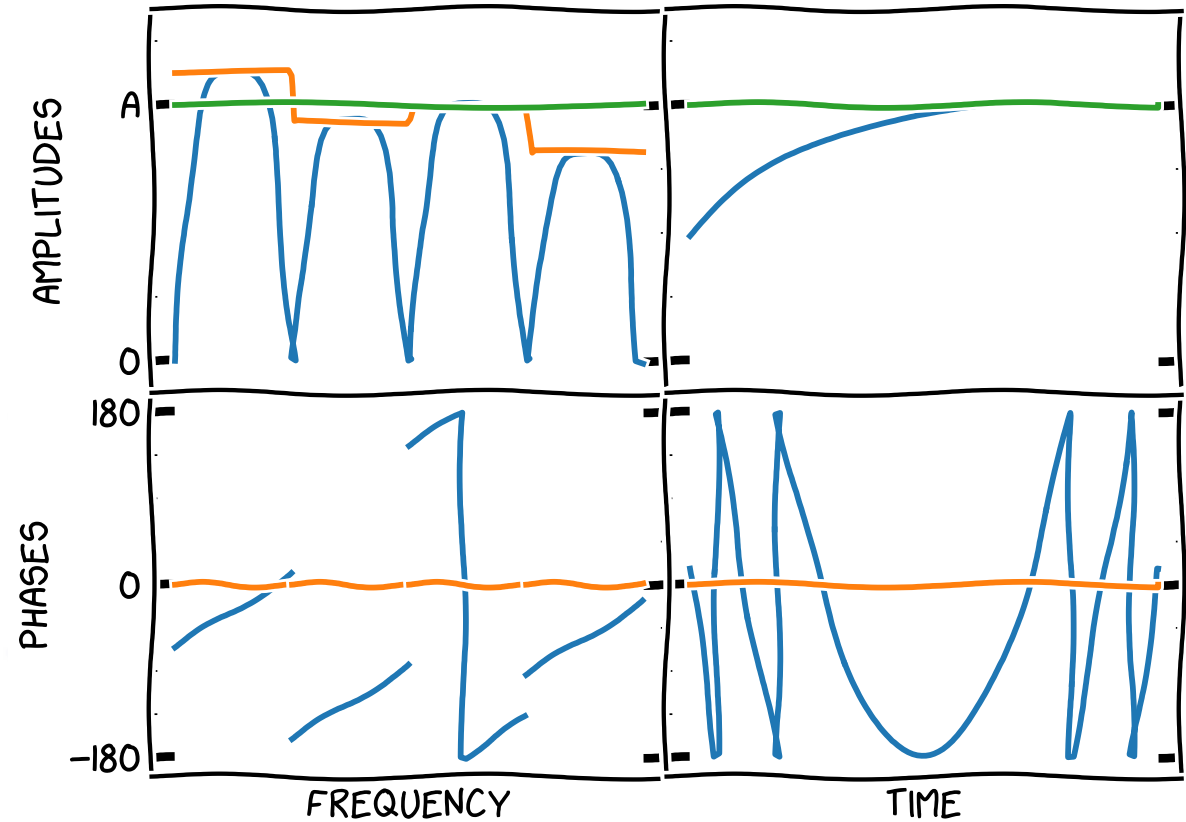
Solve the amplitude-related issues.

- It will significantly increase the S/N of your images.
- But it breaks the astrometry!

Same way as you saw in previous tutorials.

*(with some remarks...)*

*But you need to image first!*

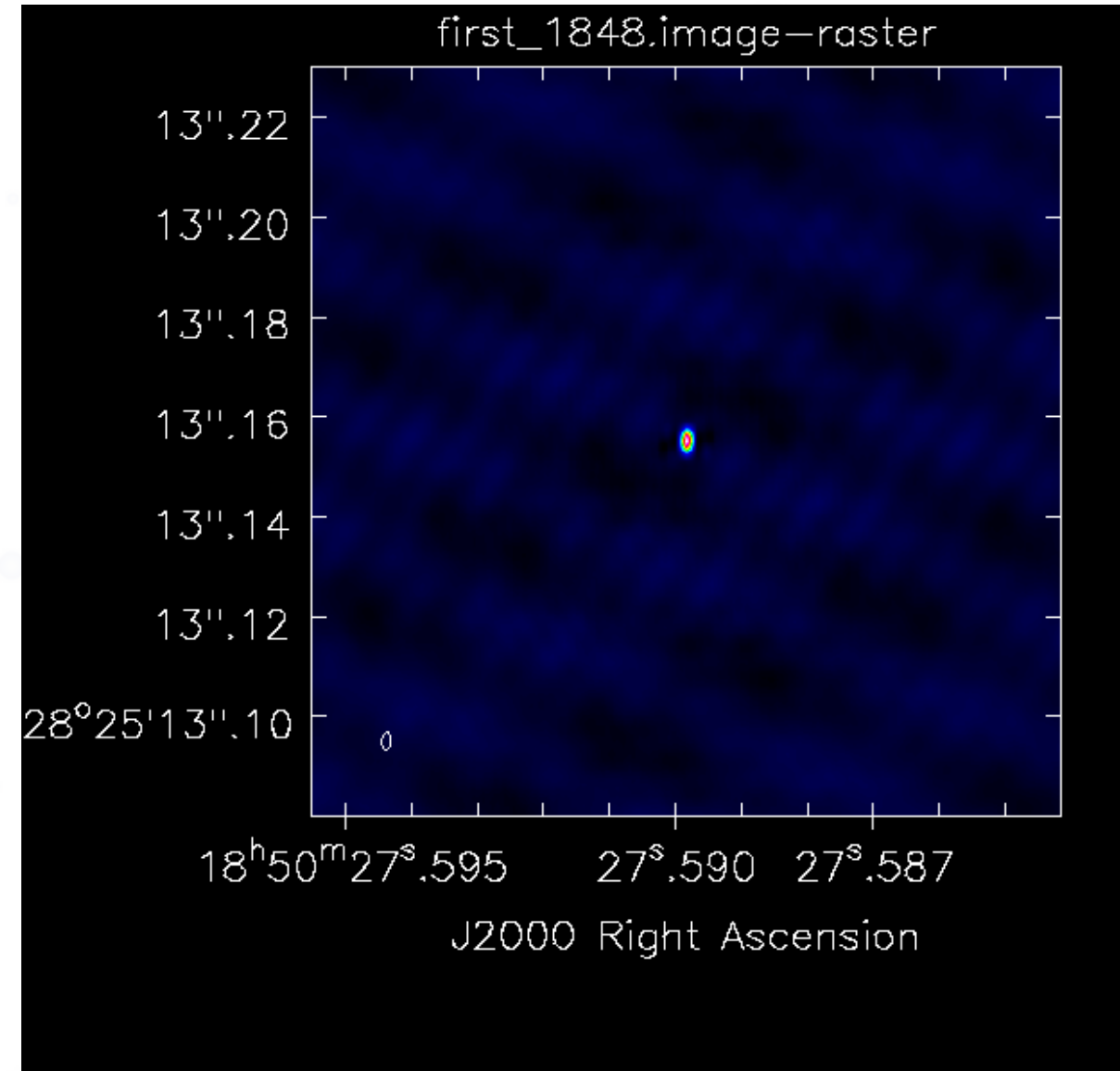


# Calibrating your data

## Imaging

### VLBI particularities:

- $uv$  coverage is much poorer.
- Single source in your entire field.
- Non-gaussian noise.  
Stronger spikes in the imaged field:  
 $6\text{-}\sigma$  level required for detections.
- Measured flux densities may (slightly) differ when doing in the **image plane** or  **$uv$  plane**.
- Different **weighing** schemes may provide quite different images.



# Calibrating your data

## Imaging and self-calibration

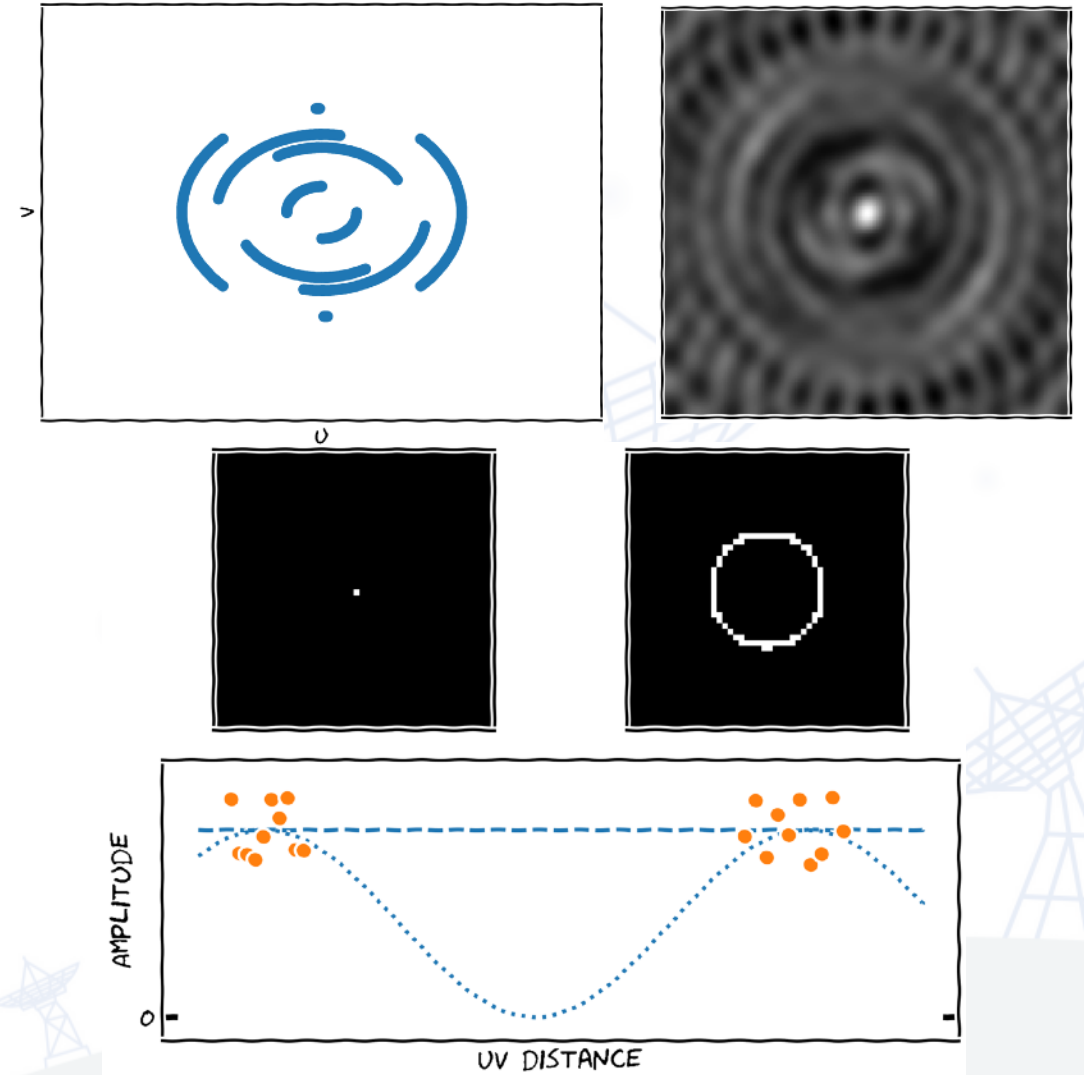
Getting an accurate model of your source is critical!

Self-calibration “modifies” your data to fit your model.

Can easily scale up/down your station amplitudes (artificially).

It needs high signal-to-noise...

NOTE: *parang=False* from now on!



# Summary



**EVN Data Reduction Guide (AIPS & CASA, to be updated soon):**

[evlbi.org/evn-data-reduction-guide](http://evlbi.org/evn-data-reduction-guide)

**Tutorial for the advance sessions:**

[jive.eu/jvs2025](http://jive.eu/jvs2025) -> data reduction guide

**General information for EVN astronomers (and links to different tutorials):**

[evlbi.org/evn-for-astronomers](http://evlbi.org/evn-for-astronomers)

**Pipelines are coming online!**

*VPIPE* (Jack Radcliffe), *rPicard* (Michael Janssen), *PSRVLBIReduce* (Hao Ding & Adam Deller), ...

